

# BPhO

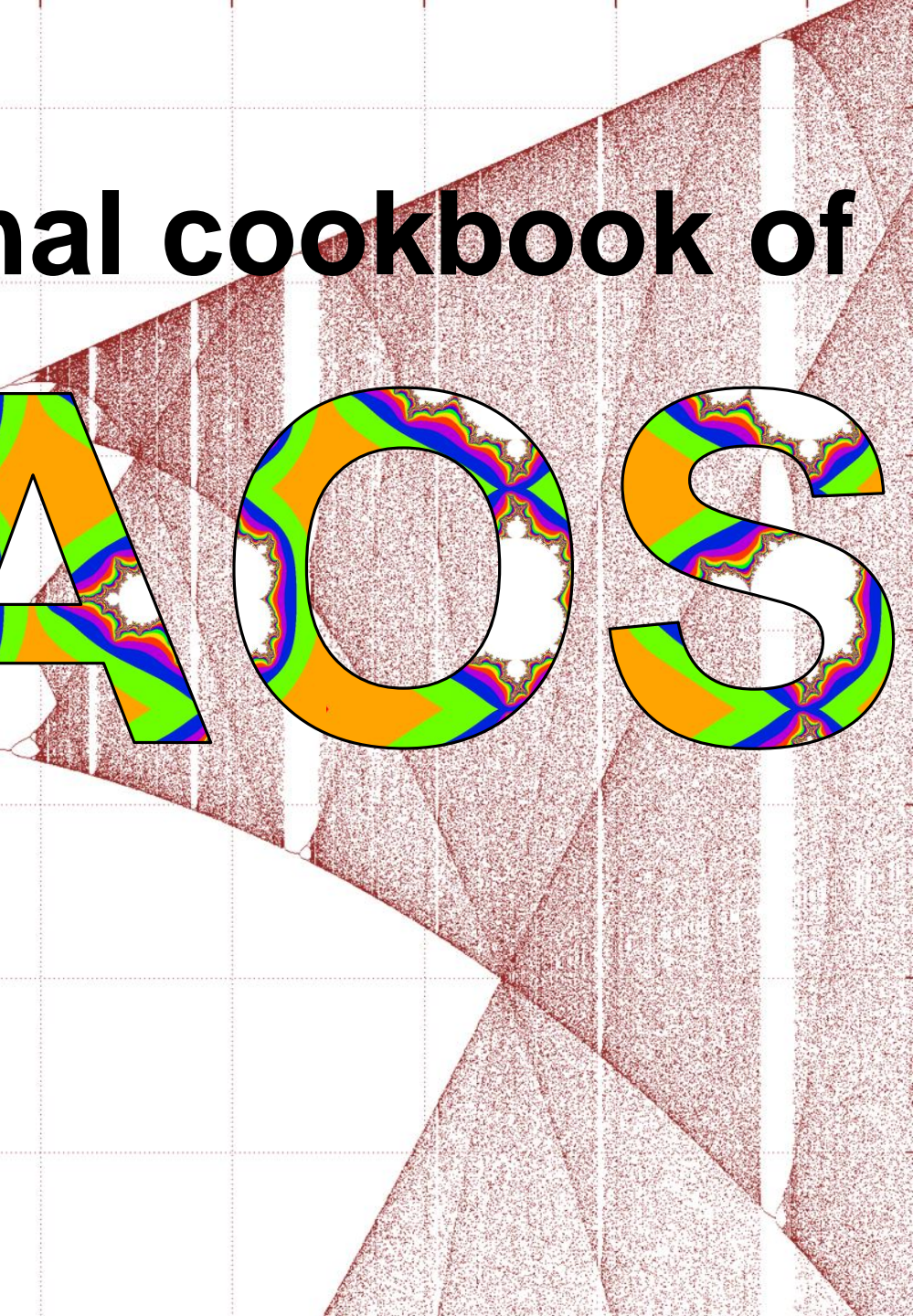
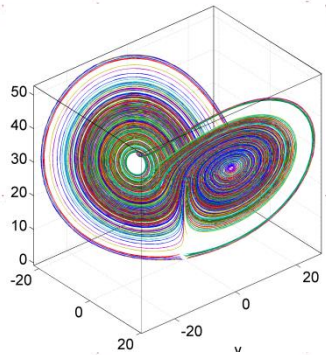
## Computational Challenge

# Chaos

Dr Andrew French.  
December 2023.

# A computational cookbook of

CHAOS



# 1. What is chaos?

2. A short but chaotic history

3. The **logistic map** and population modelling

4. Pendulums and **phase space**

5. Lorenz and Rössler **strange attractors**

6. Shaw's dripping faucet

## 7. Fractals

- Koch snowflake
- **Fractal dimension**
- Barnsley fern and Sierpinski triangle

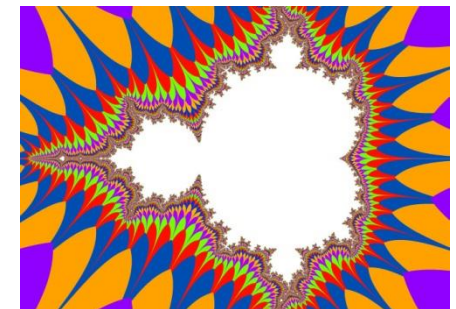
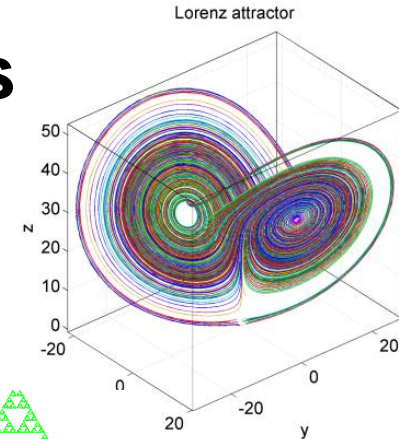
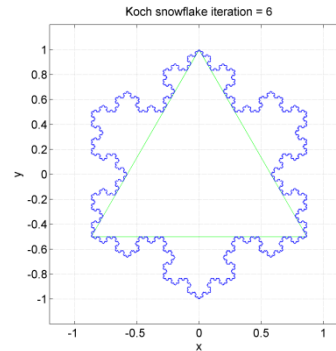
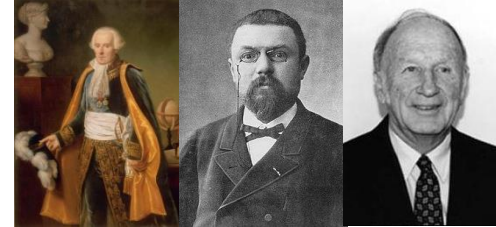
8. **Mandelbrot**, complex numbers and **iteration**

9. Chaos in planetary systems

10. Chaos in fluid flow

11. **Phase locking** & order from chaos

12. Further reading



# What is Chaos?

**Dynamics**, the *physics of motion*, provides us with *equations* which can be used to **predict the future position of objects** if we know (i) their present **position** and **velocity** and (ii) the **forces** which act on each object.

This works *very well* for planetary motion, tides etc. *Not so well* for weather or indeed the position of pool balls....

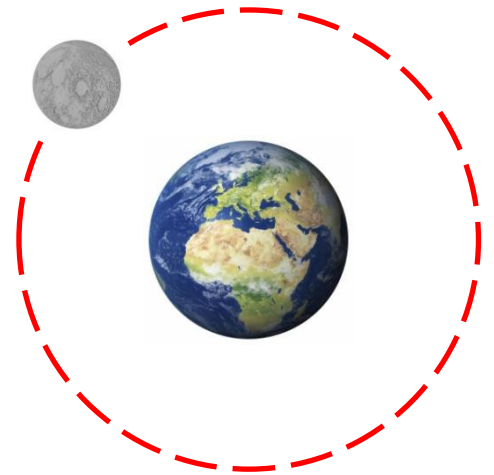
This is because **most systems cannot be solved exactly**. An *approximate numerical method* is required to work out what happens next.

Many systems, even really simple ones, are **highly sensitive to initial conditions**.

**This means future behaviour becomes increasingly difficult to predict**



*Nonlinearity* is often the problem!



# What is Chaos?



i.e. where we  
know the laws of  
motion

“Simple *deterministic* systems with only a few elements can generate **random behaviour**. The randomness is fundamental; gathering more information does not make it go away. Randomness generated in this way has come to be called chaos.”

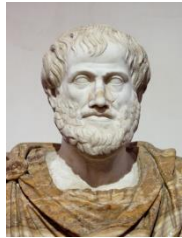


Robert Shaw of  
the “Santa Cruz  
Chaos Cabal”  
1970s-1980s



# Does the flap of a butterfly's wings in Brazil set off a tornado in Texas?

Edward Norton Lorenz  
1917-2008



Hmmm. What does this "**Butterfly Effect**" mean for Causality?

"... it is found that non-periodic solutions are ordinarily **unstable with respect to small modifications**, so that slightly differing initial states can evolve into considerably different states"



i.e. if I change pressure by even a tiny amount in a weather model, the effect may be profound after a relatively short time

# A short but chaotic history

I give you:  
Laws of motion  
Calculus  
Gravitation ...



Isaac Newton  
1642-1727



Pierre Simon Laplace  
1749-1827

Michel Hénon  
1931-2013



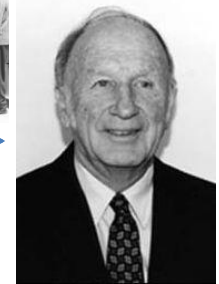
The *Uncertainty Principle* indeed sets a limit on what we can know for certain

If we know the position and momentum of all particles in the Universe we could know the **past** *and* the **future!**

“Sensitive dependence on initial conditions”



Henri Poincaré  
1854-1912

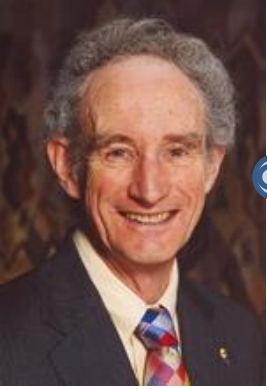


Edward Norton Lorenz  
1917-2008



Planetary dynamics can often be **chaotic**

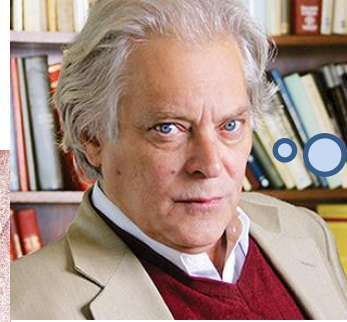
But we can only know the initial situation *approximately*. And small errors can often **amplify** with interactions between many particles



Robert May  
1936-

Chaos can be seen in *very simple* mathematical models, such as how an ecological population changes year on year

**You *don't* need complicated interactions to produce unpredictable behaviour**



Mitchell Feigenbaum  
1944-

I discovered *universal* mathematical truths about these systems

4.669201609...



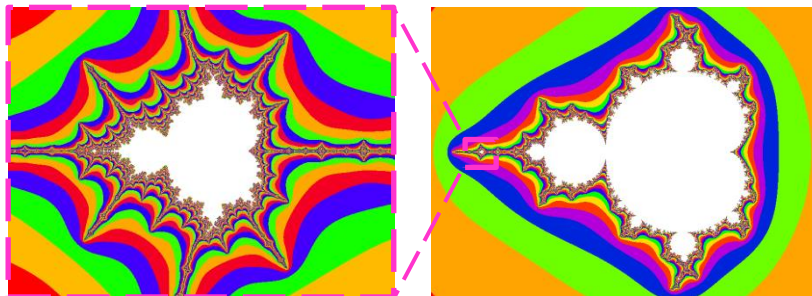
Gaston Julia  
1893-1978

Very intricate geometry is hidden within the simplest of **quadratic equations** (if we use **complex numbers** and **iteration**)

$$z_{n+1} = z_n^2 + z_0$$



Doc Brown = Mitchell Feigenbaum?



Benoit Mandelbrot  
1924-2010

Much of geometry in the natural world is **self similar on all scales**. We can use **fractional dimensions** to describe these *fractal* objects.

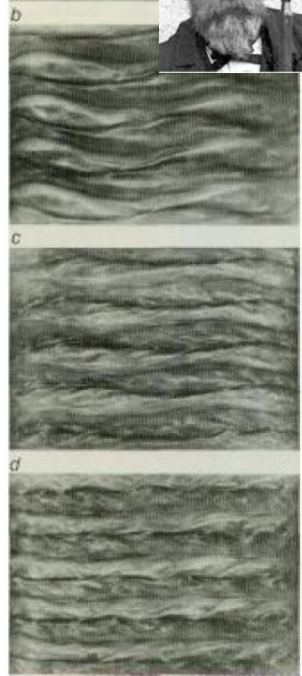


Jerry Gollub (1944-) & Harry Swinney (1939-)



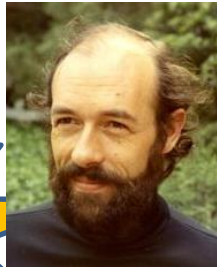
We measured a transition to chaos (turbulence) in fluid trapped between two rotating cylinders

A Couette cell

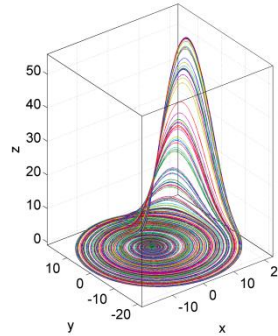


Universality!

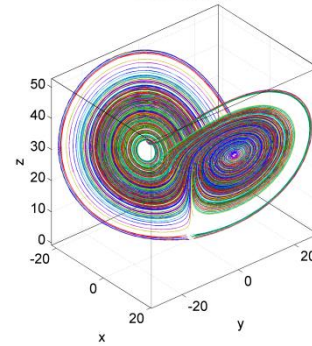
David Ruelle (1935-)  
& Floris Takens (1940-2010)



Rosler attractor



Lorenz attractor



How to investigate nonlinear dynamics?

We propose a strange attractor



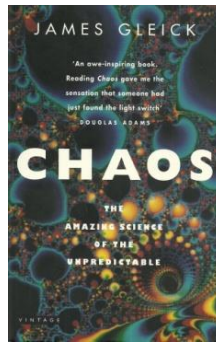
Otto Rössler 1940-



Edward Lorenz 1917-2008

James Gleick 1954-

Robert Shaw James Crutchfield J. Doyne Farmer, Norman Packard  
"Santa Cruz Chaos Cabal"  
1970s-1980s



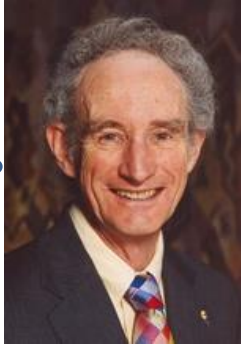
I wrote this all up in a book



# The logistic map and population modelling



I published this model in 1976



Robert May  
1936-

Assume an ecosystem can support a maximum number of rabbits.  
Let  $x$  be the fraction of this maximum at year  $n$ .

To account for **reproduction**, next year's population is proportional to the previous.

To account for **starvation**, next year's population is *also proportional* to the fraction of the maximum population as yet unfilled.

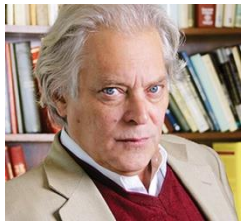


$$x_{n+1} = r x_n (1 - x_n)$$

Growth  
parameter

The population next year is predicted using this **iterative equation** called a **logistic map**

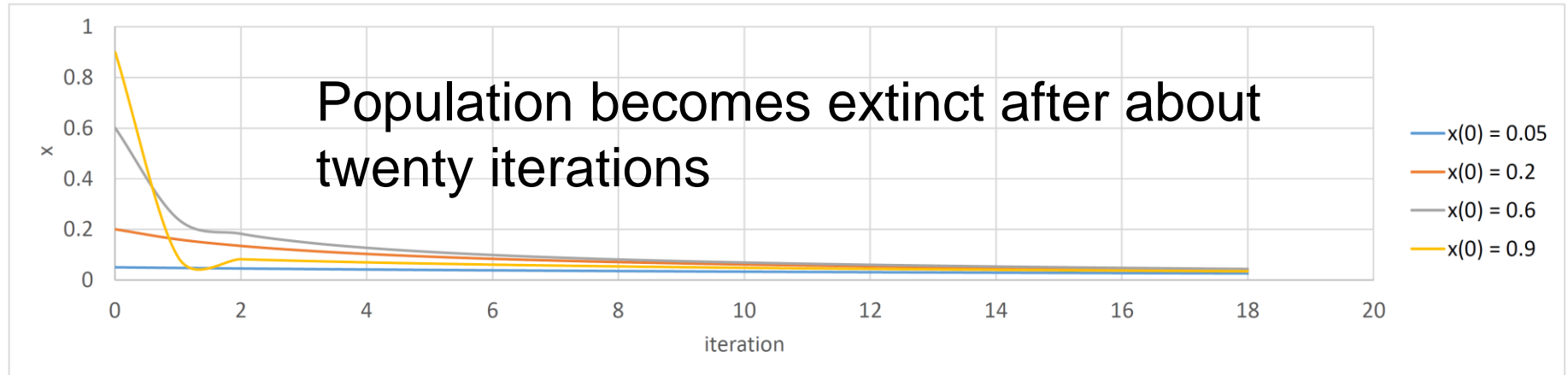
The pattern of  $x$  values with  $n$  is not always simple .....



$$r = 1 \quad x_{n+1} = rx_n (1 - x_n)$$

iteration number n

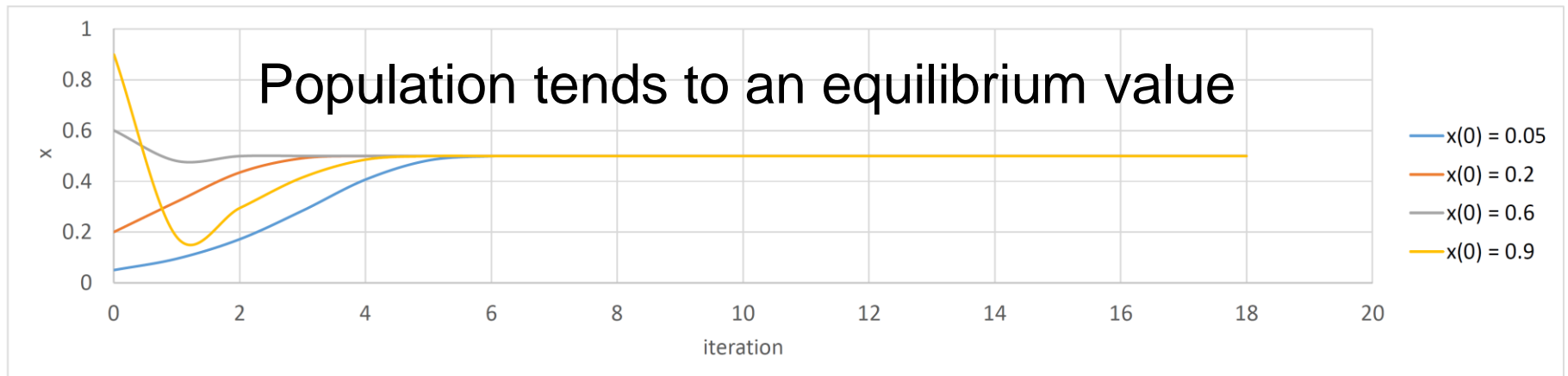
| x(n) | 0        | 1        | 2        | 3        | 4        | 5        | 6        | 7        | 8        | 9        | 10       | 11       | 12       | 13       | 14       | 15       | 16       | 17       | 18       |
|------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|
| 0    | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        |
| 0.05 | 0.0475   | 0.045244 | 0.043197 | 0.041331 | 0.039623 | 0.038053 | 0.036605 | 0.035265 | 0.034021 | 0.032864 | 0.031784 | 0.030773 | 0.029826 | 0.028937 | 0.028099 | 0.02731  | 0.026564 | 0.025858 | 0.025185 |
| 0.1  | 0.09     | 0.0819   | 0.075192 | 0.069538 | 0.064703 | 0.060516 | 0.056854 | 0.053622 | 0.050746 | 0.048171 | 0.045851 | 0.043749 | 0.041835 | 0.040084 | 0.038478 | 0.036997 | 0.035628 | 0.034359 | 0.033185 |
| 0.15 | 0.1275   | 0.111244 | 0.098869 | 0.089094 | 0.081156 | 0.07457  | 0.069009 | 0.064247 | 0.060119 | 0.056505 | 0.053312 | 0.05047  | 0.047923 | 0.045626 | 0.043544 | 0.041648 | 0.039914 | 0.038321 | 0.036871 |
| 0.2  | 0.16     | 0.1344   | 0.116337 | 0.102802 | 0.092234 | 0.083727 | 0.076717 | 0.070831 | 0.065814 | 0.061483 | 0.057703 | 0.054373 | 0.051417 | 0.048773 | 0.046394 | 0.044242 | 0.042284 | 0.040496 | 0.038851 |
| 0.25 | 0.1875   | 0.152344 | 0.129135 | 0.112459 | 0.099812 | 0.08985  | 0.081777 | 0.075089 | 0.069451 | 0.064627 | 0.060451 | 0.056796 | 0.053571 | 0.050701 | 0.04813  | 0.045814 | 0.043715 | 0.041804 | 0.040085 |
| 0.3  | 0.21     | 0.1659   | 0.138377 | 0.119229 | 0.105013 | 0.093986 | 0.085152 | 0.077901 | 0.071833 | 0.066673 | 0.062228 | 0.058355 | 0.05495  | 0.05193  | 0.049234 | 0.04681  | 0.044619 | 0.042628 | 0.040835 |
| 0.35 | 0.2275   | 0.175744 | 0.144858 | 0.123874 | 0.108529 | 0.096751 | 0.08739  | 0.079753 | 0.073392 | 0.068006 | 0.063381 | 0.059364 | 0.05584  | 0.052722 | 0.049942 | 0.047448 | 0.045197 | 0.043154 | 0.041315 |
| 0.4  | 0.24     | 0.1824   | 0.14913  | 0.12689  | 0.110789 | 0.098515 | 0.08881  | 0.080923 | 0.074374 | 0.068843 | 0.064103 | 0.059994 | 0.056395 | 0.053214 | 0.050383 | 0.047844 | 0.045555 | 0.04348  | 0.041605 |
| 0.45 | 0.2475   | 0.186244 | 0.151557 | 0.128587 | 0.112053 | 0.099497 | 0.089597 | 0.08157  | 0.074916 | 0.069304 | 0.064501 | 0.06034  | 0.056699 | 0.053485 | 0.050624 | 0.048061 | 0.045751 | 0.043658 | 0.041765 |
| 0.5  | 0.25     | 0.1875   | 0.152344 | 0.129135 | 0.112459 | 0.099812 | 0.08985  | 0.081777 | 0.075089 | 0.069451 | 0.064627 | 0.060451 | 0.056796 | 0.053571 | 0.050701 | 0.04813  | 0.045814 | 0.043715 | 0.041804 |
| 0.55 | 0.2475   | 0.186244 | 0.151557 | 0.128587 | 0.112053 | 0.099497 | 0.089597 | 0.08157  | 0.074916 | 0.069304 | 0.064501 | 0.06034  | 0.056699 | 0.053485 | 0.050624 | 0.048061 | 0.045751 | 0.043658 | 0.041765 |
| 0.6  | 0.24     | 0.1824   | 0.14913  | 0.12689  | 0.110789 | 0.098515 | 0.08881  | 0.080923 | 0.074374 | 0.068843 | 0.064103 | 0.059994 | 0.056395 | 0.053214 | 0.050383 | 0.047844 | 0.045555 | 0.04348  | 0.041605 |
| 0.65 | 0.2275   | 0.175744 | 0.144858 | 0.123874 | 0.108529 | 0.096751 | 0.08739  | 0.079753 | 0.073392 | 0.068006 | 0.063381 | 0.059364 | 0.05584  | 0.052722 | 0.049942 | 0.047448 | 0.045197 | 0.043154 | 0.041315 |
| 0.7  | 0.21     | 0.1659   | 0.138377 | 0.119229 | 0.105013 | 0.093986 | 0.085152 | 0.077901 | 0.071833 | 0.066673 | 0.062228 | 0.058355 | 0.05495  | 0.05193  | 0.049234 | 0.04681  | 0.044619 | 0.042628 | 0.040835 |
| 0.75 | 0.1875   | 0.152344 | 0.129135 | 0.112459 | 0.099812 | 0.08985  | 0.081777 | 0.075089 | 0.069451 | 0.064627 | 0.060451 | 0.056796 | 0.053571 | 0.050701 | 0.04813  | 0.045814 | 0.043715 | 0.041804 | 0.040085 |
| 0.8  | 0.16     | 0.1344   | 0.116337 | 0.102802 | 0.092234 | 0.083727 | 0.076717 | 0.070831 | 0.065814 | 0.061483 | 0.057703 | 0.054373 | 0.051417 | 0.048773 | 0.046394 | 0.044242 | 0.042284 | 0.040496 | 0.038851 |
| 0.85 | 0.1275   | 0.111244 | 0.098869 | 0.089094 | 0.081156 | 0.07457  | 0.069009 | 0.064247 | 0.060119 | 0.056505 | 0.053312 | 0.05047  | 0.047923 | 0.045626 | 0.043544 | 0.041648 | 0.039914 | 0.038321 | 0.036871 |
| 0.9  | 0.09     | 0.0819   | 0.075192 | 0.069538 | 0.064703 | 0.060516 | 0.056854 | 0.053622 | 0.050746 | 0.048171 | 0.045851 | 0.043749 | 0.041835 | 0.040084 | 0.038478 | 0.036997 | 0.035628 | 0.034359 | 0.033185 |
| 0.95 | 0.0475   | 0.045244 | 0.043197 | 0.041331 | 0.039623 | 0.038053 | 0.036605 | 0.035265 | 0.034021 | 0.032864 | 0.031784 | 0.030773 | 0.029826 | 0.028937 | 0.028099 | 0.02731  | 0.026564 | 0.025858 | 0.025185 |
| 1    | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 | -2.2E-16 |



$$r = 2 \quad x_{n+1} = rx_n (1 - x_n)$$

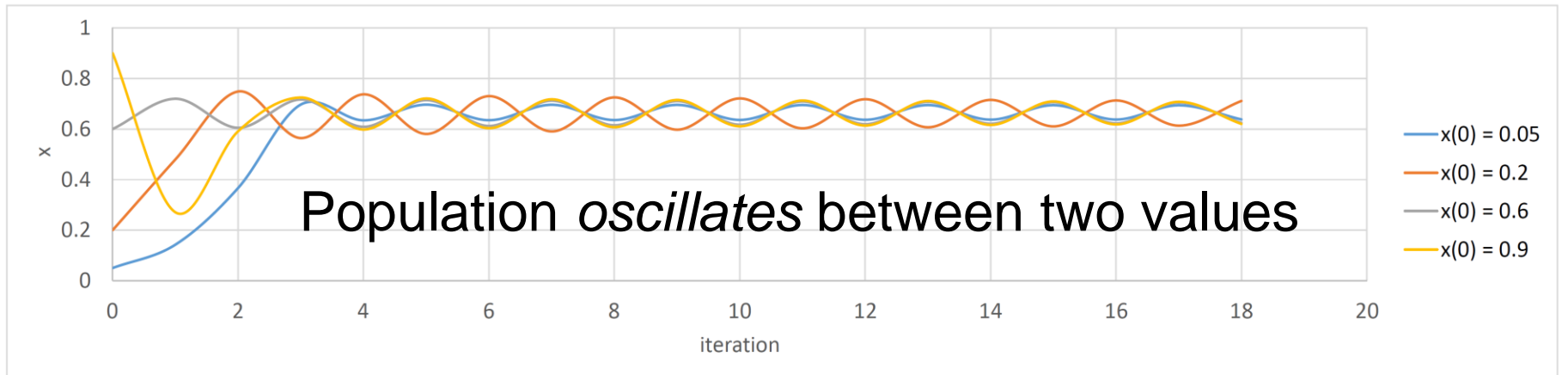
iteration number n

| x(n) | 0        | 1        | 2        | 3        | 4        | 5        | 6        | 7        | 8        | 9        | 10       | 11       | 12       | 13       | 14       | 15       | 16       | 17       | 18  |
|------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|-----|
| 0    | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0   |
| 0.05 | 0.095    | 0.17195  | 0.284766 | 0.407349 | 0.482832 | 0.49941  | 0.499999 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.1  | 0.18     | 0.2952   | 0.416114 | 0.485926 | 0.499604 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.15 | 0.255    | 0.37995  | 0.471176 | 0.498338 | 0.499994 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.2  | 0.32     | 0.4352   | 0.491602 | 0.499859 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.25 | 0.375    | 0.46875  | 0.498047 | 0.499992 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.3  | 0.42     | 0.4872   | 0.499672 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.35 | 0.455    | 0.49595  | 0.499967 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.4  | 0.48     | 0.4992   | 0.499999 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.45 | 0.495    | 0.49995  | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.5  | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.55 | 0.495    | 0.49995  | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.6  | 0.48     | 0.4992   | 0.499999 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.65 | 0.455    | 0.49595  | 0.499967 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.7  | 0.42     | 0.4872   | 0.499672 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.75 | 0.375    | 0.46875  | 0.498047 | 0.499992 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.8  | 0.32     | 0.4352   | 0.491602 | 0.499859 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.85 | 0.255    | 0.37995  | 0.471176 | 0.498338 | 0.499994 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.9  | 0.18     | 0.2952   | 0.416114 | 0.485926 | 0.499604 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 0.95 | 0.095    | 0.17195  | 0.284766 | 0.407349 | 0.482832 | 0.49941  | 0.499999 | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5      | 0.5 |
| 1    | -4.4E-16 | -8.9E-16 | -1.8E-15 | -3.6E-15 | -7.1E-15 | -1.4E-14 | -2.8E-14 | -5.7E-14 | -1.1E-13 | -2.3E-13 | -4.5E-13 | -9.1E-13 | -1.8E-12 | -3.6E-12 | -7.3E-12 | -1.5E-11 | -2.9E-11 | -5.8E-11 |     |



$$r = 3 \quad x_{n+1} = rx_n (1 - x_n)$$

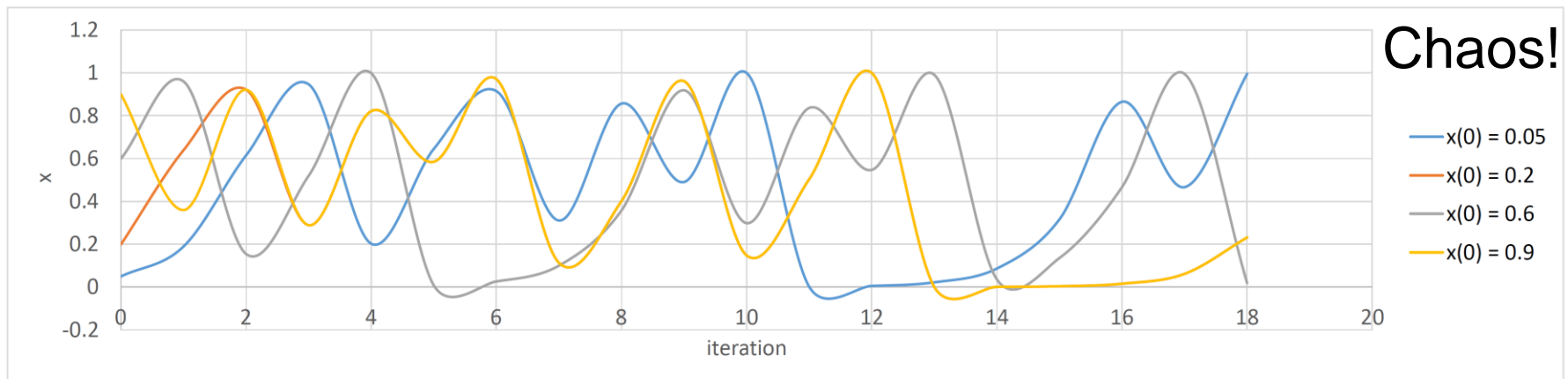
| iteration number n |          | 0        | 1        | 2        | 3        | 4        | 5        | 6        | 7        | 8        | 9        | 10       | 11       | 12       | 13       | 14       | 15       | 16       | 17       | 18 |
|--------------------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----|
| x(n)               | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0  |
| 0.05               | 0.1425   | 0.366581 | 0.696598 | 0.634047 | 0.696094 | 0.634641 | 0.695615 | 0.635204 | 0.695159 | 0.635738 | 0.694725 | 0.636246 | 0.694311 | 0.63673  | 0.693915 | 0.637191 | 0.693536 | 0.637632 | 0.637632 |    |
| 0.1                | 0.27     | 0.5913   | 0.724993 | 0.598135 | 0.721109 | 0.603333 | 0.717967 | 0.607471 | 0.71535  | 0.610873 | 0.713121 | 0.613738 | 0.711191 | 0.616195 | 0.709496 | 0.618334 | 0.707991 | 0.620219 | 0.620219 |    |
| 0.15               | 0.3825   | 0.708581 | 0.619482 | 0.707172 | 0.621239 | 0.705904 | 0.622811 | 0.704752 | 0.62423  | 0.703701 | 0.625518 | 0.702736 | 0.626694 | 0.701846 | 0.627775 | 0.701021 | 0.628772 | 0.700253 | 0.700253 |    |
| 0.2                | 0.48     | 0.7488   | 0.564296 | 0.737598 | 0.580641 | 0.730491 | 0.590622 | 0.725363 | 0.597634 | 0.721403 | 0.602943 | 0.718208 | 0.607155 | 0.715553 | 0.61061  | 0.713296 | 0.613514 | 0.711343 | 0.711343 |    |
| 0.25               | 0.5625   | 0.738281 | 0.579666 | 0.73096  | 0.589973 | 0.725715 | 0.597158 | 0.721681 | 0.602573 | 0.718436 | 0.606857 | 0.715745 | 0.610362 | 0.71346  | 0.613304 | 0.711487 | 0.61582  | 0.709757 | 0.709757 |    |
| 0.3                | 0.63     | 0.6993   | 0.630839 | 0.698644 | 0.631622 | 0.698027 | 0.632356 | 0.697446 | 0.633046 | 0.696897 | 0.633695 | 0.696377 | 0.634308 | 0.695884 | 0.634889 | 0.695415 | 0.635439 | 0.694969 | 0.694969 |    |
| 0.35               | 0.6825   | 0.650081 | 0.682427 | 0.650161 | 0.682355 | 0.65024  | 0.682284 | 0.650318 | 0.682213 | 0.650395 | 0.682144 | 0.65047  | 0.682076 | 0.650545 | 0.682009 | 0.650619 | 0.681942 | 0.650691 | 0.650691 |    |
| 0.4                | 0.72     | 0.6048   | 0.717051 | 0.608667 | 0.714575 | 0.611873 | 0.712453 | 0.614591 | 0.710607 | 0.616934 | 0.708979 | 0.618983 | 0.707529 | 0.620795 | 0.706226 | 0.622413 | 0.705045 | 0.62387  | 0.62387  |    |
| 0.45               | 0.7425   | 0.573581 | 0.733757 | 0.586072 | 0.727775 | 0.594356 | 0.723291 | 0.600424 | 0.719745 | 0.605136 | 0.716839 | 0.608942 | 0.714395 | 0.612105 | 0.712298 | 0.614789 | 0.71047  | 0.617107 | 0.617107 |    |
| 0.5                | 0.75     | 0.5625   | 0.738281 | 0.579666 | 0.73096  | 0.589973 | 0.725715 | 0.597158 | 0.721681 | 0.602573 | 0.718436 | 0.606857 | 0.715745 | 0.610362 | 0.71346  | 0.613304 | 0.711487 | 0.61582  | 0.61582  |    |
| 0.55               | 0.7425   | 0.573581 | 0.733757 | 0.586072 | 0.727775 | 0.594356 | 0.723291 | 0.600424 | 0.719745 | 0.605136 | 0.716839 | 0.608942 | 0.714395 | 0.612105 | 0.712298 | 0.614789 | 0.71047  | 0.617107 | 0.617107 |    |
| 0.6                | 0.72     | 0.6048   | 0.717051 | 0.608667 | 0.714575 | 0.611873 | 0.712453 | 0.614591 | 0.710607 | 0.616934 | 0.708979 | 0.618983 | 0.707529 | 0.620795 | 0.706226 | 0.622413 | 0.705045 | 0.62387  | 0.62387  |    |
| 0.65               | 0.6825   | 0.650081 | 0.682427 | 0.650161 | 0.682355 | 0.65024  | 0.682284 | 0.650318 | 0.682213 | 0.650395 | 0.682144 | 0.65047  | 0.682076 | 0.650545 | 0.682009 | 0.650619 | 0.681942 | 0.650691 | 0.650691 |    |
| 0.7                | 0.63     | 0.6993   | 0.630839 | 0.698644 | 0.631622 | 0.698027 | 0.632356 | 0.697446 | 0.633046 | 0.696897 | 0.633695 | 0.696377 | 0.634308 | 0.695884 | 0.634889 | 0.695415 | 0.635439 | 0.694969 | 0.694969 |    |
| 0.75               | 0.5625   | 0.738281 | 0.579666 | 0.73096  | 0.589973 | 0.725715 | 0.597158 | 0.721681 | 0.602573 | 0.718436 | 0.606857 | 0.715745 | 0.610362 | 0.71346  | 0.613304 | 0.711487 | 0.61582  | 0.709757 | 0.709757 |    |
| 0.8                | 0.48     | 0.7488   | 0.564296 | 0.737598 | 0.580641 | 0.730491 | 0.590622 | 0.725363 | 0.597634 | 0.721403 | 0.602943 | 0.718208 | 0.607155 | 0.715553 | 0.61061  | 0.713296 | 0.613514 | 0.711343 | 0.711343 |    |
| 0.85               | 0.3825   | 0.708581 | 0.619482 | 0.707172 | 0.621239 | 0.705904 | 0.622811 | 0.704752 | 0.62423  | 0.703701 | 0.625518 | 0.702736 | 0.626694 | 0.701846 | 0.627775 | 0.701021 | 0.628772 | 0.700253 | 0.700253 |    |
| 0.9                | 0.27     | 0.5913   | 0.724993 | 0.598135 | 0.721109 | 0.603333 | 0.717967 | 0.607471 | 0.71535  | 0.610873 | 0.713121 | 0.613738 | 0.711191 | 0.616195 | 0.709496 | 0.618334 | 0.707991 | 0.620219 | 0.620219 |    |
| 0.95               | 0.1425   | 0.366581 | 0.696598 | 0.634047 | 0.696094 | 0.634641 | 0.695615 | 0.635204 | 0.695159 | 0.635738 | 0.694725 | 0.636246 | 0.694311 | 0.63673  | 0.693915 | 0.637191 | 0.693536 | 0.637632 | 0.637632 |    |
| 1                  | -6.7E-16 | -2E-15   | -6E-15   | -1.8E-14 | -5.4E-14 | -1.6E-13 | -4.9E-13 | -1.5E-12 | -4.4E-12 | -1.3E-11 | -3.9E-11 | -1.2E-10 | -3.5E-10 | -1.1E-09 | -3.2E-09 | -9.6E-09 | -2.9E-08 | -8.6E-08 | -8.6E-08 |    |



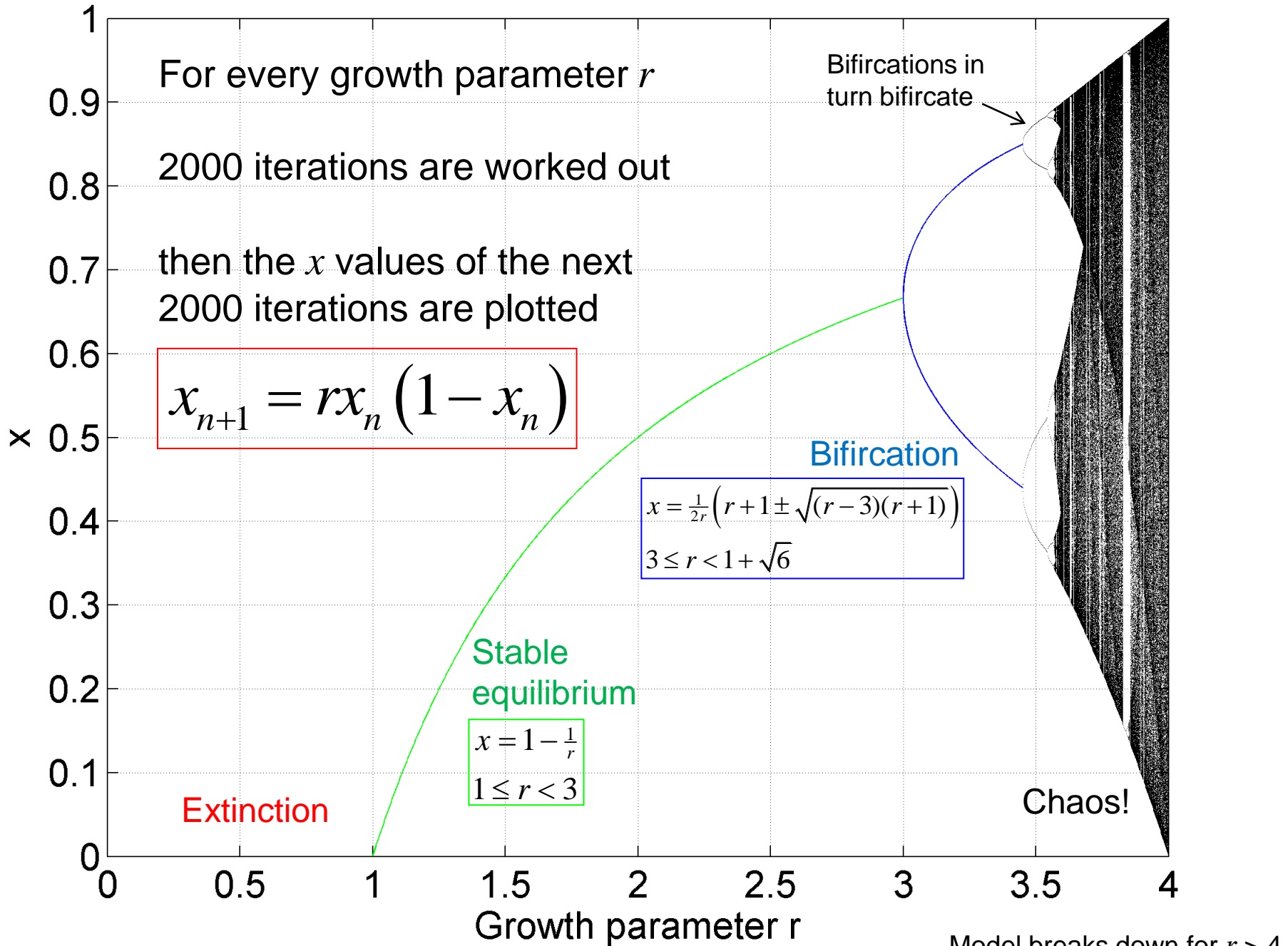
$$r = 4 \quad x_{n+1} = rx_n (1 - x_n)$$

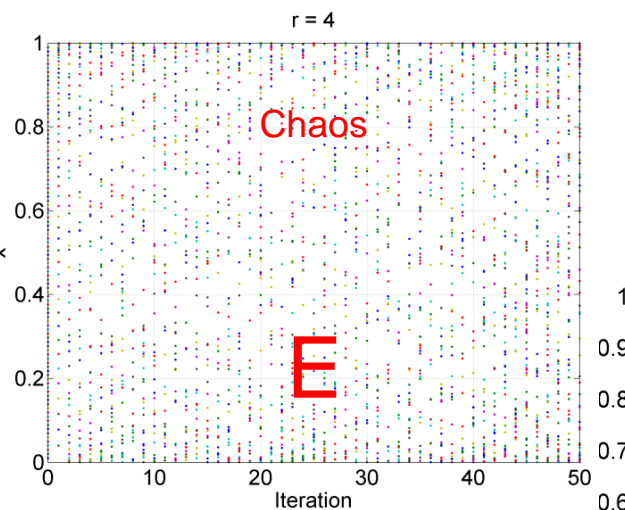
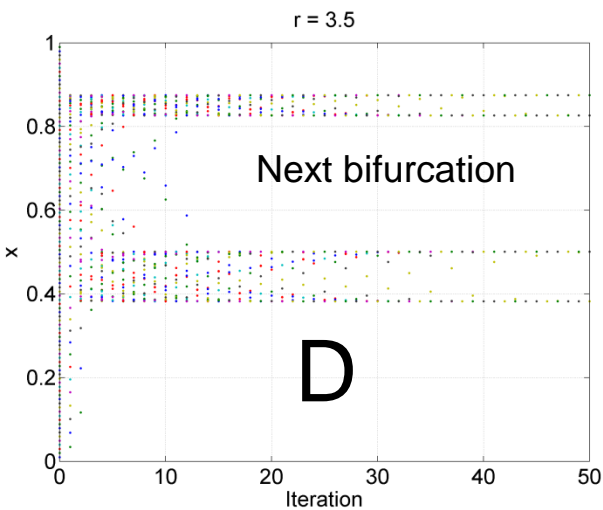
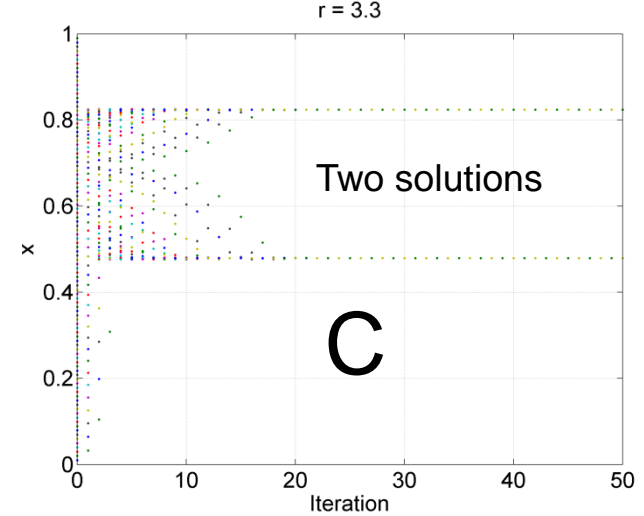
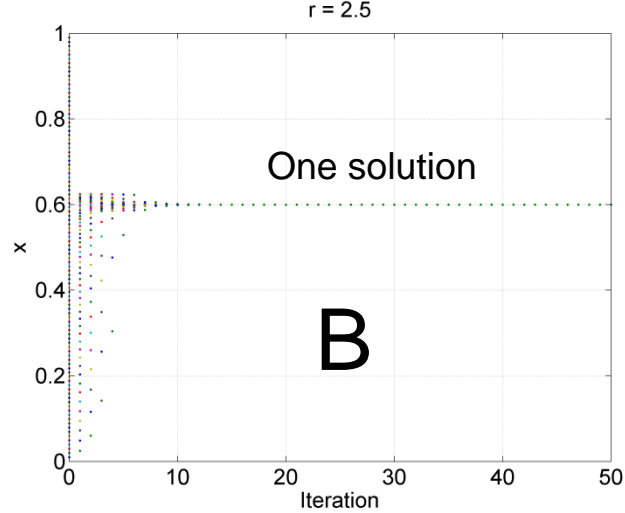
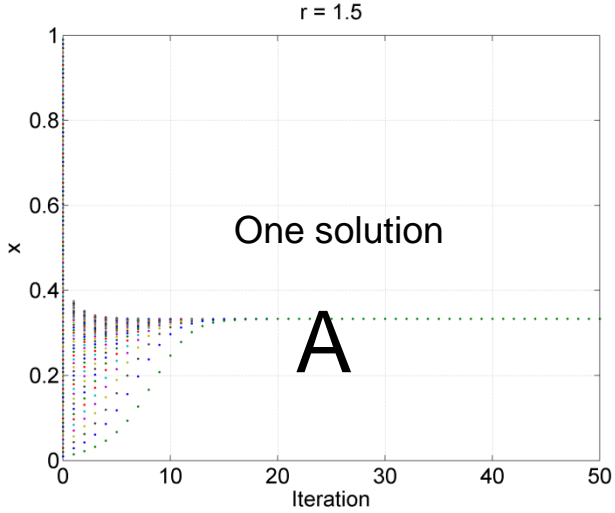
iteration number n

| x(n) | 0        | 1        | 2        | 3        | 4        | 5        | 6        | 7        | 8        | 9        | 10       | 11       | 12       | 13       | 14       | 15       | 16       | 17       | 18 |
|------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----|
| 0    | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0        | 0  |
| 0.05 | 0.19     | 0.6156   | 0.946547 | 0.202385 | 0.6457   | 0.915085 | 0.310816 | 0.856838 | 0.490667 | 0.999652 | 0.001393 | 0.005565 | 0.022137 | 0.086589 | 0.316366 | 0.865114 | 0.466766 | 0.995582 |    |
| 0.1  | 0.36     | 0.9216   | 0.289014 | 0.821939 | 0.585421 | 0.970813 | 0.113339 | 0.401974 | 0.961563 | 0.147837 | 0.503924 | 0.999938 | 0.000246 | 0.000985 | 0.003936 | 0.015682 | 0.061745 | 0.23173  |    |
| 0.15 | 0.51     | 0.9996   | 0.001599 | 0.006387 | 0.025386 | 0.098965 | 0.356683 | 0.917841 | 0.301635 | 0.842605 | 0.530488 | 0.996282 | 0.014817 | 0.058389 | 0.219918 | 0.686217 | 0.861293 | 0.47787  |    |
| 0.2  | 0.64     | 0.9216   | 0.289014 | 0.821939 | 0.585421 | 0.970813 | 0.113339 | 0.401974 | 0.961563 | 0.147837 | 0.503924 | 0.999938 | 0.000246 | 0.000985 | 0.003936 | 0.015682 | 0.061745 | 0.23173  |    |
| 0.25 | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     |    |
| 0.3  | 0.84     | 0.5376   | 0.994345 | 0.022492 | 0.087945 | 0.320844 | 0.871612 | 0.447617 | 0.989024 | 0.043422 | 0.166146 | 0.554165 | 0.988265 | 0.046391 | 0.176954 | 0.582565 | 0.972732 | 0.106097 |    |
| 0.35 | 0.91     | 0.3276   | 0.881113 | 0.419012 | 0.973764 | 0.102192 | 0.366996 | 0.92924  | 0.263011 | 0.775345 | 0.69674  | 0.845174 | 0.523421 | 0.997806 | 0.008757 | 0.034722 | 0.134065 | 0.464367 |    |
| 0.4  | 0.96     | 0.1536   | 0.520028 | 0.998395 | 0.006408 | 0.025467 | 0.099273 | 0.35767  | 0.918969 | 0.29786  | 0.836557 | 0.546917 | 0.991195 | 0.034909 | 0.134761 | 0.466403 | 0.995485 | 0.017978 |    |
| 0.45 | 0.99     | 0.0396   | 0.152127 | 0.515939 | 0.998984 | 0.00406  | 0.016176 | 0.063657 | 0.238418 | 0.7263   | 0.795154 | 0.651537 | 0.908147 | 0.333665 | 0.889331 | 0.393686 | 0.954789 | 0.172666 |    |
| 0.5  | 1        | 4.44E-16 | 1.78E-15 | 7.11E-15 | 2.84E-14 | 1.14E-13 | 4.55E-13 | 1.82E-12 | 7.28E-12 | 2.91E-11 | 1.16E-10 | 4.66E-10 | 1.86E-09 | 7.45E-09 | 2.98E-08 | 1.19E-07 | 4.77E-07 | 1.91E-06 |    |
| 0.55 | 0.99     | 0.0396   | 0.152127 | 0.515939 | 0.998984 | 0.00406  | 0.016176 | 0.063657 | 0.238418 | 0.7263   | 0.795154 | 0.651537 | 0.908147 | 0.333665 | 0.889331 | 0.393686 | 0.954789 | 0.172666 |    |
| 0.6  | 0.96     | 0.1536   | 0.520028 | 0.998395 | 0.006408 | 0.025467 | 0.099273 | 0.35767  | 0.918969 | 0.29786  | 0.836557 | 0.546917 | 0.991195 | 0.034909 | 0.134761 | 0.466403 | 0.995485 | 0.017978 |    |
| 0.65 | 0.91     | 0.3276   | 0.881113 | 0.419012 | 0.973764 | 0.102192 | 0.366996 | 0.92924  | 0.263011 | 0.775345 | 0.69674  | 0.845174 | 0.523421 | 0.997806 | 0.008757 | 0.034722 | 0.134065 | 0.464367 |    |
| 0.7  | 0.84     | 0.5376   | 0.994345 | 0.022492 | 0.087945 | 0.320844 | 0.871612 | 0.447617 | 0.989024 | 0.043422 | 0.166146 | 0.554165 | 0.988265 | 0.046391 | 0.176954 | 0.582565 | 0.972732 | 0.106097 |    |
| 0.75 | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     | 0.75     |    |
| 0.8  | 0.64     | 0.9216   | 0.289014 | 0.821939 | 0.585421 | 0.970813 | 0.113339 | 0.401974 | 0.961563 | 0.147837 | 0.503924 | 0.999938 | 0.000246 | 0.000985 | 0.003936 | 0.015682 | 0.061745 | 0.23173  |    |
| 0.85 | 0.51     | 0.9996   | 0.001599 | 0.006387 | 0.025386 | 0.098965 | 0.356683 | 0.917841 | 0.301635 | 0.842605 | 0.530488 | 0.996282 | 0.014817 | 0.058389 | 0.219918 | 0.686217 | 0.861293 | 0.47787  |    |
| 0.9  | 0.36     | 0.9216   | 0.289014 | 0.821939 | 0.585421 | 0.970813 | 0.113339 | 0.401974 | 0.961563 | 0.147837 | 0.503924 | 0.999938 | 0.000246 | 0.000985 | 0.003936 | 0.015682 | 0.061745 | 0.23173  |    |
| 0.95 | 0.19     | 0.6156   | 0.946547 | 0.202385 | 0.6457   | 0.915085 | 0.310816 | 0.856838 | 0.490667 | 0.999652 | 0.001393 | 0.005565 | 0.022137 | 0.086589 | 0.316366 | 0.865114 | 0.466766 | 0.995582 |    |
| 1    | -8.9E-16 | -3.6E-15 | -1.4E-14 | -5.7E-14 | -2.3E-13 | -9.1E-13 | -3.6E-12 | -1.5E-11 | -5.8E-11 | -2.3E-10 | -9.3E-10 | -3.7E-09 | -1.5E-08 | -6E-08   | -2.4E-07 | -9.5E-07 | -3.8E-06 | -1.5E-05 |    |

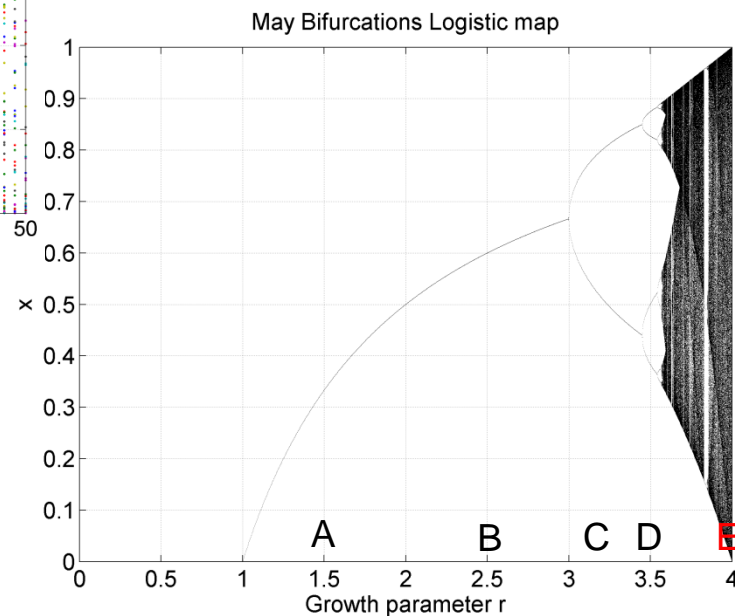


# May Bifurcations Logistic map





$$x_{n+1} = rx_n(1 - x_n)$$



Tracking the bifurcations maps the 'road to chaos'. The ratio of successive bifurcation intervals is a **universal constant!**  
4.669201609...



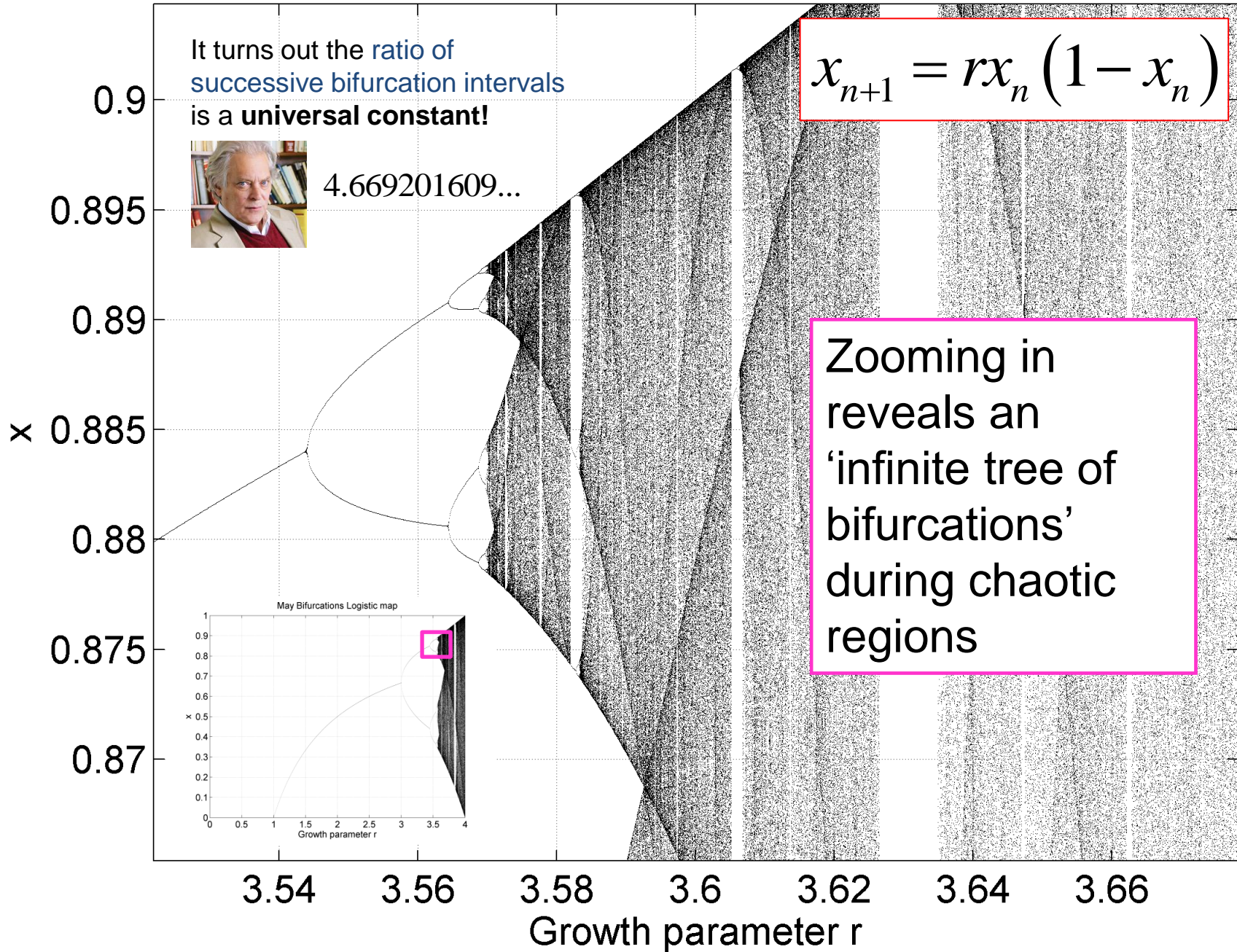
# May Bifurcations Logistic map

It turns out the ratio of successive bifurcation intervals is a **universal constant!**



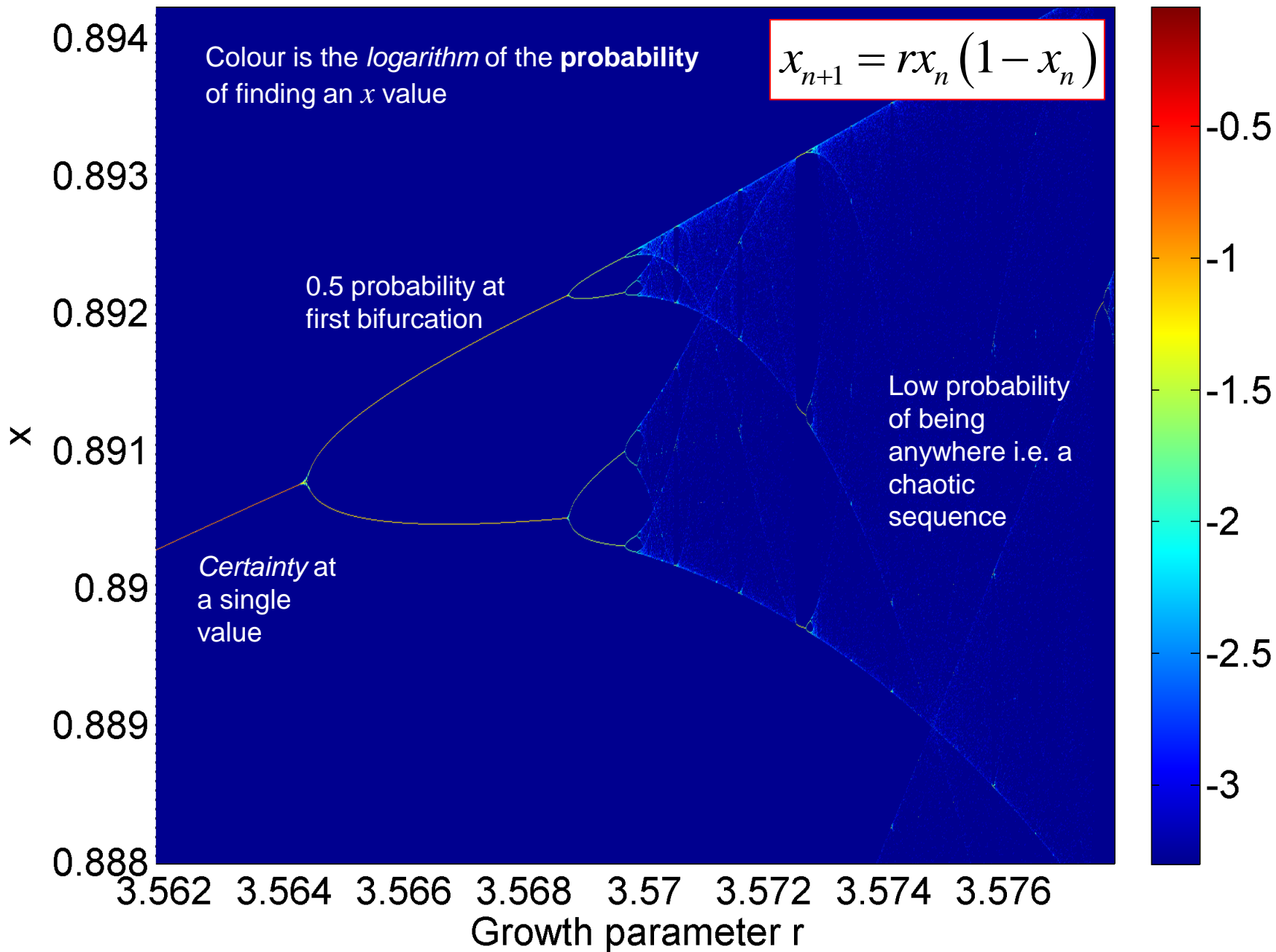
4.669201609...

$$x_{n+1} = rx_n(1 - x_n)$$



Zooming in reveals an 'infinite tree of bifurcations' during chaotic regions

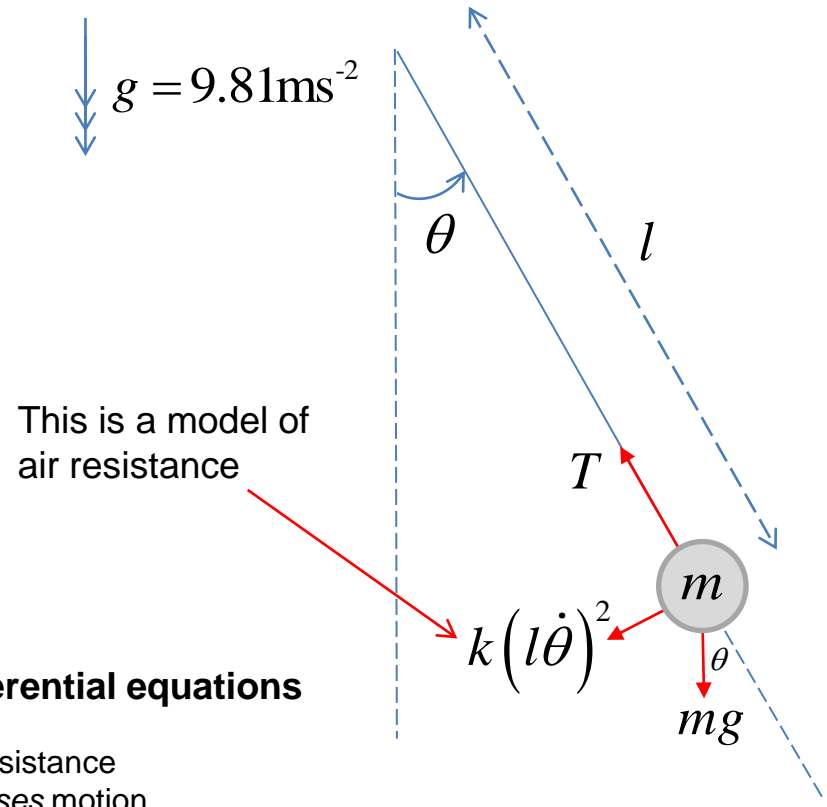
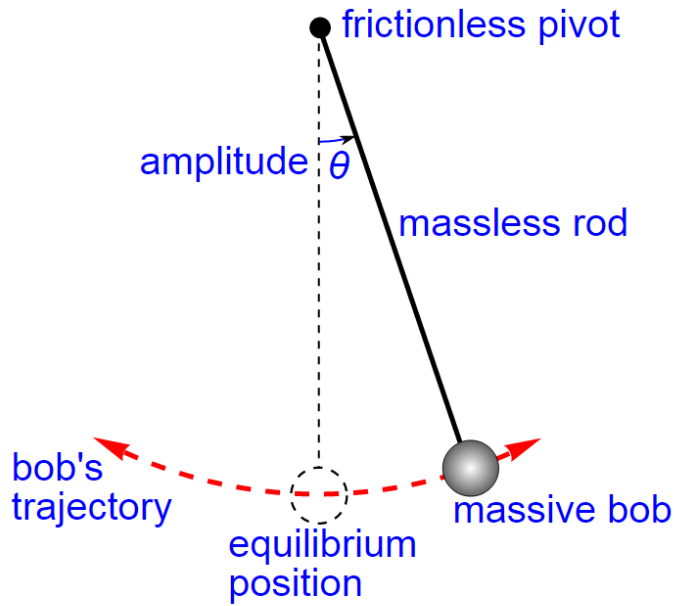
# May Bifurcations Logistic map probability



# Pendulums and phase space

$$\dot{\theta} = \frac{d\theta}{dt}$$

Although we can't fully 'solve' a chaotic system, we can create a **diagram which describes the motion**. In **phase space**, patterns often emerge, which are hidden in the randomness of a **time series**.



We can use **Newton's Second Law** to write down **differential equations** for the motion of the pendulum bob

$$ml \frac{d\dot{\theta}}{dt} = -mg \sin \theta - kl^2 \dot{\theta} |\dot{\theta}|$$

$$\therefore \frac{d\dot{\theta}}{dt} = -\frac{g}{l} \sin \theta - \frac{kl}{m} \dot{\theta} |\dot{\theta}|$$

So that air resistance always *opposes* motion

If angles are small and we ignore air resistance:

$$\frac{d\dot{\theta}}{dt} \approx -\frac{g}{l} \theta$$

We can solve this!

$$\theta = \theta_0 \cos\left(2\pi \frac{t}{P}\right) \quad P = 2\pi \sqrt{\frac{l}{g}}$$

To keep things simple (!) let's use the **period**  $P$  of a frictionless, small angle ideal pendulum to **define a time scale**. We can then make our pendulum equation in terms of **dimensionless numbers**.

$$t \rightarrow P\tau \quad \dot{\theta} \rightarrow \frac{\dot{\theta}}{P} \quad \text{i.e.} \quad \dot{\theta} = \frac{d\theta}{d\tau}$$

using this *dimensionless time scale*

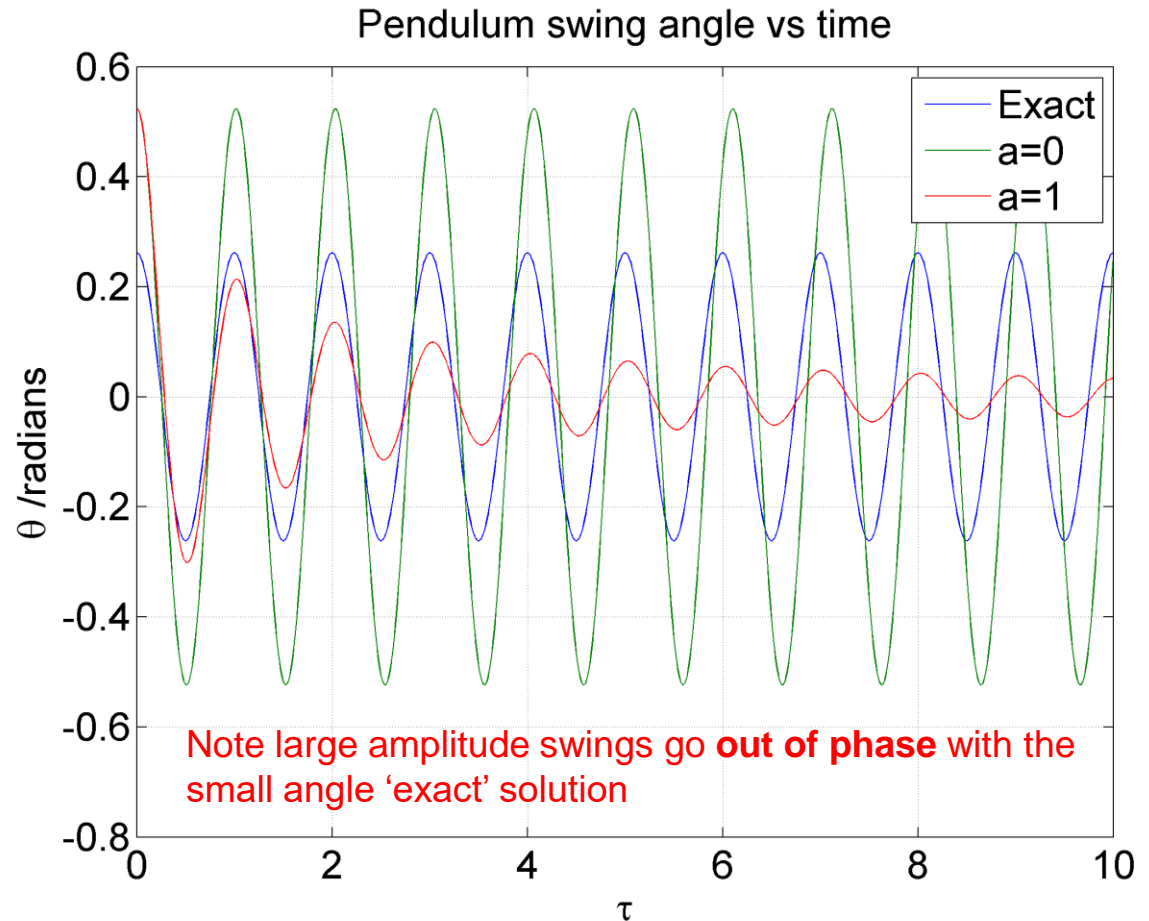
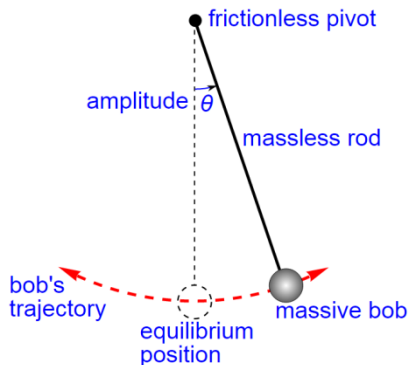
$$P = 2\pi \sqrt{\frac{l}{g}}$$

$$\frac{1}{P^2} \frac{d\dot{\theta}}{d\tau} = -\frac{g}{l} \sin \theta - \frac{1}{P^2} \frac{kl}{m} \dot{\theta} |\dot{\theta}|$$

$$\therefore \frac{d\dot{\theta}}{d\tau} = 4\pi^2 \sin \theta - a \dot{\theta} |\dot{\theta}|$$

$$a = \frac{gk}{4\pi^2 m}$$

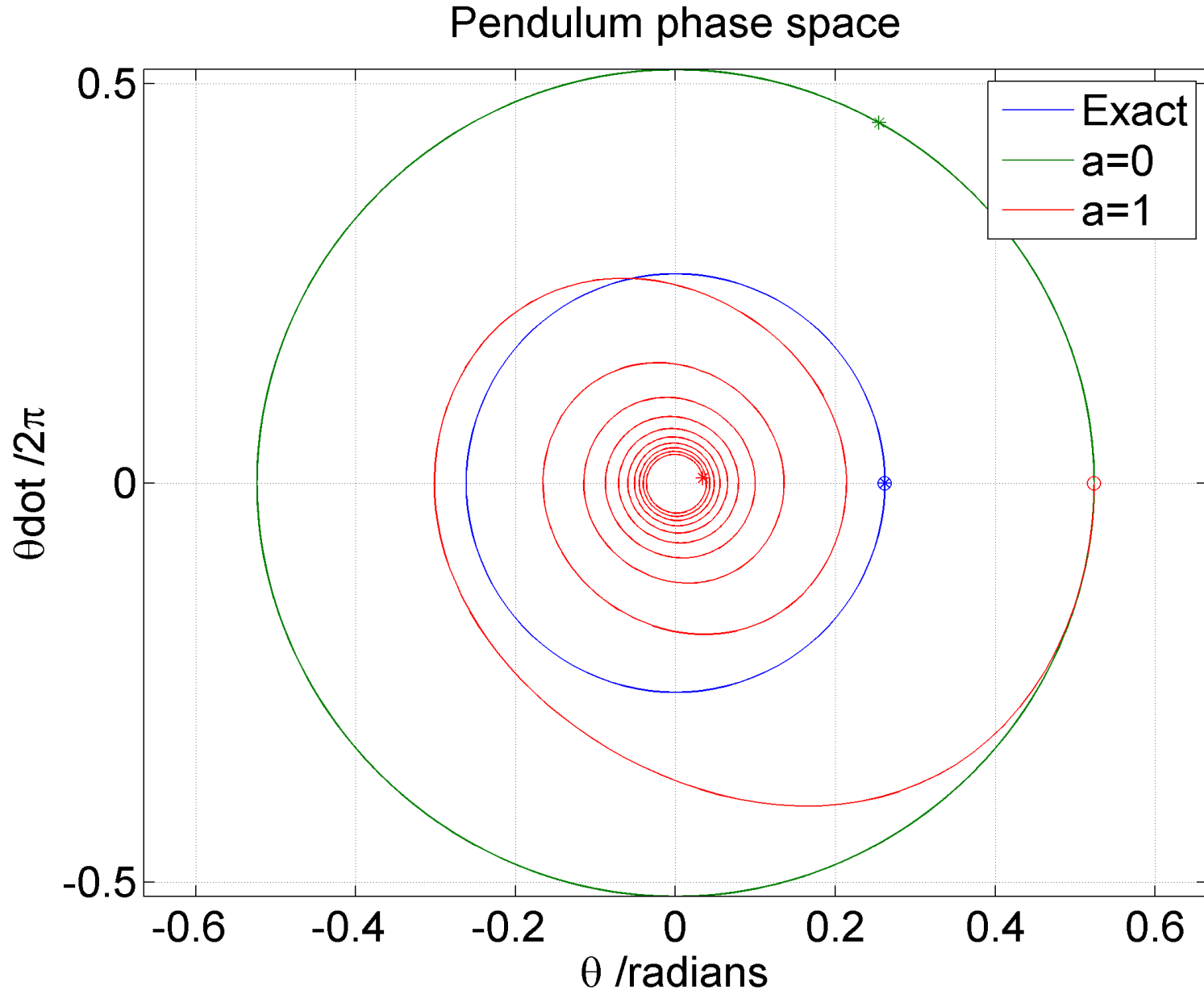
$a$  is now simply a *number* which sets the effect of air resistance



Perhaps a more informative picture of the motion is the **phase portrait**, or **Poincaré diagram**



Henri Poincaré  
1854-1912



Recall 'Exact' means small angles, and no air resistance

The frictionless oscillations are circles whereas air resistance causes an inspiralling to zero angle and zero angular speed



**HARDCORE MATHS ALERT!!**

# The double pendulum

$$x_1 = l_1 \sin \theta_1$$

$$y_1 = -l_1 \cos \theta_1$$

$$x_2 = l_1 \sin \theta_1 + l_2 \sin \theta_2$$

$$y_2 = -l_1 \cos \theta_1 - l_2 \cos \theta_2$$

$x, y$  coordinates

$$v_{x1} = l_1 \cos \theta_1 \dot{\theta}_1$$

$$v_{y1} = l_1 \sin \theta_1 \dot{\theta}_1$$

Velocities

$$v_{x2} = l_1 \cos \theta_1 \dot{\theta}_1 + l_2 \cos \theta_2 \dot{\theta}_2$$

$$v_{y2} = l_1 \sin \theta_1 \dot{\theta}_1 + l_2 \sin \theta_2 \dot{\theta}_2$$

Potential energy

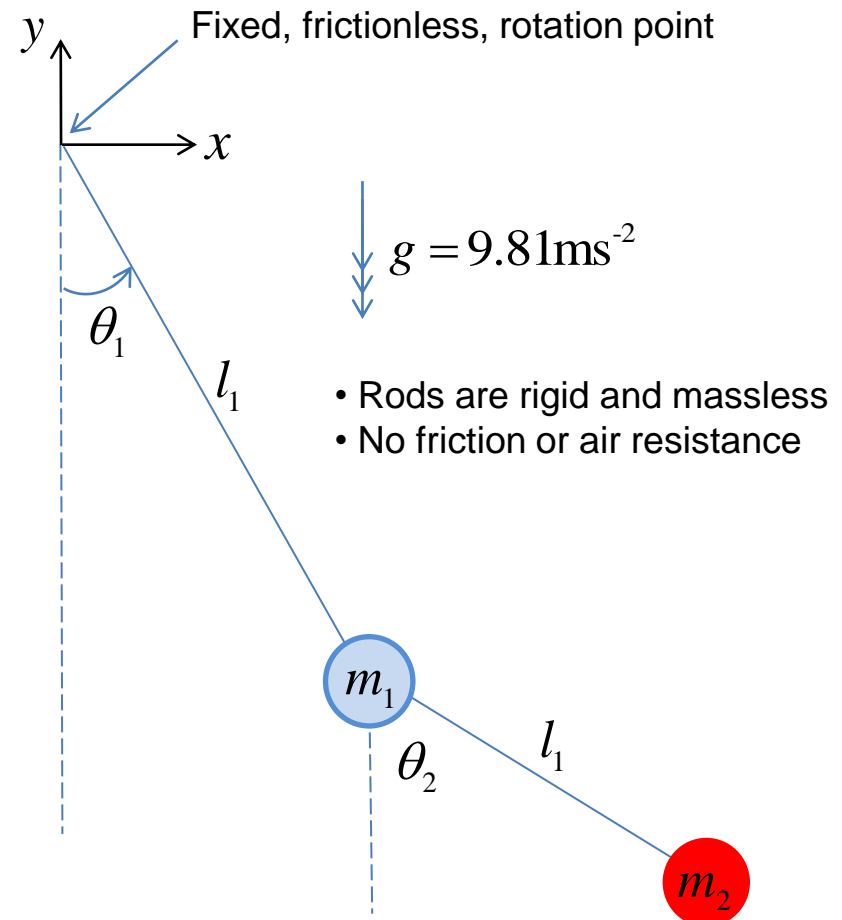
$$V = m_1 g y_1 + m_2 g y_2$$

$$V = -(m_1 + m_2) g l_1 \cos \theta_1 - m_2 g l_2 \cos \theta_2$$

Kinetic energy

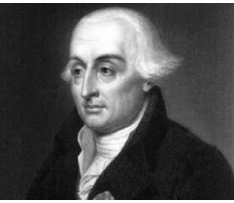
$$T = \frac{1}{2} m_1 (v_{x1}^2 + v_{y1}^2) + \frac{1}{2} m_2 (v_{x2}^2 + v_{y2}^2)$$

$$T = \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 [l_1^2 \dot{\theta}_1^2 + l_2^2 \dot{\theta}_2^2 + 2l_1 l_2 \dot{\theta}_1 \dot{\theta}_2 \cos(\theta_1 - \theta_2)]$$



Ok. Time for a deep breath ...

We need to compute the **Lagrangian**  $L$  and then solve the **Euler-Lagrange equations!**



Joseph Louis Lagrange  
1736-1813

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\theta}_1} \right) = \frac{\partial L}{\partial \theta_1}$$

$$(m_1 + m_2)l_1\ddot{\theta}_1 + m_2l_2\ddot{\theta}_2 \cos(\theta_1 - \theta_2) + m_2l_2\dot{\theta}_2^2 \sin(\theta_1 - \theta_2) + g(m_1 + m_2)\sin\theta_1 = 0 \quad [1]$$

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\theta}_2} \right) = \frac{\partial L}{\partial \theta_2}$$

$$m_2l_1\ddot{\theta}_1 \cos(\theta_1 - \theta_2) + m_2l_2\ddot{\theta}_2 - m_2l_1\dot{\theta}_1^2 \sin(\theta_1 - \theta_2) + m_2g \sin\theta_2 = 0 \quad [2]$$

$$L = T - V$$

$$L = \frac{1}{2}(m_1 + m_2)l_1^2\dot{\theta}_1^2 + \frac{1}{2}m_2l_2^2\dot{\theta}_2^2 + m_2l_1l_2\dot{\theta}_1\dot{\theta}_2 \cos(\theta_1 - \theta_2) + (m_1 + m_2)gl_1 \cos\theta_1 + m_2gl_2 \cos\theta_2$$

$$\frac{d\theta_1}{dt} = \omega_1$$

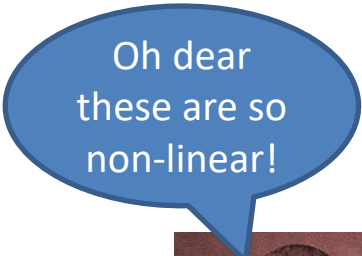
Four coupled non-linear differential equations. A mere bagatelle!

$$\frac{d\omega_1}{dt} = \frac{m_2l_1\omega_1^2 \sin\Delta \cos\Delta + m_2g \sin\theta_2 \cos\Delta + m_2l_2\omega_2^2 \sin\Delta - (m_1 + m_2)g \sin\theta_1}{(m_1 + m_2)l_1 - m_2l_1 \cos^2\Delta}$$

$$\frac{d\theta_2}{dt} = \omega_2$$

$$\frac{d\omega_2}{dt} = \frac{-m_2l_2\omega_2^2 \sin\Delta \cos\Delta + (m_1 + m_2)(g \sin\theta_1 \cos\Delta - l_1\omega_1^2 \sin\Delta - g \sin\theta_2)}{(m_1 + m_2)l_2 - m_2l_2 \cos^2\Delta}$$

$$\Delta = \theta_2 - \theta_1$$



Oh dear these are so non-linear!





We can (approximately) solve the equations for the angles and angular velocities of the double pendulum using a *numeric method*. **Runge-Kutta** is a popular scheme. This has been implemented in MATLAB in order to generate the following plots.

But first a rather boring pendulum scenario to check my simulation makes sense....

## Double pendulum

$m_1 = 1\text{kg}$   $m_2 = 3\text{kg}$   $l_1 = 3\text{ metres}$   $l_2 = 2\text{ metres}$

time = 0 s

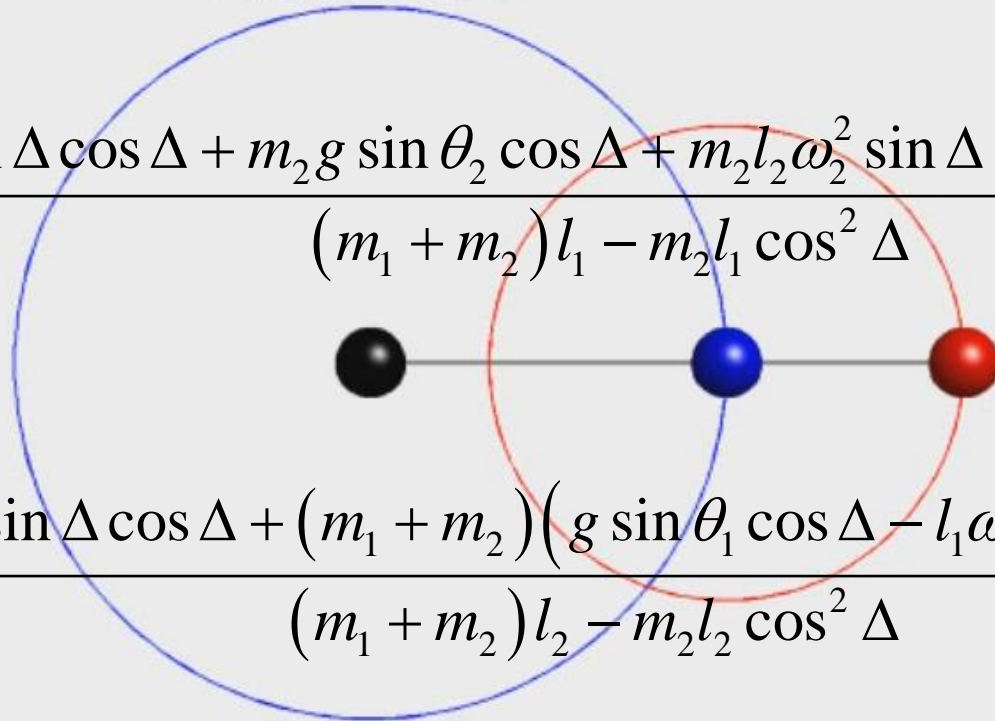
$$\frac{d\theta_1}{dt} = \omega_1$$

$$\frac{d\omega_1}{dt} = \frac{m_2 l_1 \omega_1^2 \sin \Delta \cos \Delta + m_2 g \sin \theta_2 \cos \Delta + m_2 l_2 \omega_2^2 \sin \Delta - (m_1 + m_2) g \sin \theta_1}{(m_1 + m_2) l_1 - m_2 l_1 \cos^2 \Delta}$$

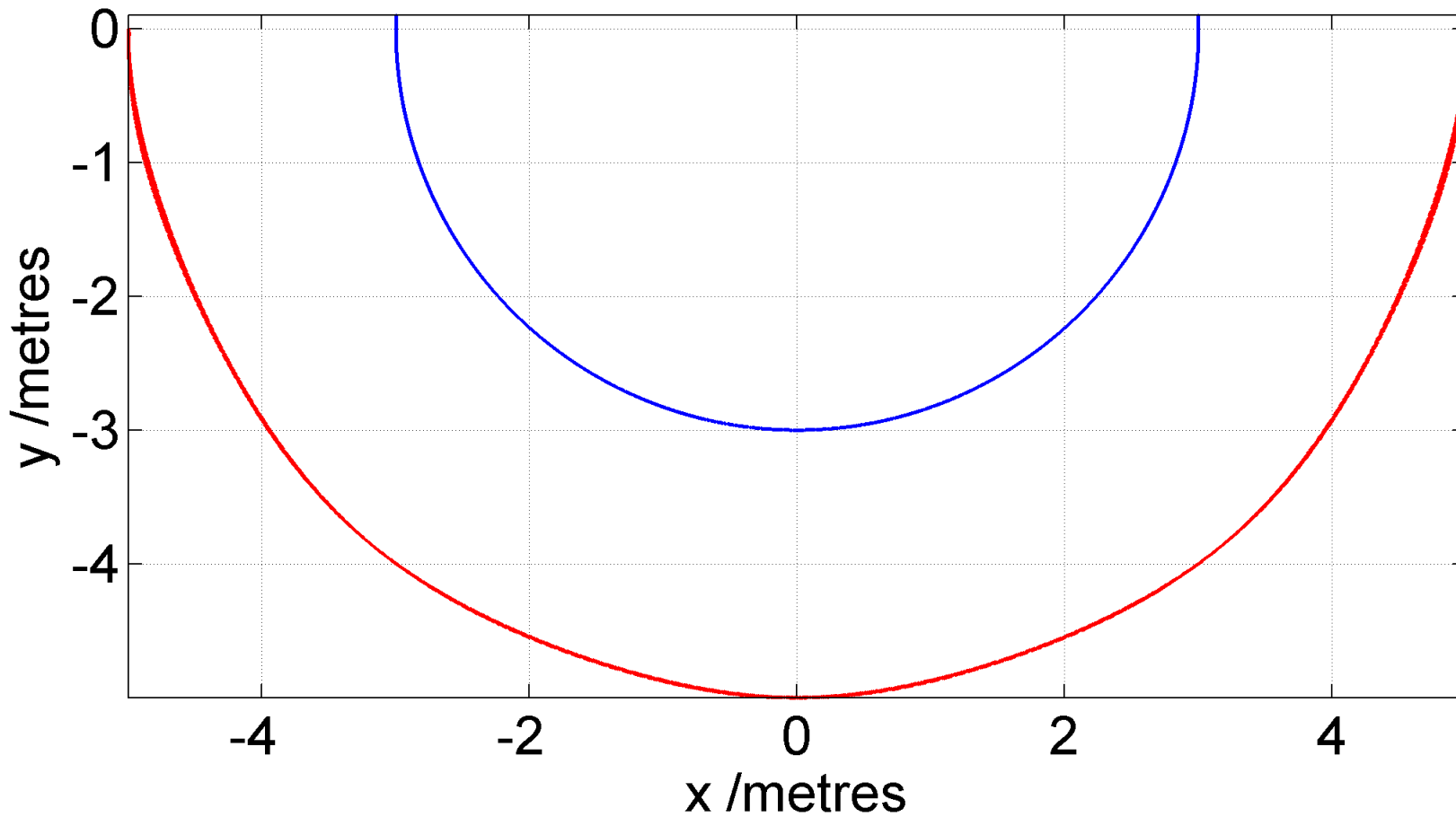
$$\frac{d\theta_2}{dt} = \omega_2$$

$$\frac{d\omega_2}{dt} = \frac{-m_2 l_2 \omega_2^2 \sin \Delta \cos \Delta + (m_1 + m_2) (g \sin \theta_1 \cos \Delta - l_1 \omega_1^2 \sin \Delta - g \sin \theta_2)}{(m_1 + m_2) l_2 - m_2 l_2 \cos^2 \Delta}$$

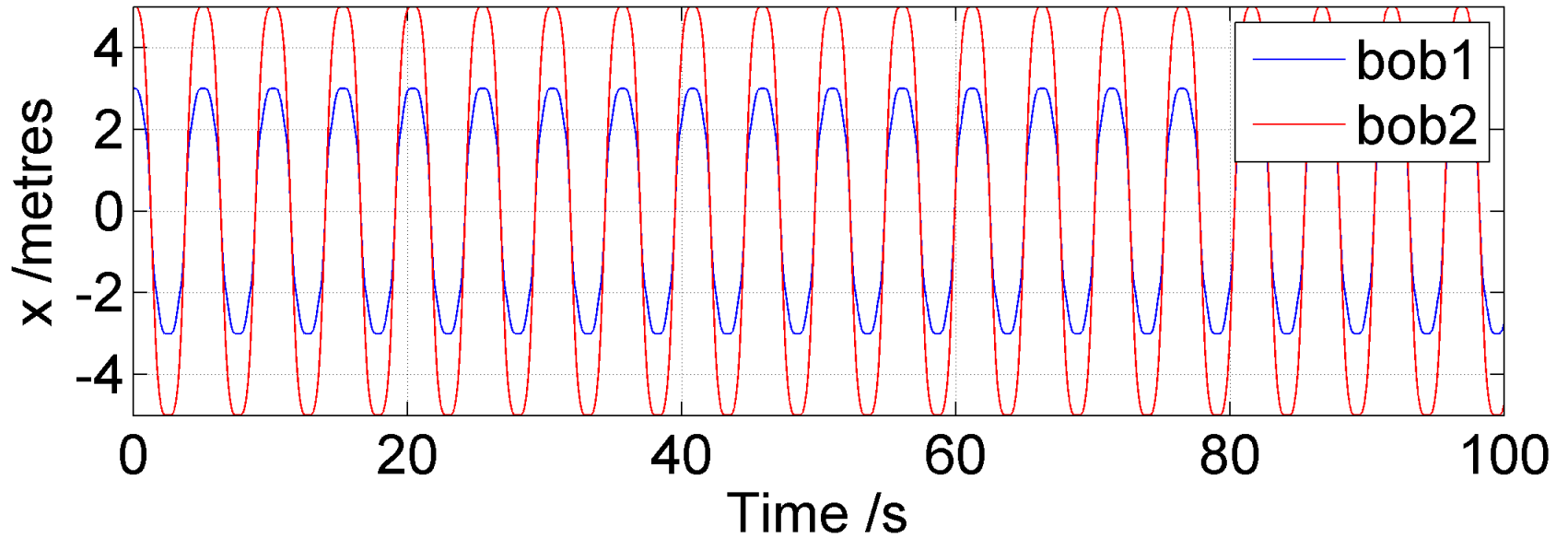
$$\Delta = \theta_2 - \theta_1$$



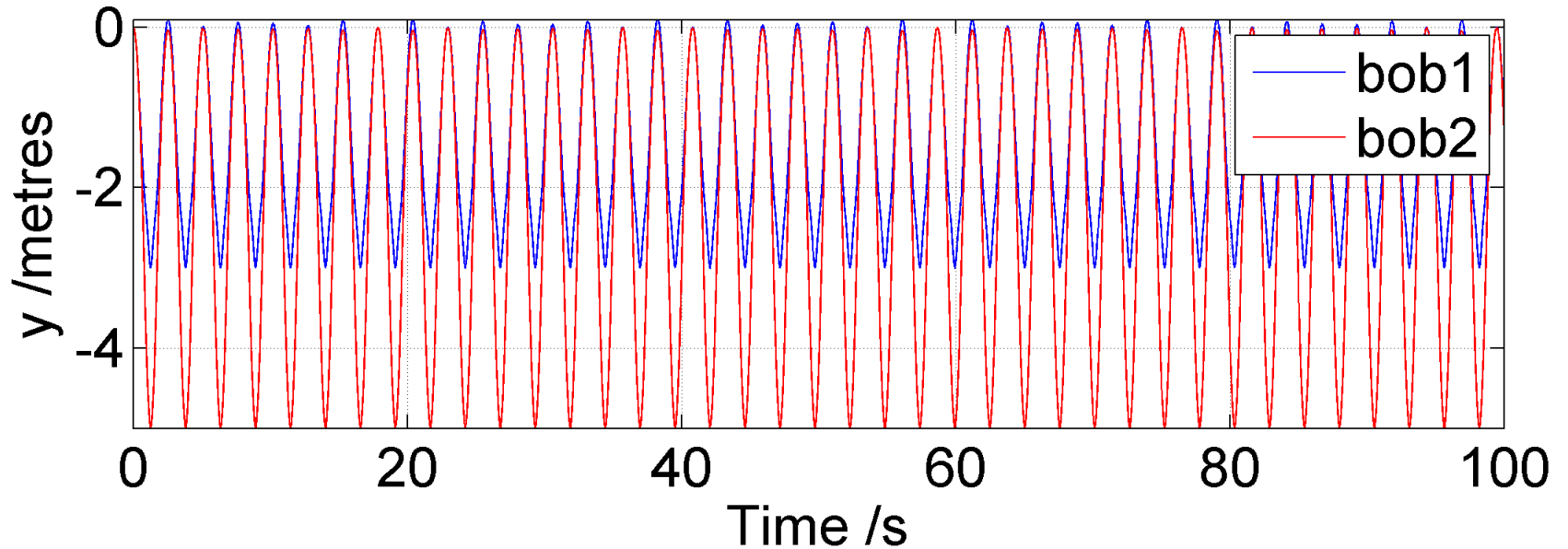
Pendulum bob x,y trajectories. Bob1 is blue, Bob2 is red



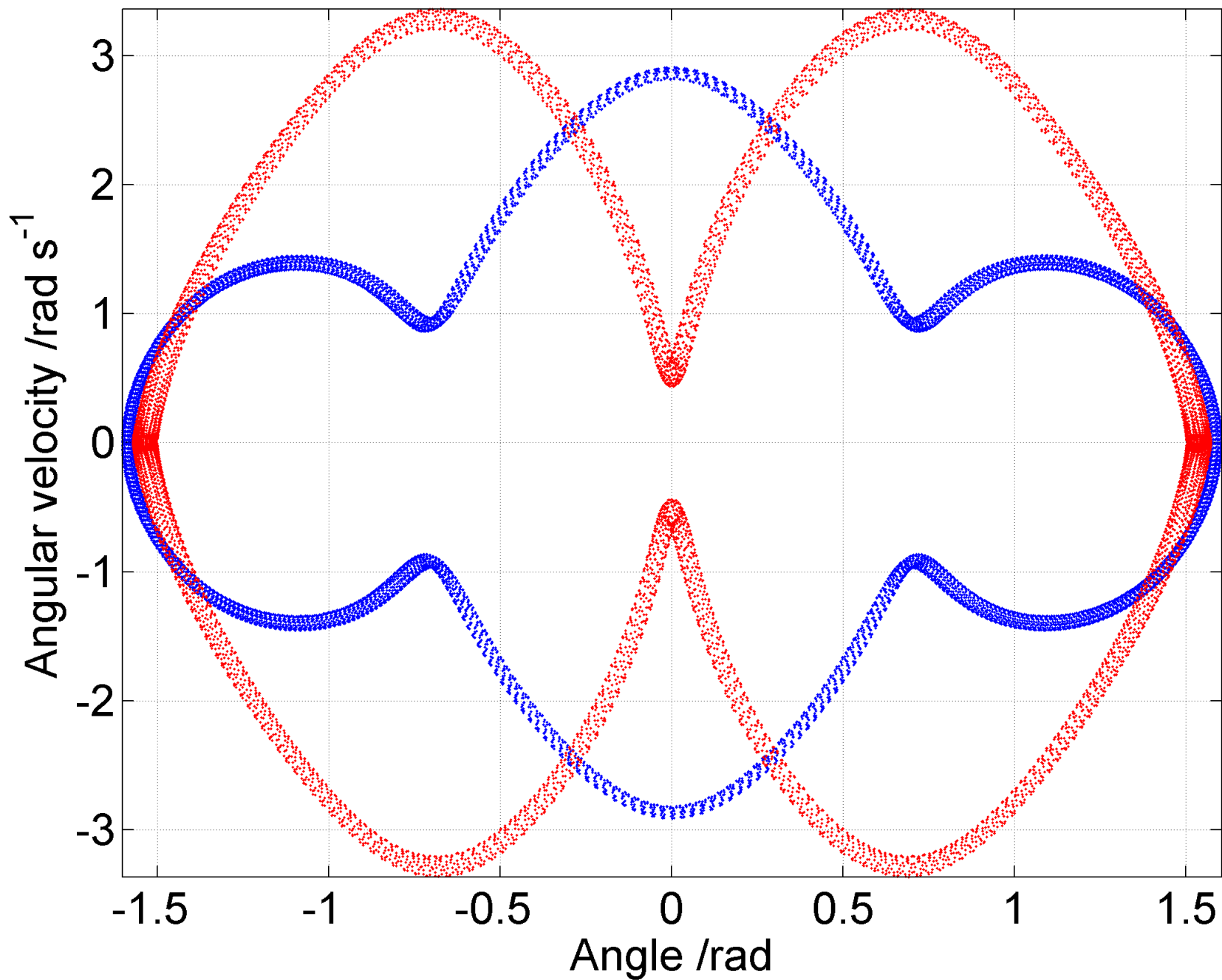
### Pendulum bob x positions



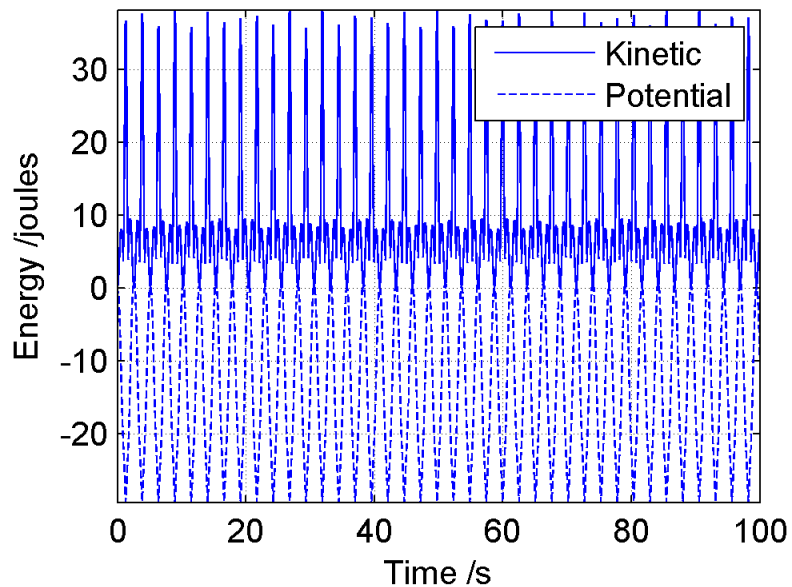
### Pendulum bob y positions



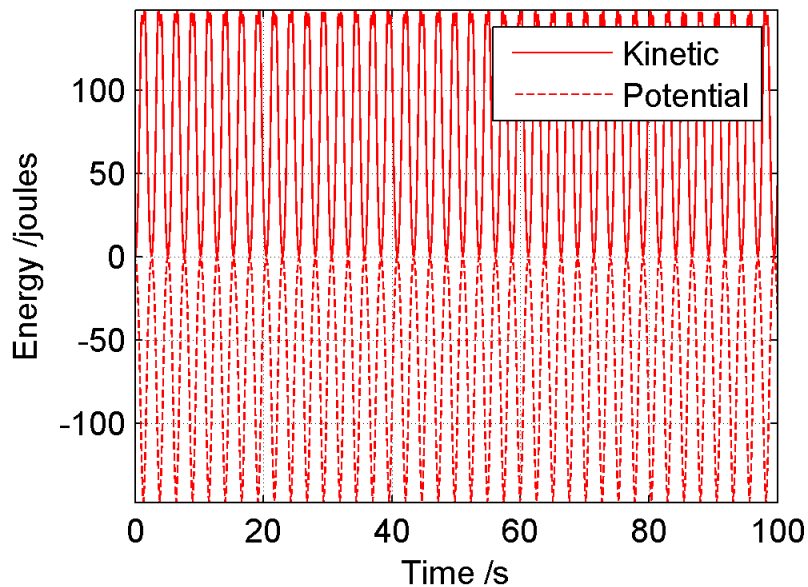
Poincare diagram: bob1 is blue, bob2 is red



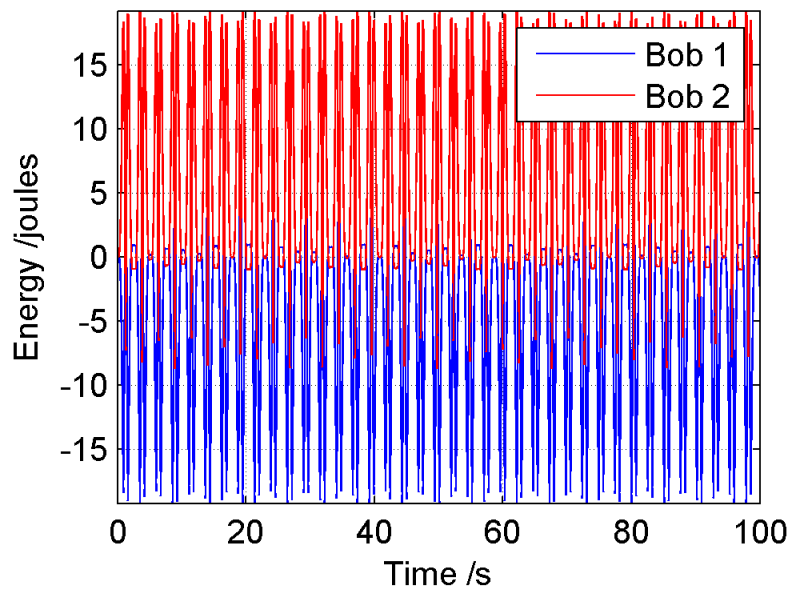
Pendulum bob 1 kinetic, potential energy



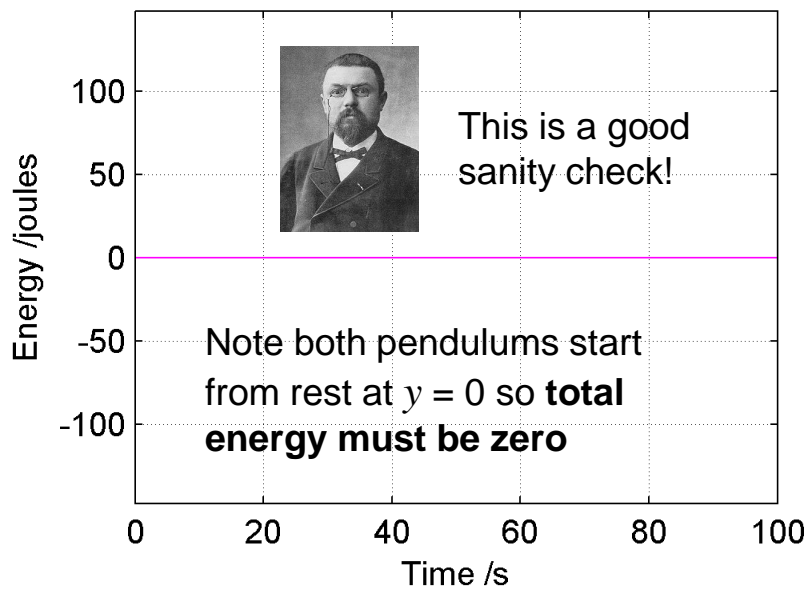
Pendulum bob 2 kinetic, potential energy



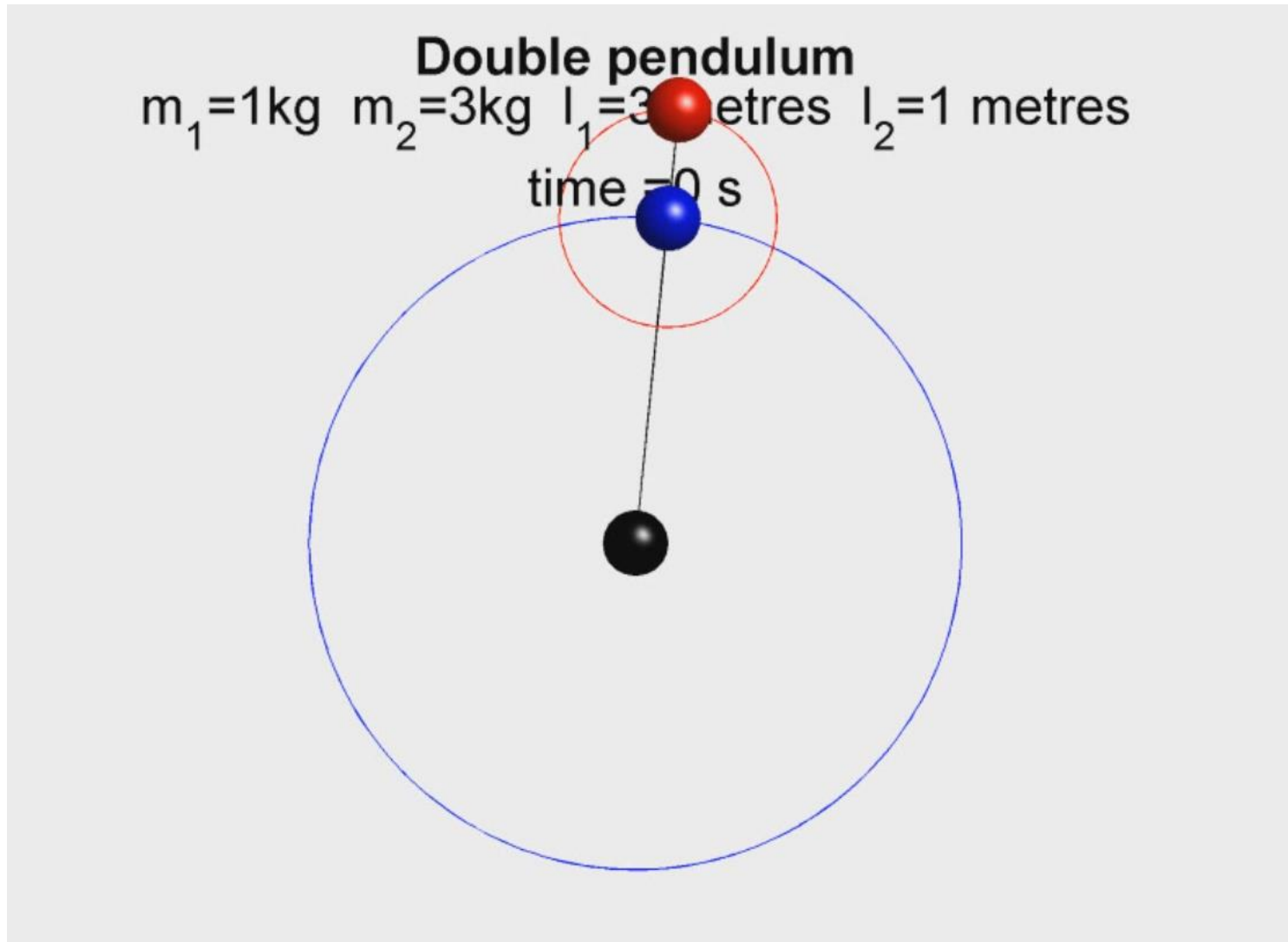
Total energies, per bob



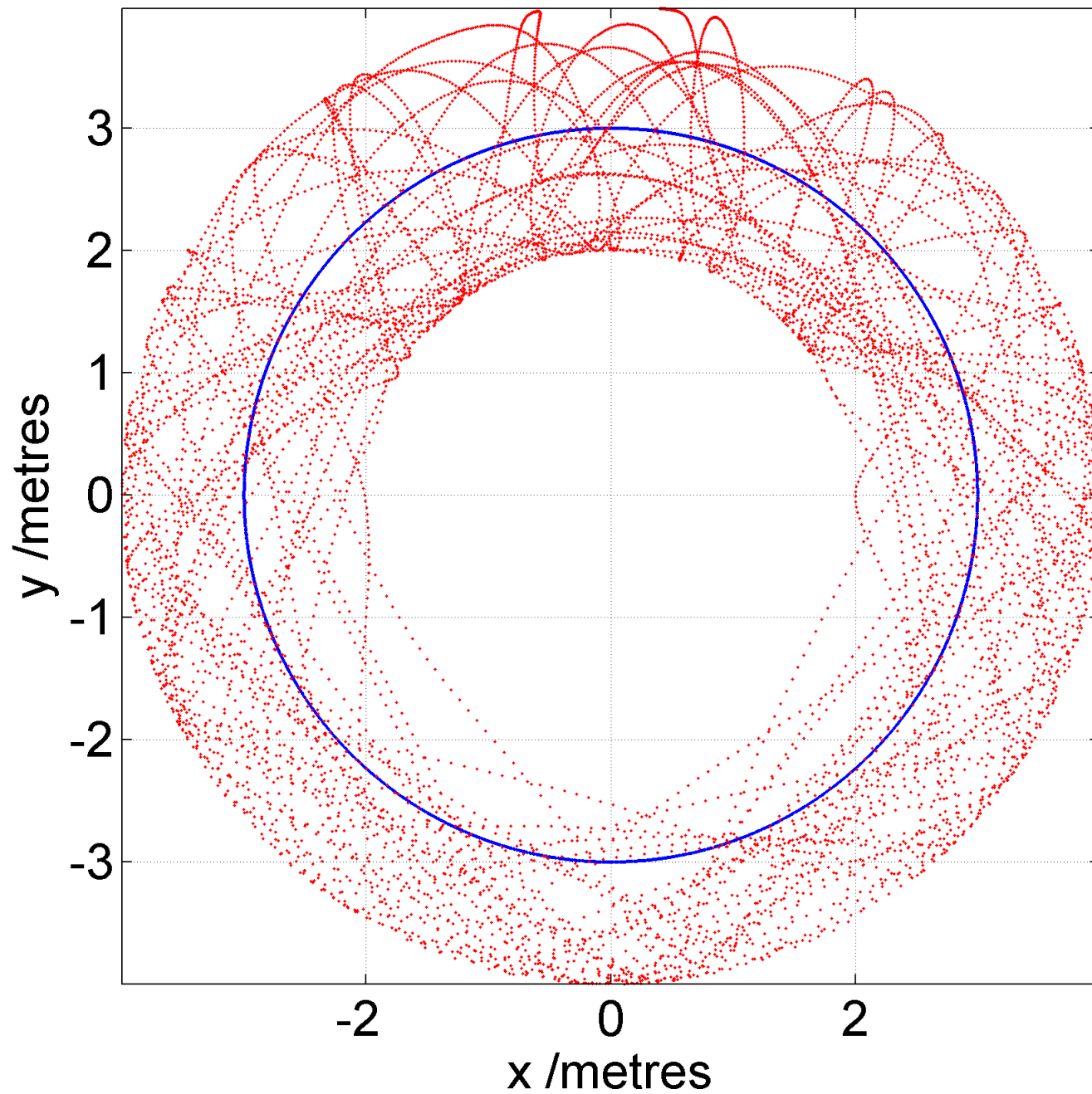
Total energy of system



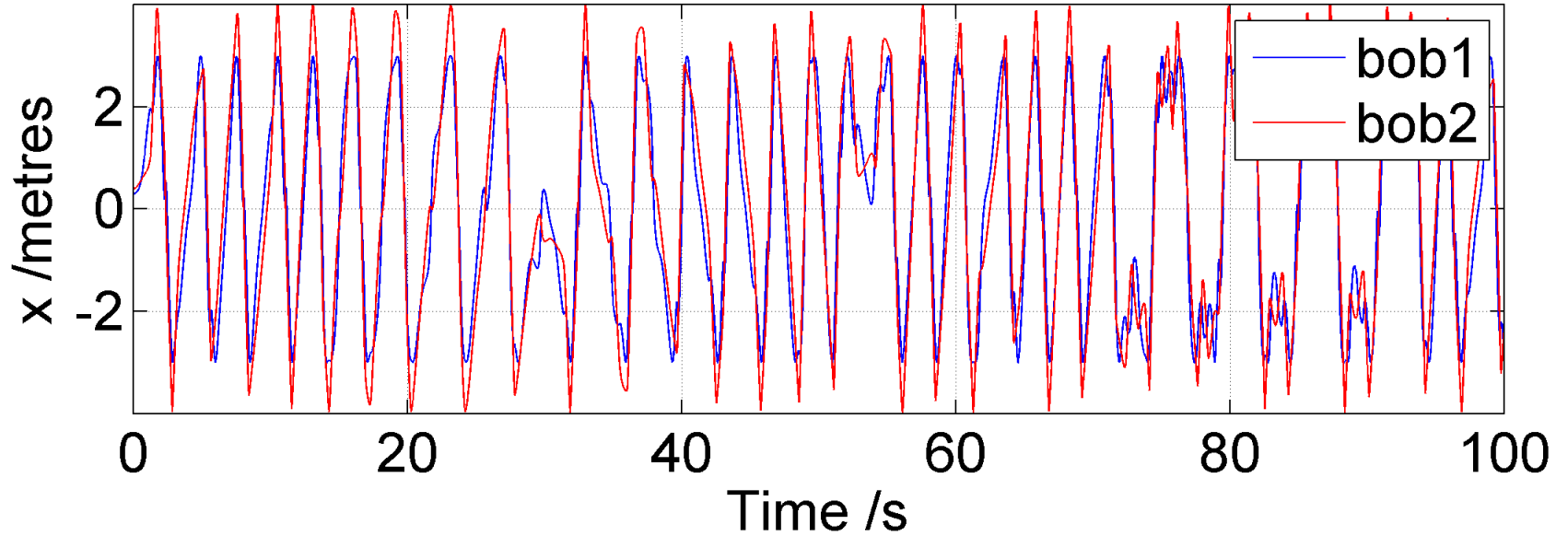
And now for **chaotic motion!**



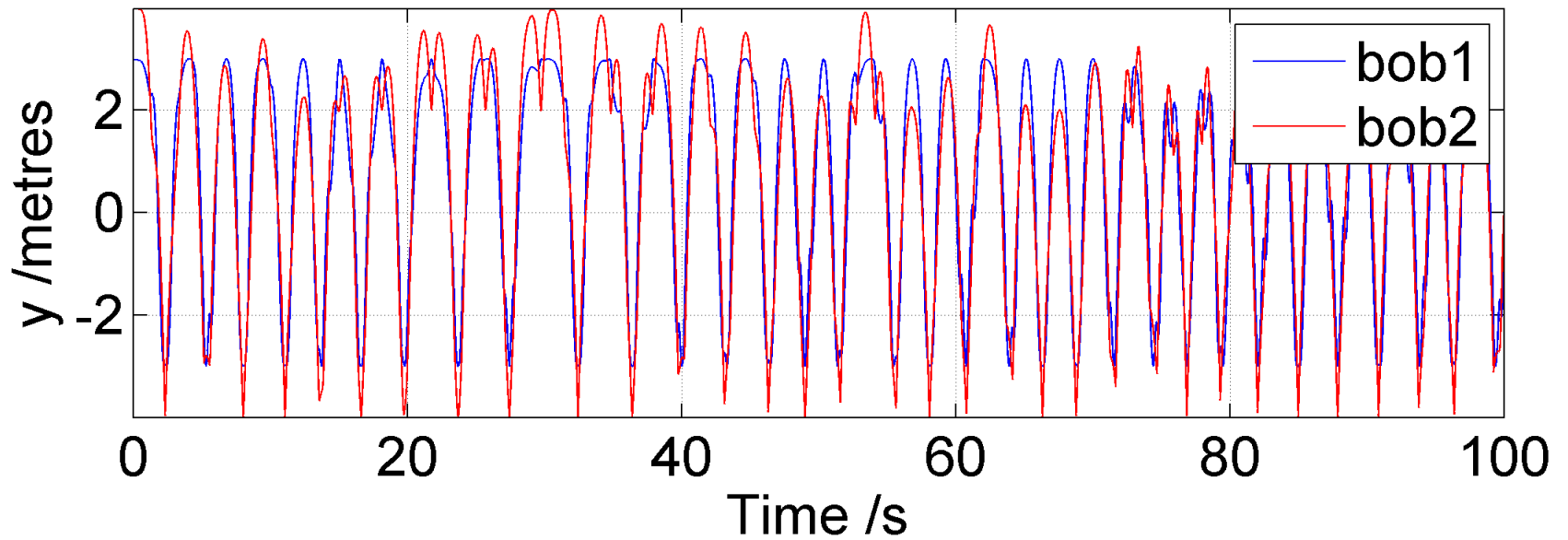
Pendulum bob x,y trajectories. Bob1 is blue, Bob2 is red



### Pendulum bob x positions

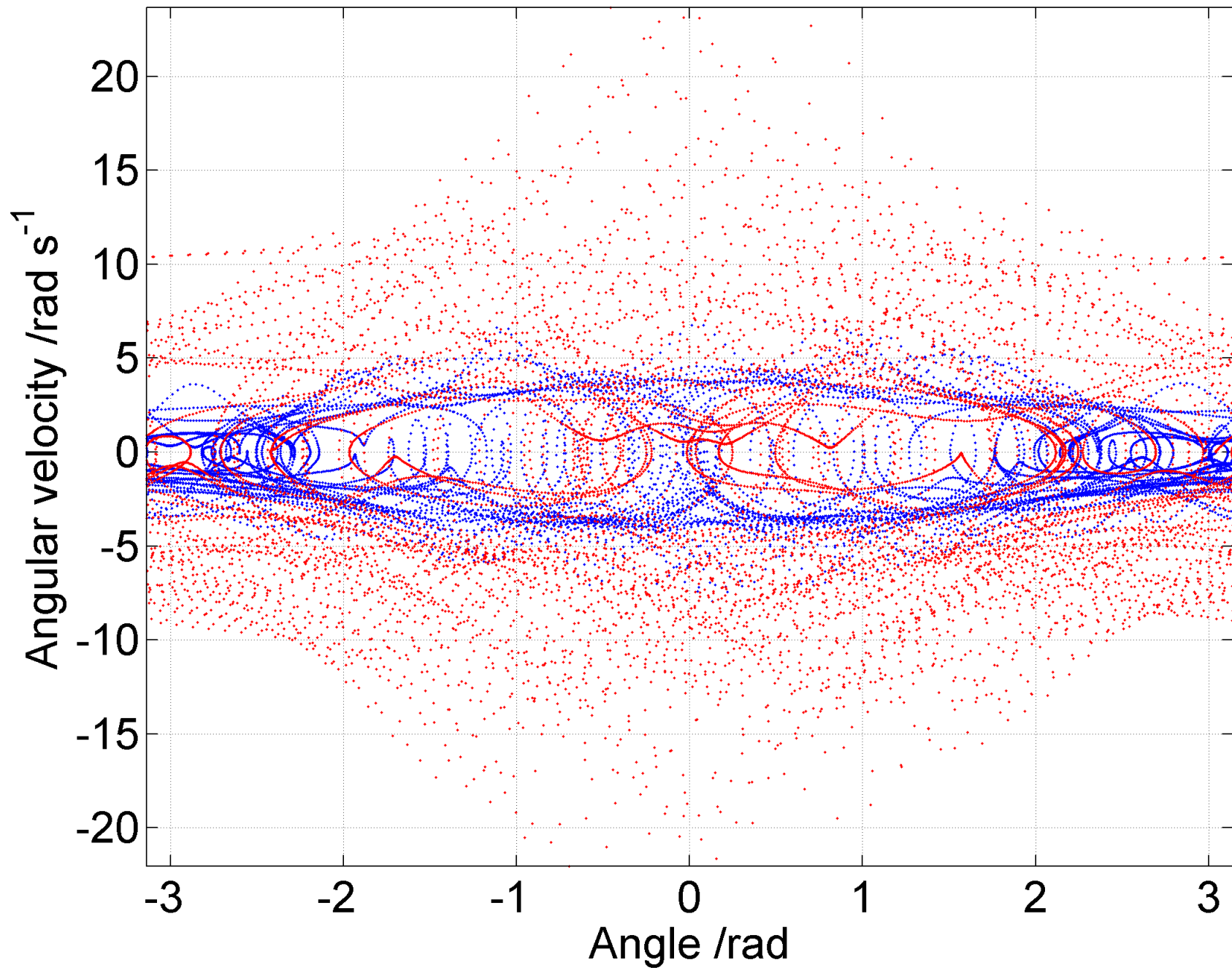


### Pendulum bob y positions

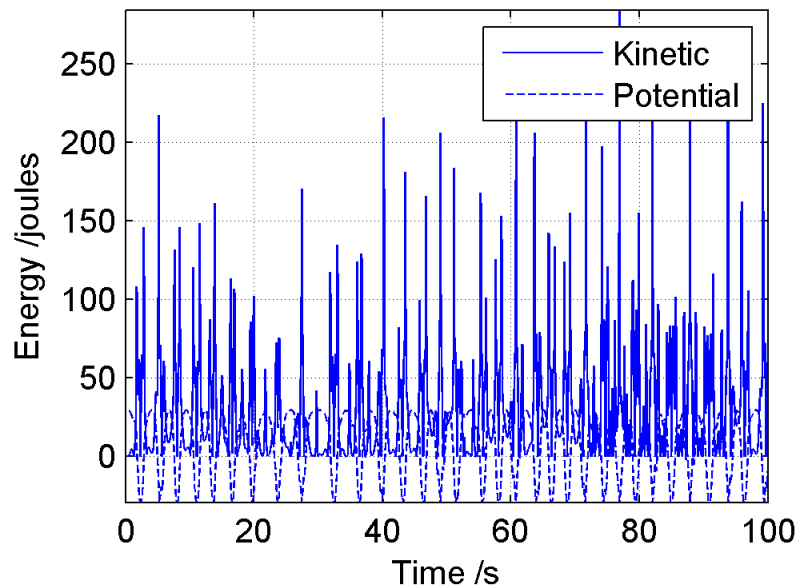




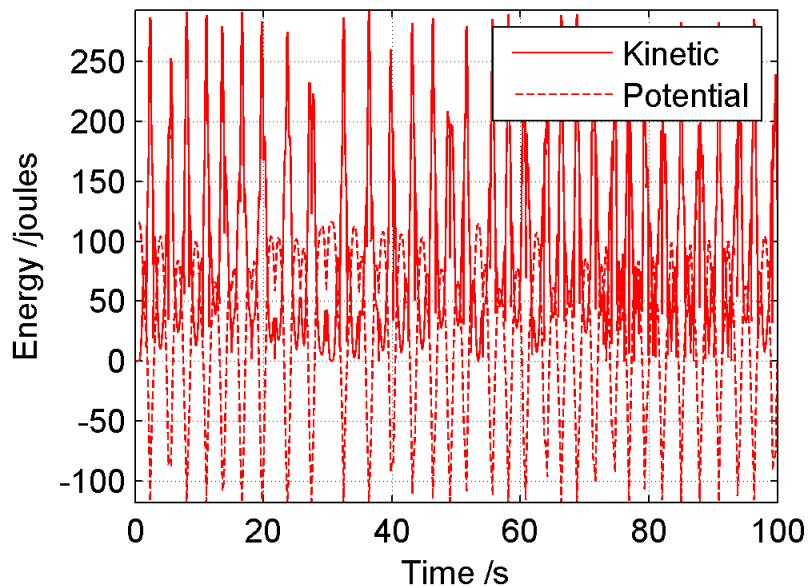
Poincare diagram: bob1 is blue, bob2 is red



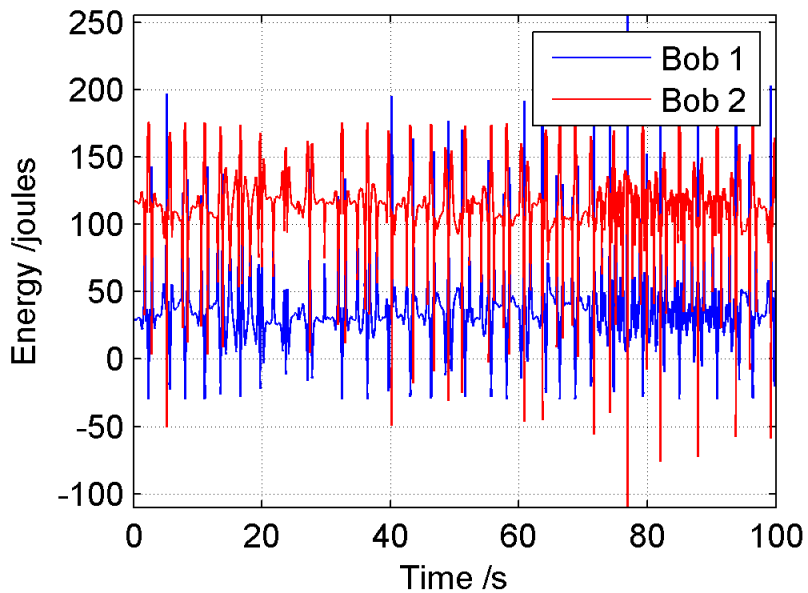
Pendulum bob 1 kinetic, potential energy



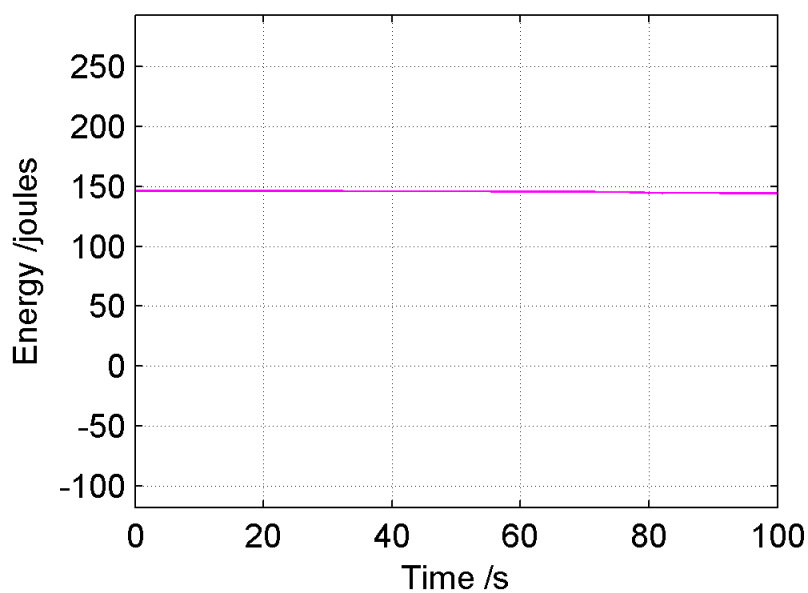
Pendulum bob 2 kinetic, potential energy



Total energies, per bob



Total energy of system



# Lorenz and Rössler strange attractors

Edward Lorenz was using a Royal McBee LGP-30 computer in 1961 to model weather patterns. He accidentally fed in 3 digit precision numbers into the model from a printout rather than the 6 digits used by the computer. These tiny errors created a hugely different weather forecast....

**Lorenz's weather model was very sensitive to initial conditions.**



His equations looked a bit like these:

$$\frac{dx}{dt} = s(y - x)$$

$$\frac{dy}{dt} = x(r - z) - y$$

$$\frac{dz}{dt} = xy - bz$$

$$s = 10$$

$$r = 28$$

$$b = \frac{8}{3}$$



Edward Lorenz  
1917-2008

Although  $x, y, z$  trajectories are chaotic, they tend to *gravitate towards a particular region*.

This region is called a **strange attractor**.

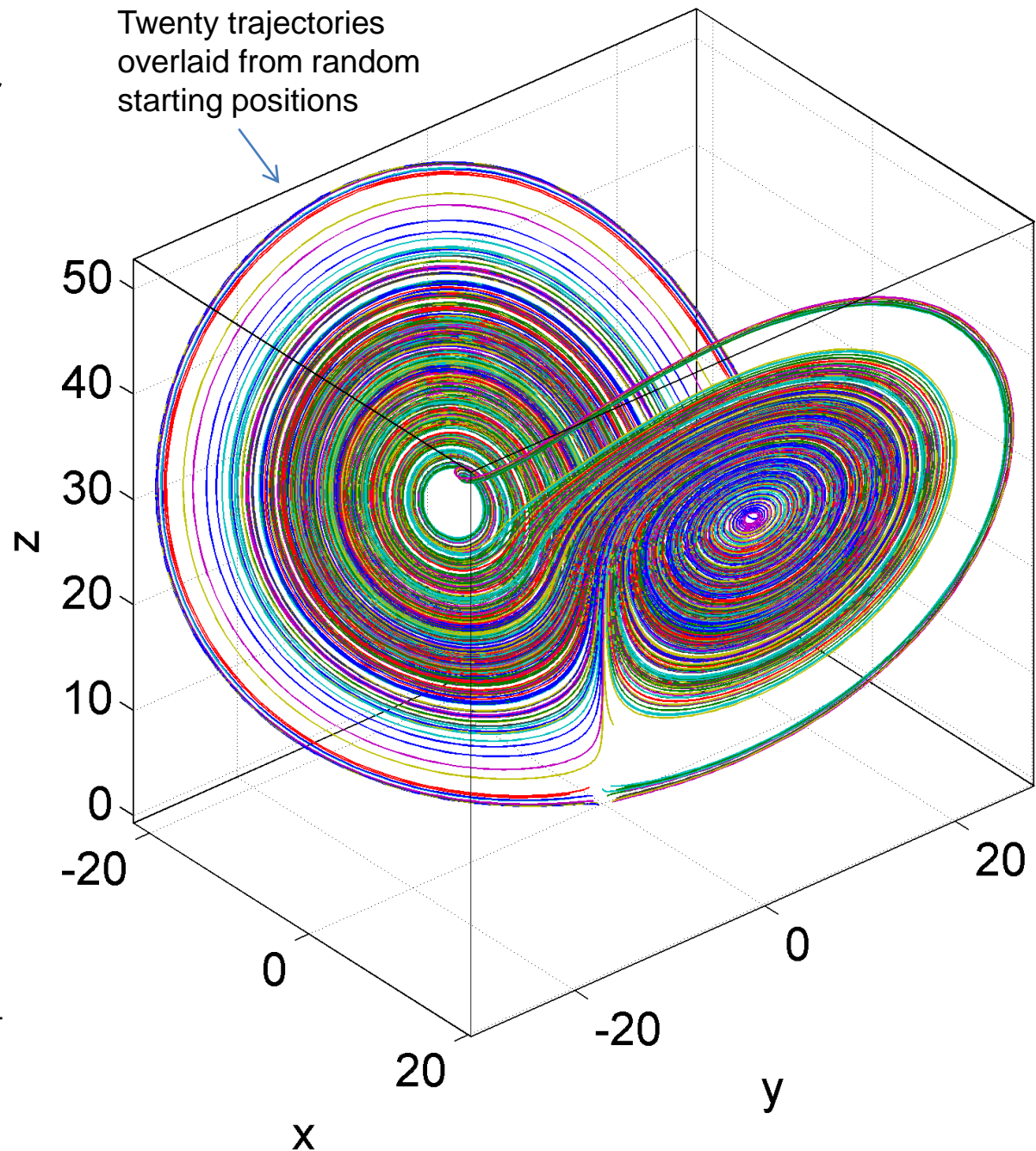
$$\frac{dx}{dt} = s(y - x)$$

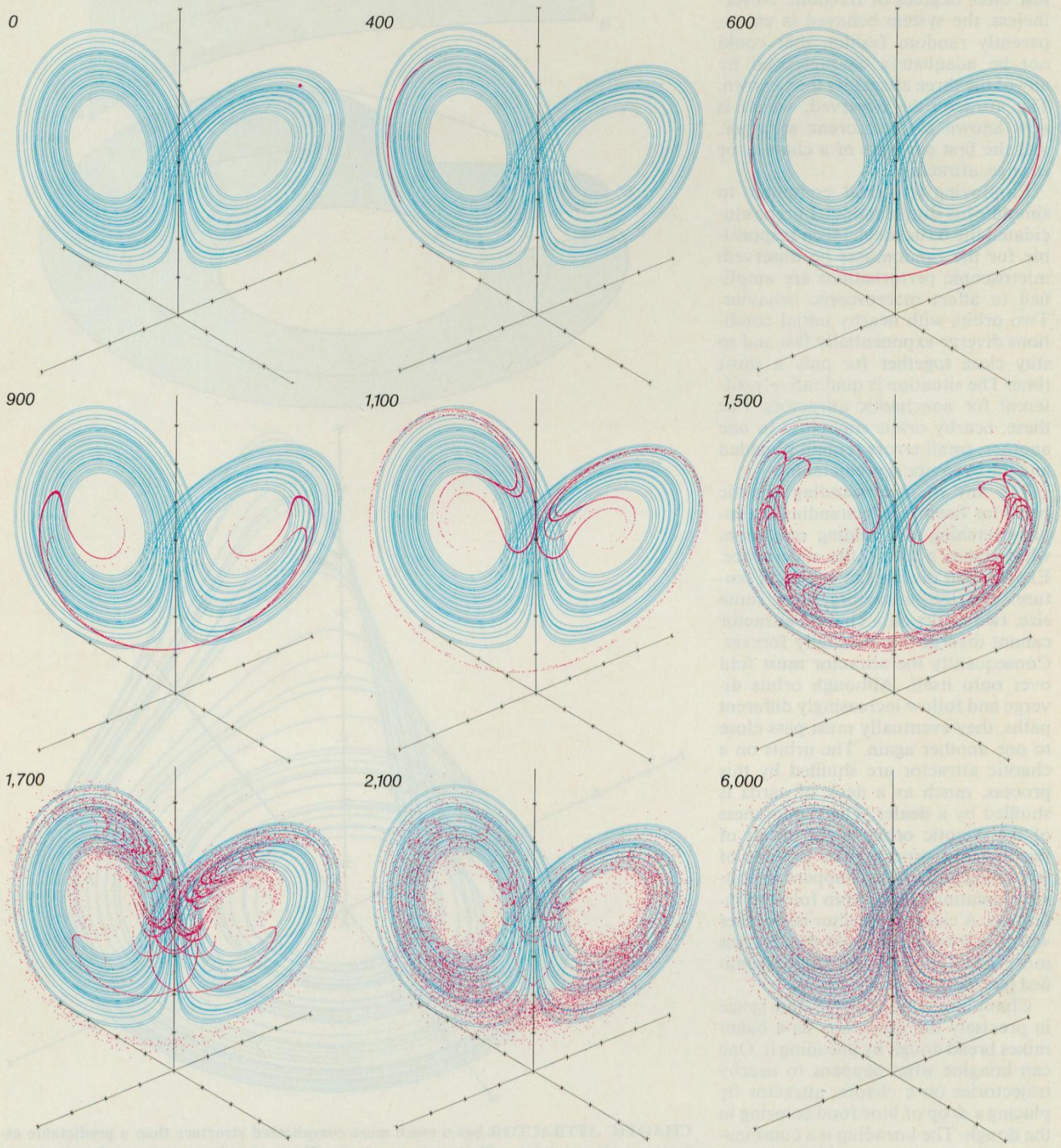
$$\frac{dy}{dt} = x(r - z) - y$$

$$\frac{dz}{dt} = xy - bz$$

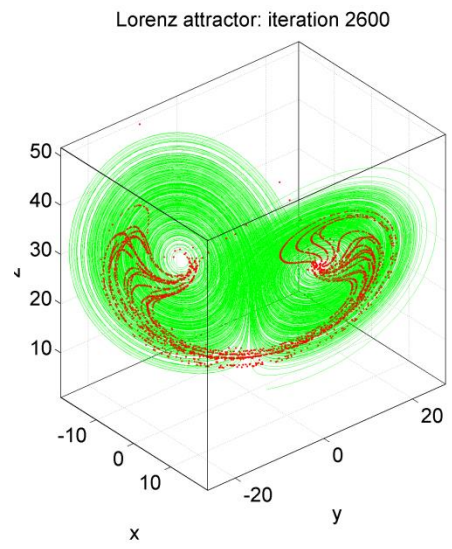
$$s = 10 \quad r = 28 \quad b = \frac{8}{3}$$

## Lorenz attractor





Applying the Lorenz equations, a cluster of initial  $x, y, z$  values separated by a *tiny* random deviation will eventually **spread out evenly throughout the strange attractor.**



Shaw *et al*; "Chaos",  
 Scientific American  
 54:12 (1986) 46-57

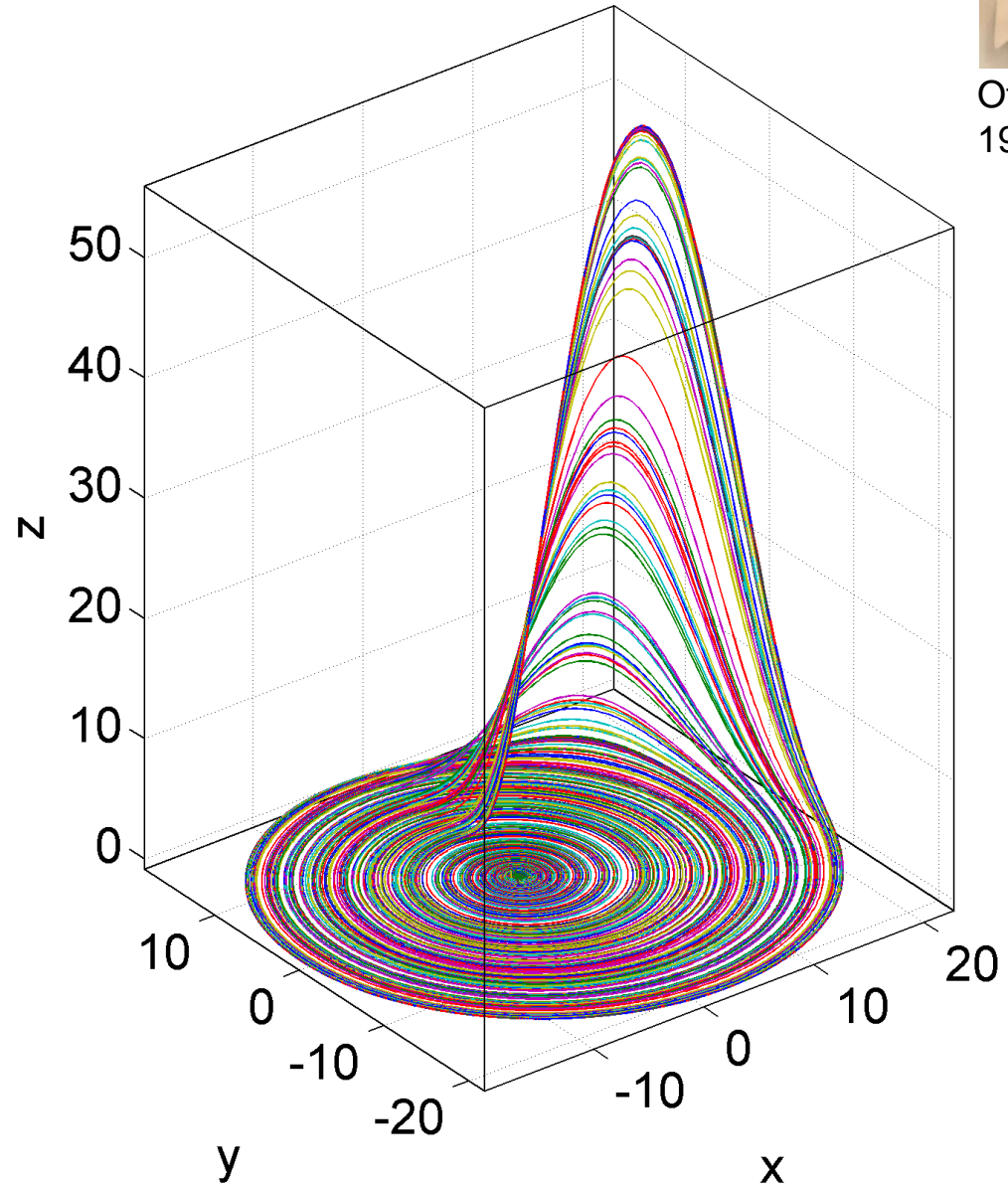
Another chaotic system with a **strange attractor** is the solution set of the **Rössler equations**

$$a = \frac{1}{10}$$

$$b = \frac{1}{10}$$

$$c = 14$$

Rossler attractor



Otto Rössler  
1940-

$$\frac{dx}{dt} = -y - z$$

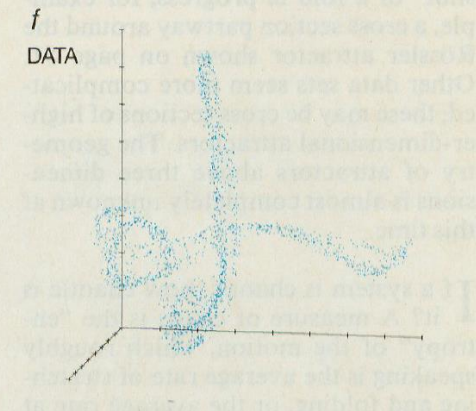
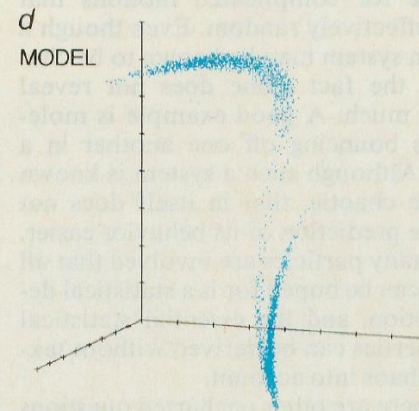
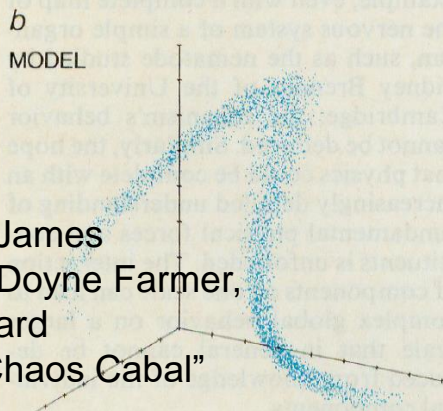
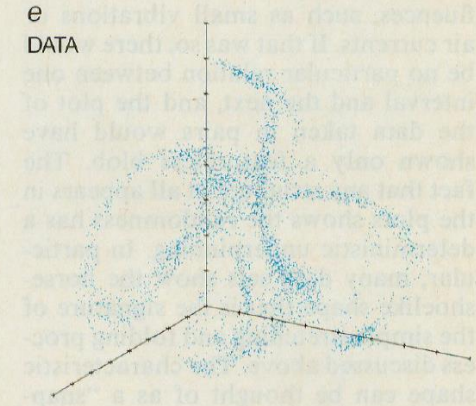
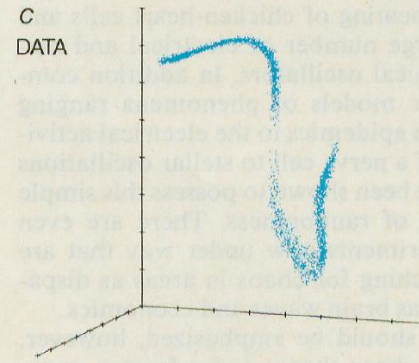
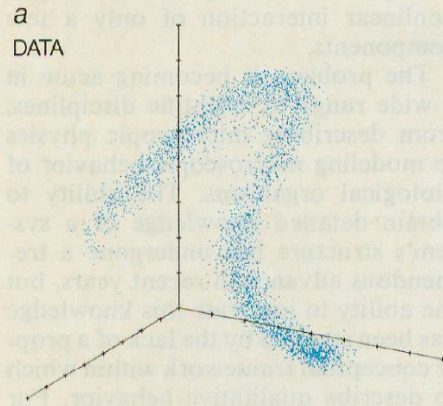
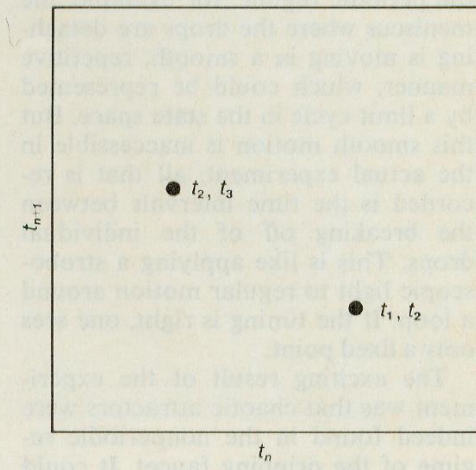
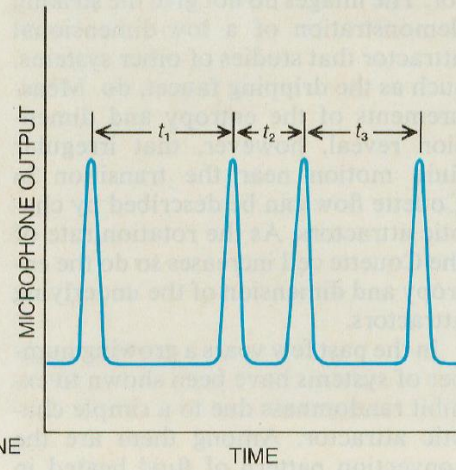
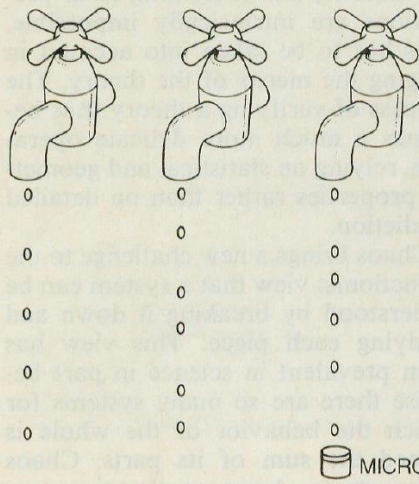
$$\frac{dy}{dt} = x + ay$$

$$\frac{dz}{dt} = z(x - c) + b$$

# Shaw's dripping faucet

Construct  $x, y, z$  coordinates from time differences between drips

Seemingly random drips form a strange attractor, whose shape depends on the flow rate



Robert Shaw James  
Crutchfield J. Doyne Farmer,  
Norman Packard  
"Santa Cruz Chaos Cabal"  
1970s-1980s

# Fractals

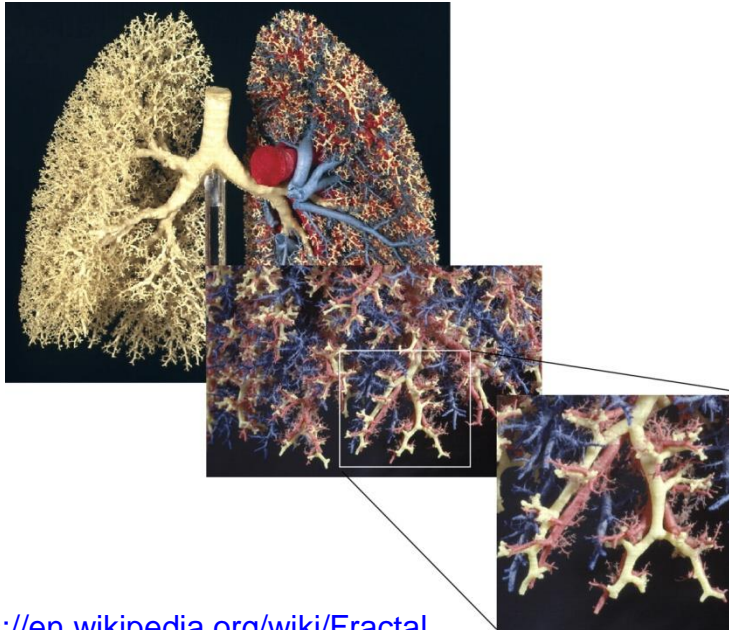
A *fractal* is a structure which is **geometrically similar over a wide range of scales**. In other words, zoom in and it looks the same.



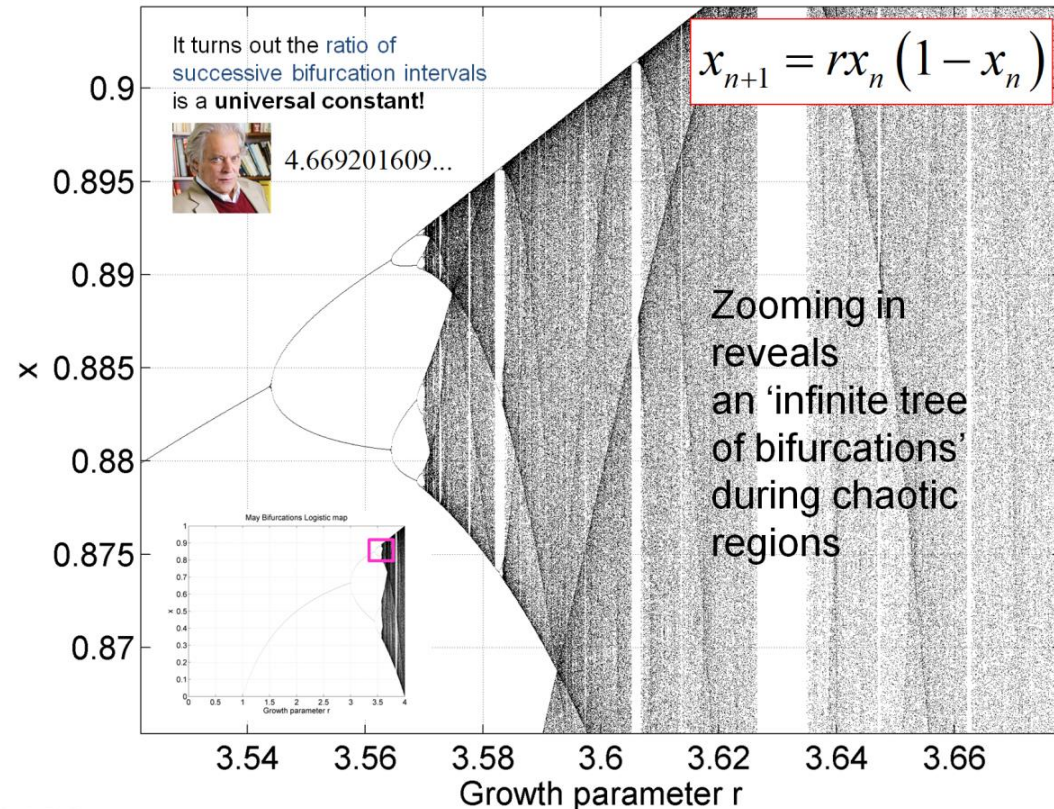
Fractals are *everywhere* in **natural forms**, from the branching structure of our lungs and trees, to the shape of coastlines, to river networks, to eddies in turbulent fluids ....

And it is also a feature of the bifurcation diagrams we have already met ....

<http://jap.physiology.org/content/110/4/1119>



May Bifurcations Logistic map



<https://en.wikipedia.org/wiki/Fractal>

<http://fractalfoundation.org/resources/what-are-fractals/>

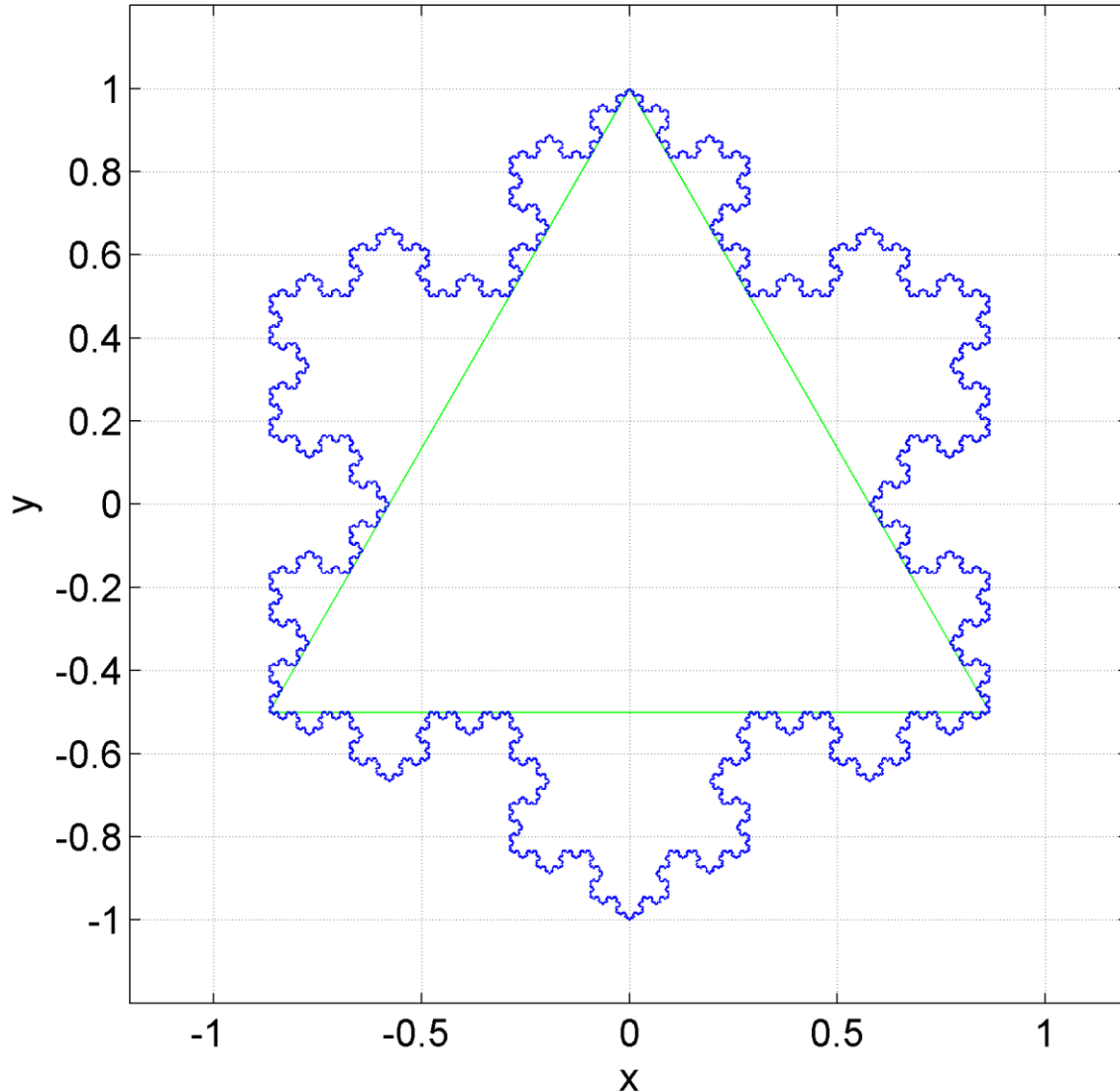


# The Koch Snowflake



Niels Fabian Helge von Koch  
(1870-1924)

Koch snowflake iteration = 6

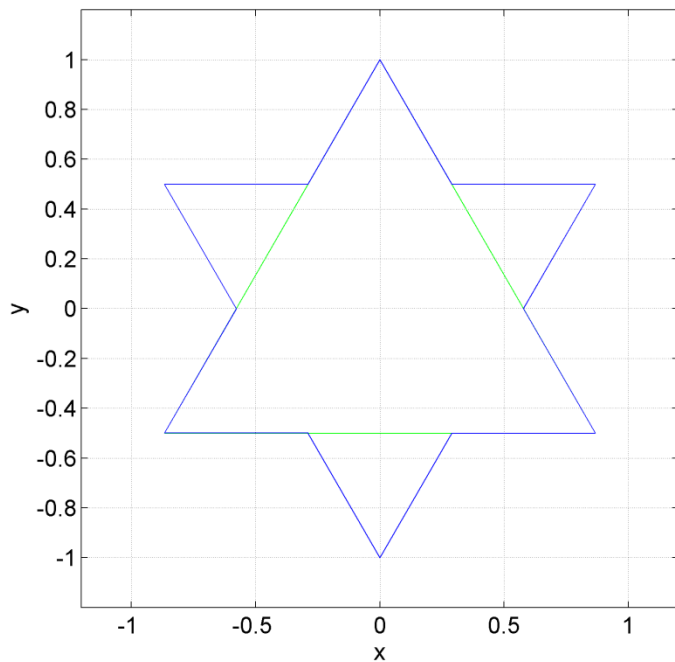


Perhaps the earliest example of *fractal geometry* – before I even coined the term!

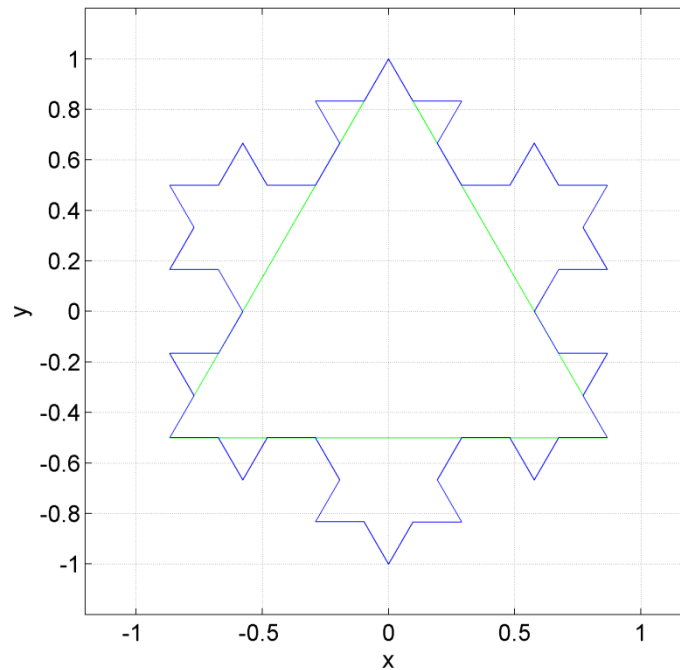


Area tends to  $\frac{8}{5}$  of the area of the green triangle....  
.... but the perimeter is *infinite!*

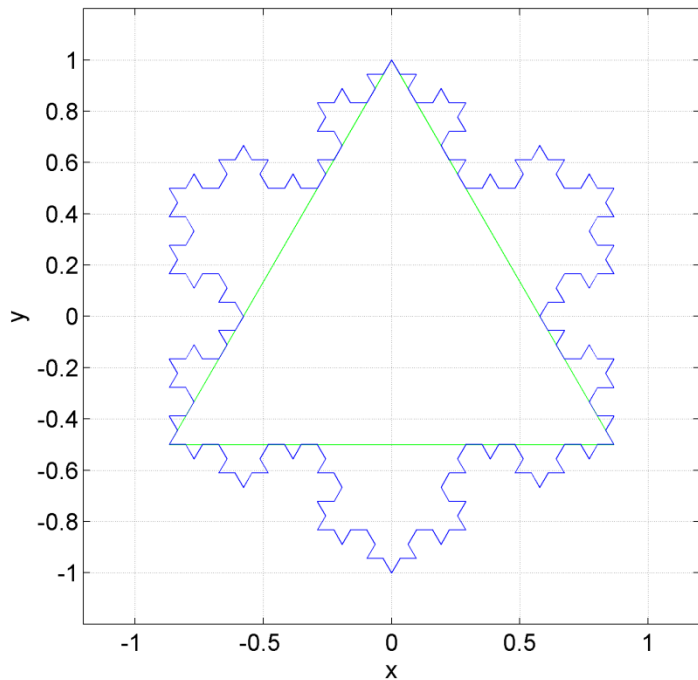
Koch snowflake iteration = 1



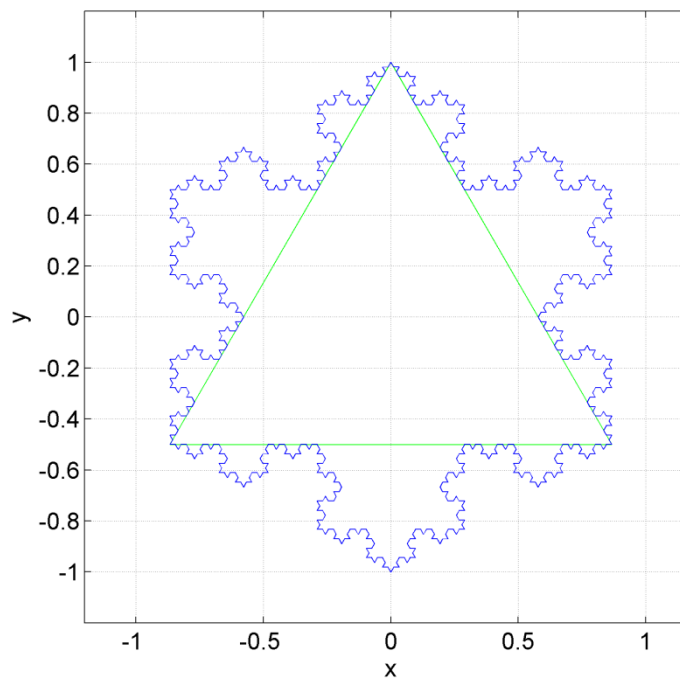
Koch snowflake iteration = 2



Koch snowflake iteration = 3



Koch snowflake iteration = 4



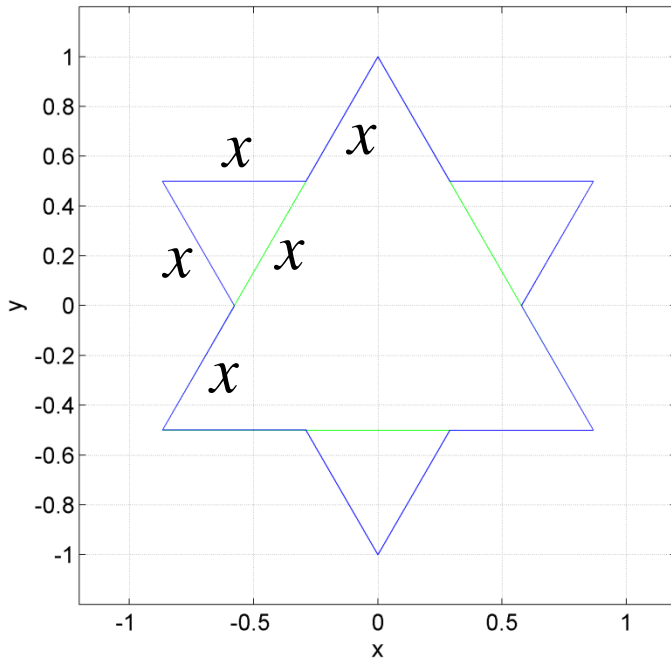
1. Start with an equilateral triangle

2. Divide each edge into thirds

3. Add another equilateral triangle to each edge with base being the central third.

*Iterate* from step 2 ...

Koch snowflake iteration = 1



**For each iteration:**

Every side length grows from

$3x \rightarrow 4x$  i.e. a factor of  $4/3$

Hence perimeter after  $n$  iterations is:

$$P_n = P_0 \left( \frac{4}{3} \right)^n$$

where  $P_0$  is the perimeter of the original triangle.

i.e. as  $n$  becomes large,  $P$  tends to infinity!

Each triangle of edge  $3x$  gains another triangle of edge size  $x$ . i.e. **gains a triangle of  $1/9$  the area of previous triangles added**

Each iteration the number of sides increases by a factor of 4, so number of sides after  $n$  iterations is  $3 \times 4^n$

→ This gives the number of extra triangles in iteration  $n+1$

Hence area added in iteration  $k$  is:

$$\Delta A_k = 3 \times 4^{k-1} \times \frac{A_0}{9^k}$$

Original triangle area is  $A_0$

Total area enclosed by Koch Snowflake is therefore:

$$\Delta A_k = 3 \times 4^{k-1} \times \frac{A_0}{9^k}$$

$$A_n = A_0 + \sum_{k=1}^n \Delta A_k = A_0 + 3 \times 4^{1-1} \times \frac{A_0}{9^1} + 3 \times 4^{2-1} \times \frac{A_0}{9^2} + 3 \times 4^{3-1} \times \frac{A_0}{9^3} + \dots$$

$$\frac{A_n}{A_0} = 1 + \frac{3}{4} \left( \frac{4}{9} + \frac{4^2}{9^2} + \frac{4^3}{9^3} + \dots + \frac{4^n}{9^n} \right)$$

$$\frac{A_n}{A_0} = 1 + \frac{3}{4} \frac{4}{9} \left( 1 + \frac{4}{9} + \frac{4^2}{9^2} + \dots + \frac{4^{n-1}}{9^{n-1}} \right)$$

Geometric progression

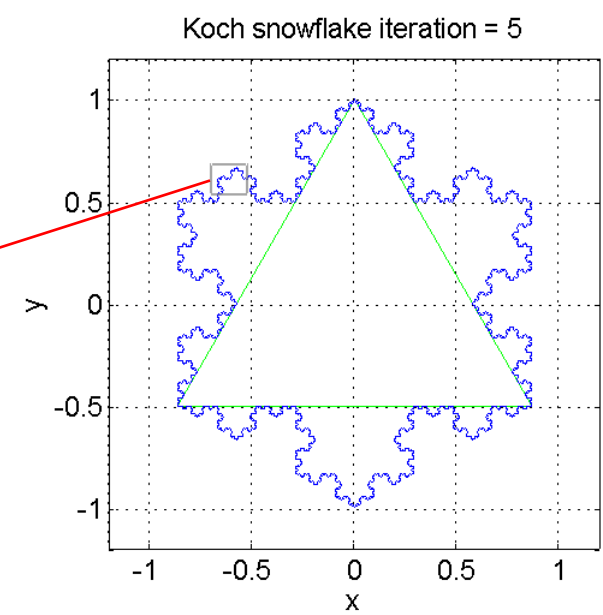
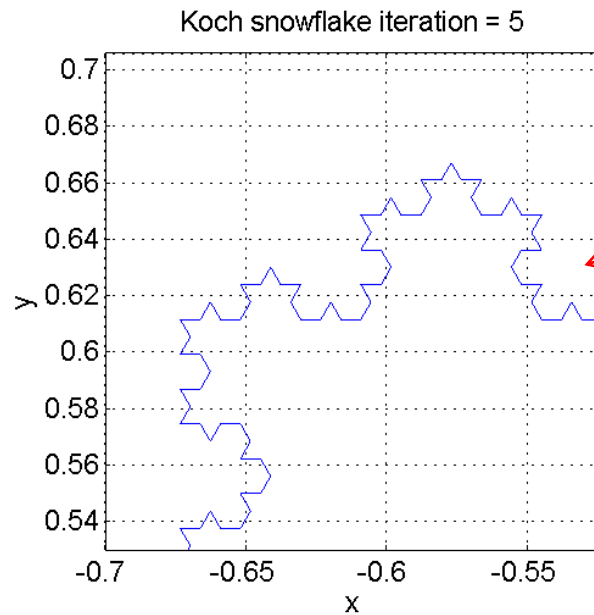
$$a + ar + ar^2 + \dots + ar^{n-1} = a \frac{1-r^n}{1-r}$$

$$\frac{A_n}{A_0} = 1 + \frac{1}{3} \frac{1 - \frac{4^n}{9^n}}{1 - \frac{4}{9}} = 1 + \frac{1}{3} \frac{9}{5} \left( 1 - \frac{4^n}{9^n} \right) = \frac{5 + 3 \left( 1 - \frac{4^n}{9^n} \right)}{5}$$

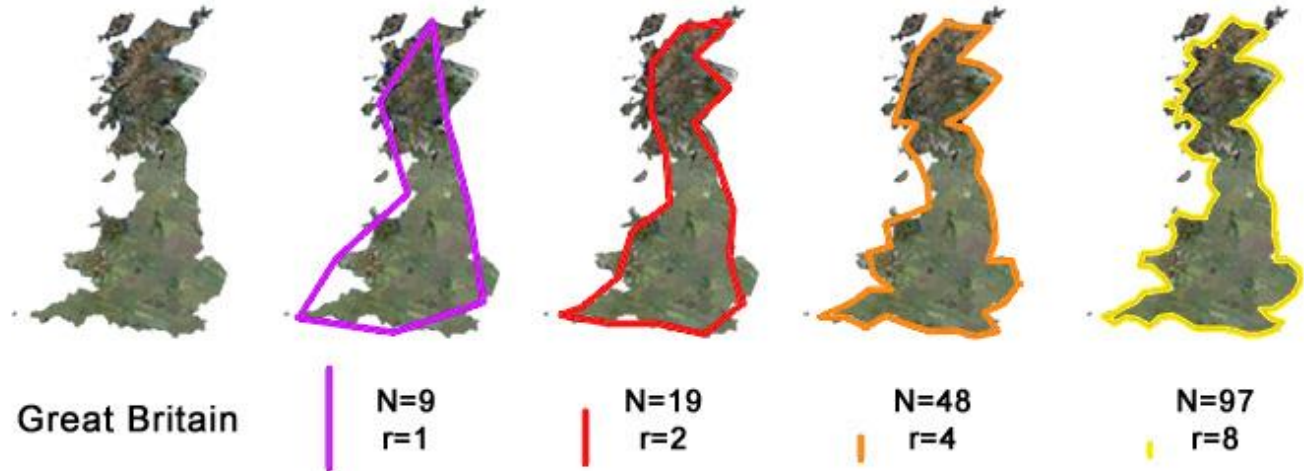
So as  $n$  becomes infinite:

$$\lim_{n \rightarrow \infty} \frac{A_n}{A_0} = \lim_{n \rightarrow \infty} \left\{ \frac{5 + 3 \left( 1 - \frac{4^n}{9^n} \right)}{5} \right\} = \frac{8}{5}$$

In the limit when  $n$  tends to infinity, the Koch Snowflake is **self similar**, i.e. has the same structure at all magnification scales.



The Koch Snowflake has a **fractal** structure. A bit like the coastline of the UK. It's perimeter depends on the *lengths of our measuring sticks* which map out greater (but similarly shaped) detail as we zoom in



Although the perimeter *is* infinite, we can calculate the number of fixed length ‘sticks’ which make up the perimeter. Let stick size  $x$  for iteration  $n$  be the perimeter divided by the number of sides

$$x_n = P_n / N_n = \frac{P_0 \left(\frac{4}{3}\right)^n}{3 \times 4^n} = \boxed{\frac{1}{3} P_0 \times 3^{-n}}$$

Define the **Fractal Dimension**  $D$  such that the **number of sticks can be defined in terms of the stick size:**

$$N_n = 3 \times \left(\frac{1}{3^n}\right)^{-D}$$

$$\therefore 3 \times \left(\frac{1}{3^n}\right)^{-D} = 3 \times 4^n$$

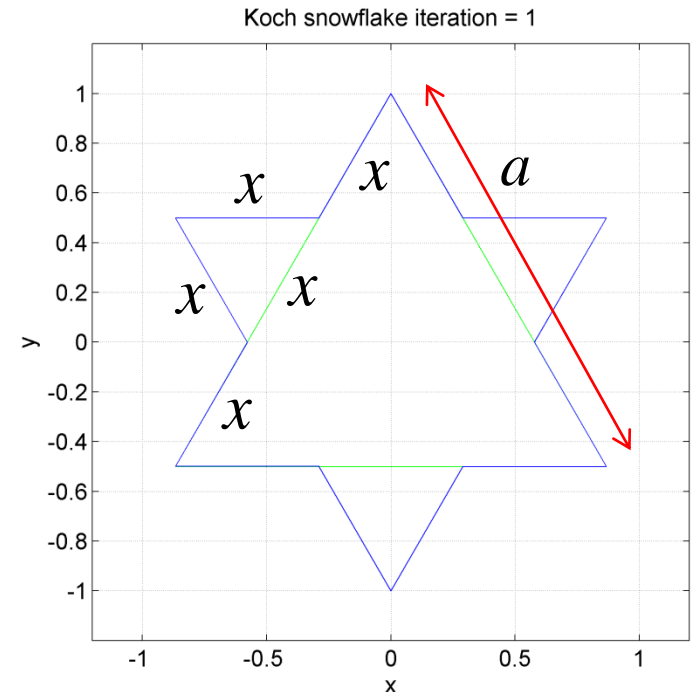
$$\left(3^{-n}\right)^{-D} = 4^n$$

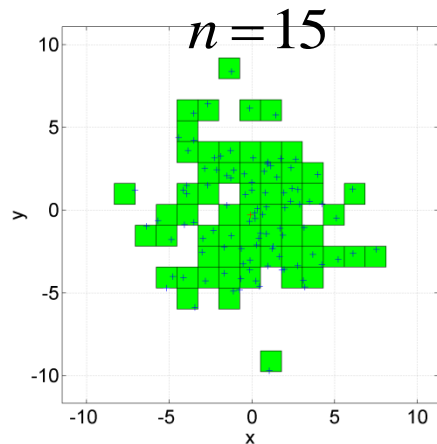
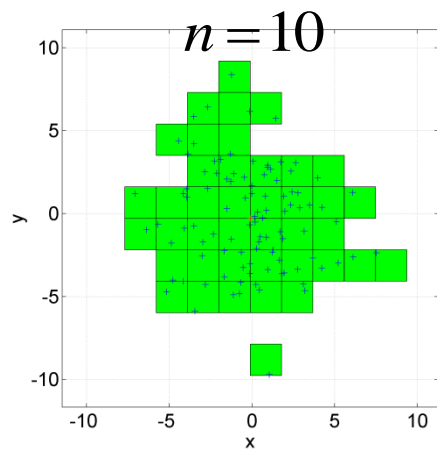
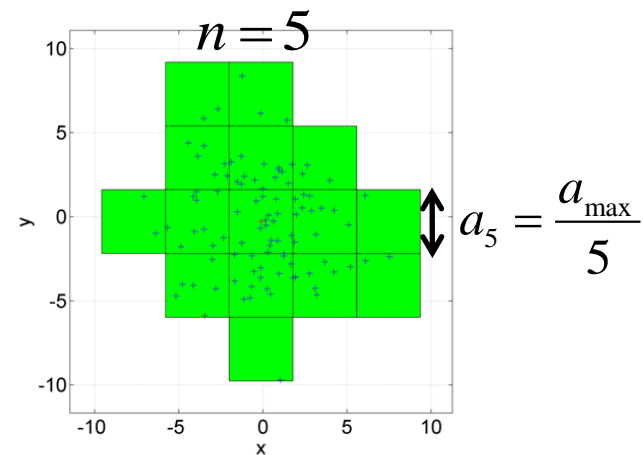
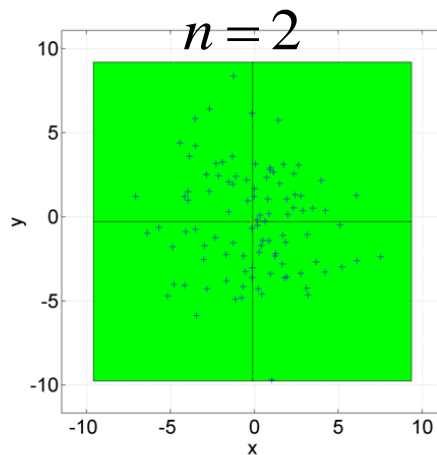
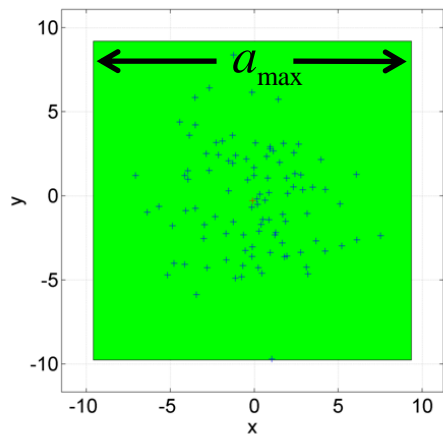
$$3^{nD} = 4^n$$

$$\therefore Dn \log 3 = n \log 4$$

$$\boxed{D = \frac{\log 4}{\log 3} \approx 1.2619}$$

The Koch curve has a ‘fractional dimension’ of about 1.2619

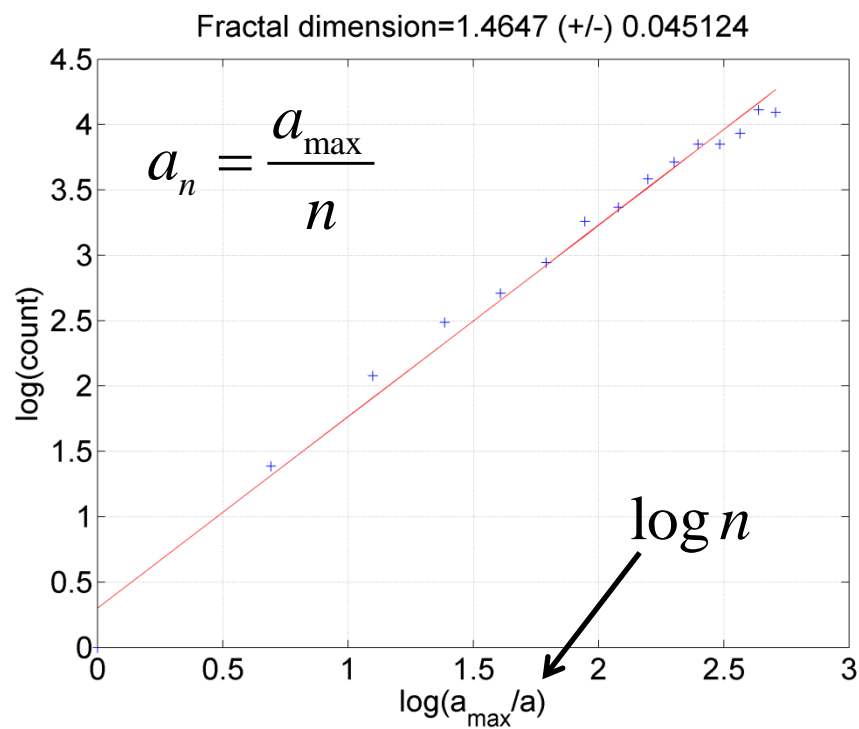




## Fractal dimension box counting method

This is better for areas or volumes

Count the green squares that contain the points  $\longrightarrow$



# Barnsley fern

Intriguingly, fractal structures like the Koch curve can be generated using an **iterated random process**. This is called the *'Chaos Game'*



```
function fern
```

```
%Define number of iterations  
N = 1e5;
```

```
%Pixel size  
psize = 0.1;
```

```
%Start x,y coordinates  
x =0;  
y = 0;  
xx = 0;  
yy = 0;
```

```
%Generate Barnsley fractal  
for n=1:N
```

```
    r = rand;  
    if r<=0.02  
        %Stem  
        xxyy = [0,0;0,0.16]*[xx;yy];  
        xx = xxyy(1); yy = xxyy(2);  
        x = [x,xx];|  
        y = [y,yy];
```

```
    elseif (r>0.01) && (r<=0.85)  
        %Smaller leaflets  
        xxyy = [0.85,0.04;-0.04,0.85]*[xx;yy] + [0;1.60] ;  
        xx = xxyy(1); yy = xxyy(2);  
        x = [x,xx];  
        y = [y,yy];
```

```
    elseif (r>0.85) && (r<=0.92)  
        %Largest left-hand leaflet  
        xxyy = [0.20,-0.26;0.23,0.22]*[xx;yy] + [0;1.60] ;  
        xx = xxyy(1); yy = xxyy(2);  
        x = [x,xx];  
        y = [y,yy];
```

```
    else  
        %Largest right hand leaflet  
        xxyy = [-0.15,0.28;0.26,0.24]*[xx;yy] + [0;0.44] ;  
        xx = xxyy(1); yy = xxyy(2);  
        x = [x,xx];  
        y = [y,yy];
```

```
    end  
end
```

```
%Plot fractal  
figure('color',[1 1 1],'name','Barnsley fern','renderer','opengl');  
plot(x,y,'g.','markersize',psize);  
axis equal  
axis off
```

```
%End of code
```

```
print(gcf,'barnsley fern.png','-dpng','-r300');
```

The **Barnsley Fern** is a fractal named after the British mathematician **Michael Barnsley** who first described it in his book *Fractals Everywhere*. He made it to resemble the Black Spleenwort, [Asplenium adiantum-nigrum](https://en.wikipedia.org/wiki/Asplenium_adiantum-nigrum).

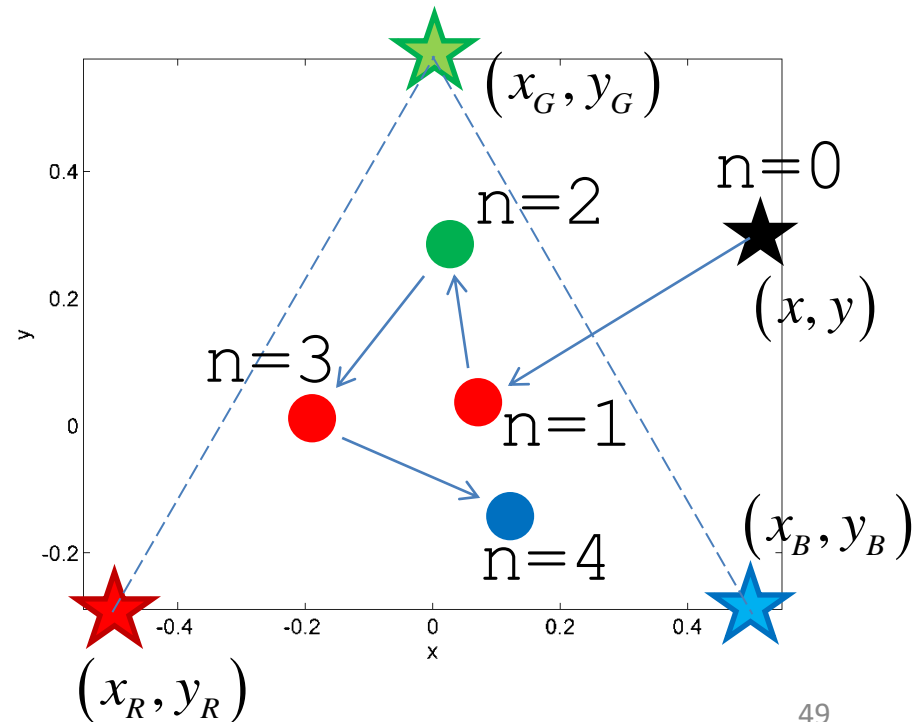


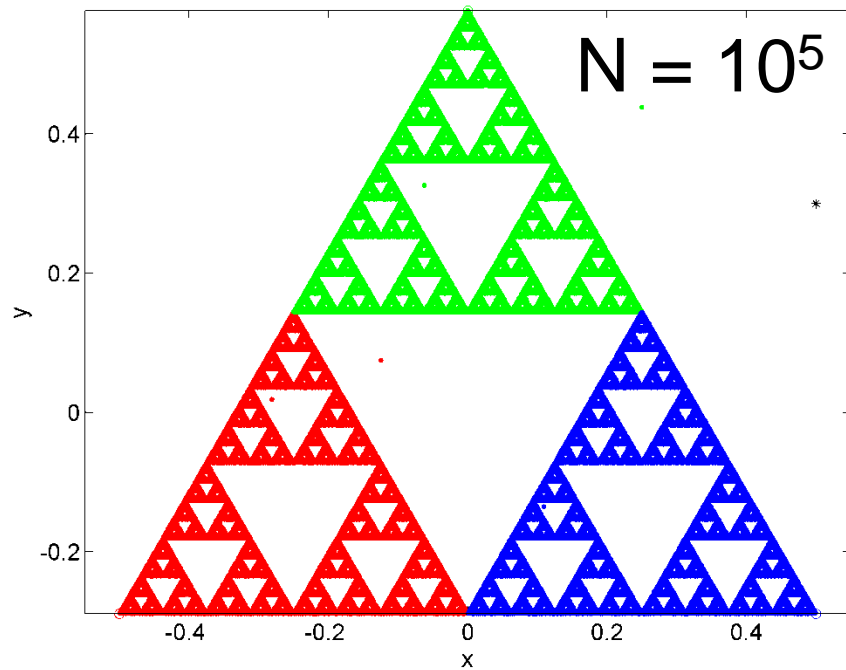
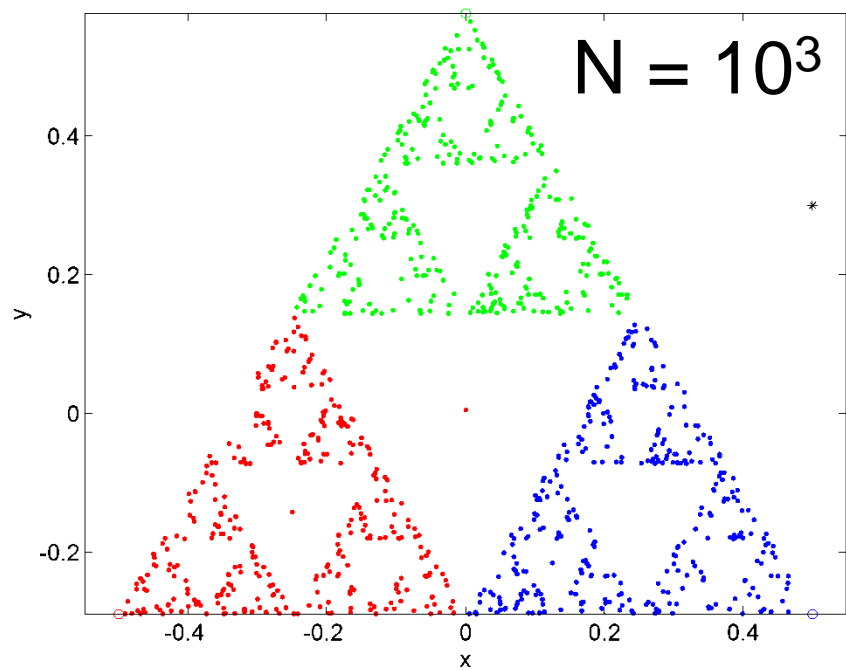
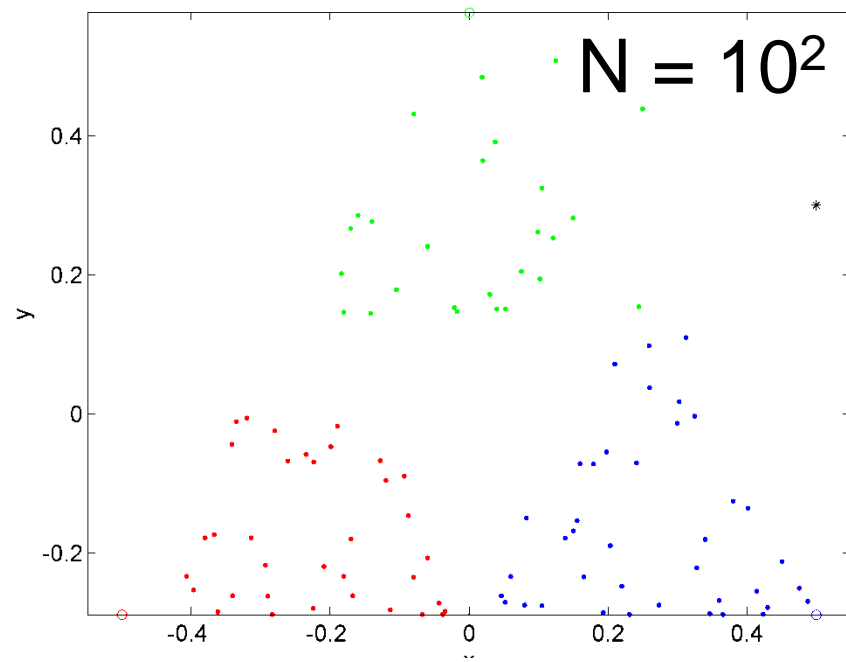
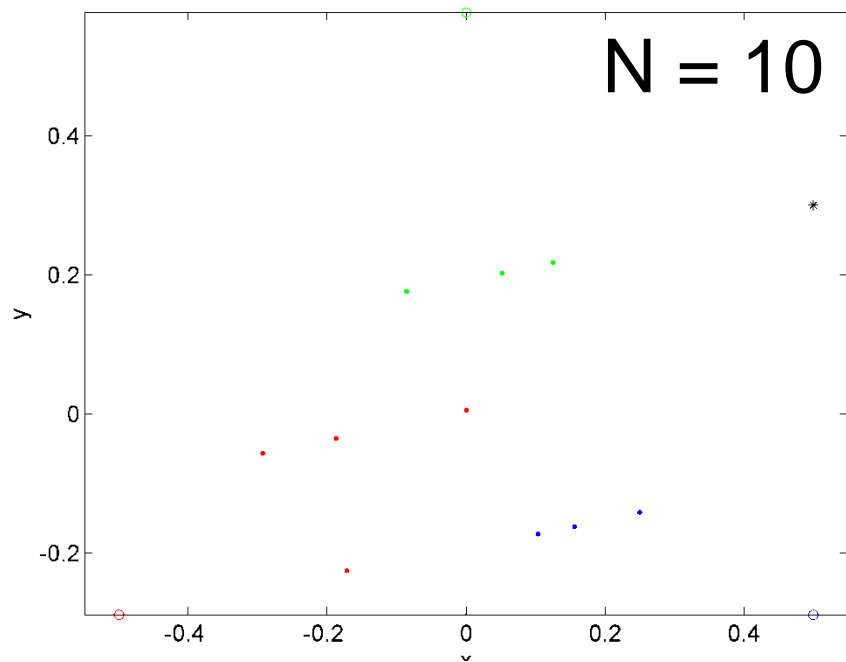
```

for n=1:N
    r = rand; %Generate a random number
    if ( r <= 1/3 )
        %Move half way towards red star
        x = 0.5*( xR + x );
        y = 0.5*( yR + y );
        %Plot a red dot
        plot( x,y, 'r.' );
    elseif ( r > 1/3 ) && ( r <=2/3 )
        %Move ... blue star
        x = 0.5*( xB + x );
        y = 0.5*( yB + y );
        %Plot a blue dot
        plot( x,y, 'b.' );
    else
        %Move ... green star
        x = 0.5*( xG + x );
        y = 0.5*( yG + y );
        %Plot a green dot
        plot( x,y, 'g.' );
    end
end
end

```

# The Sierpinski Triangle

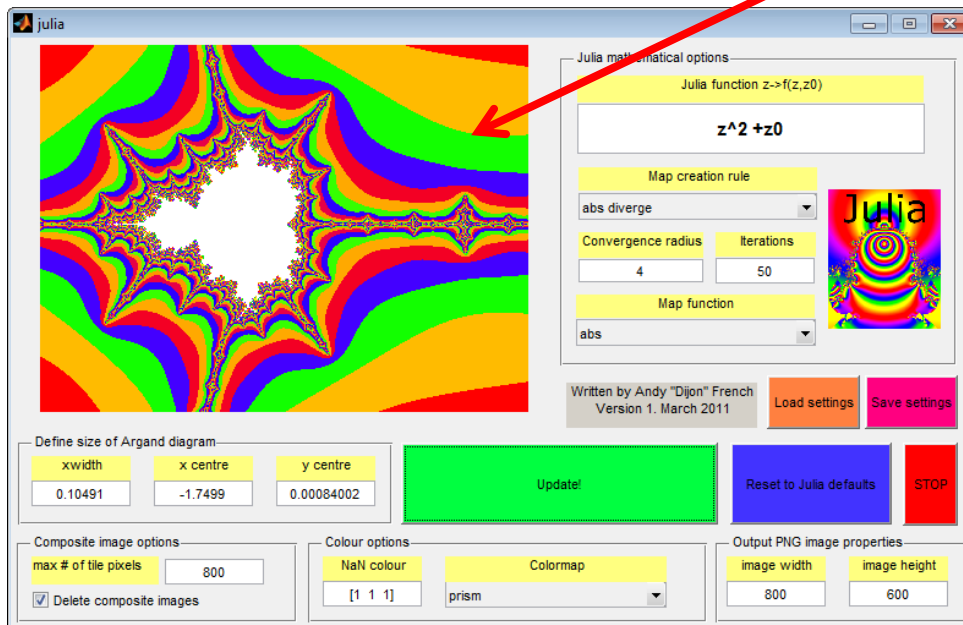
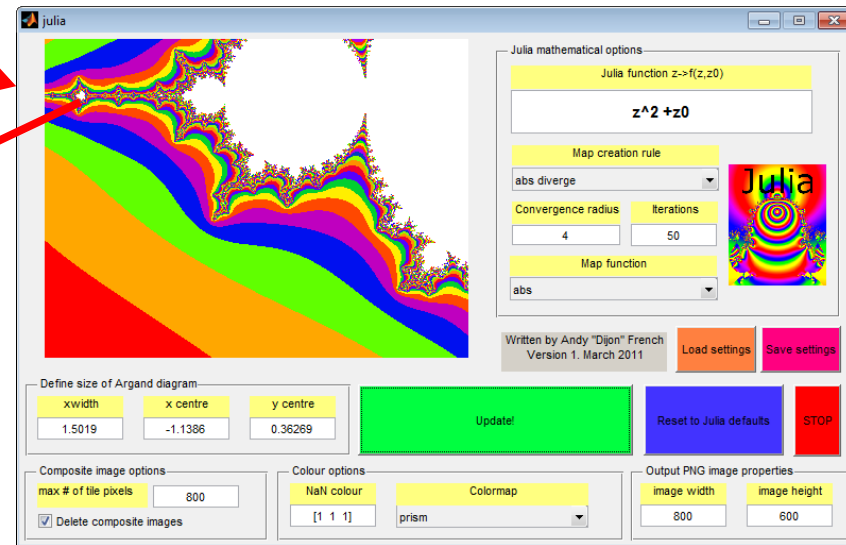
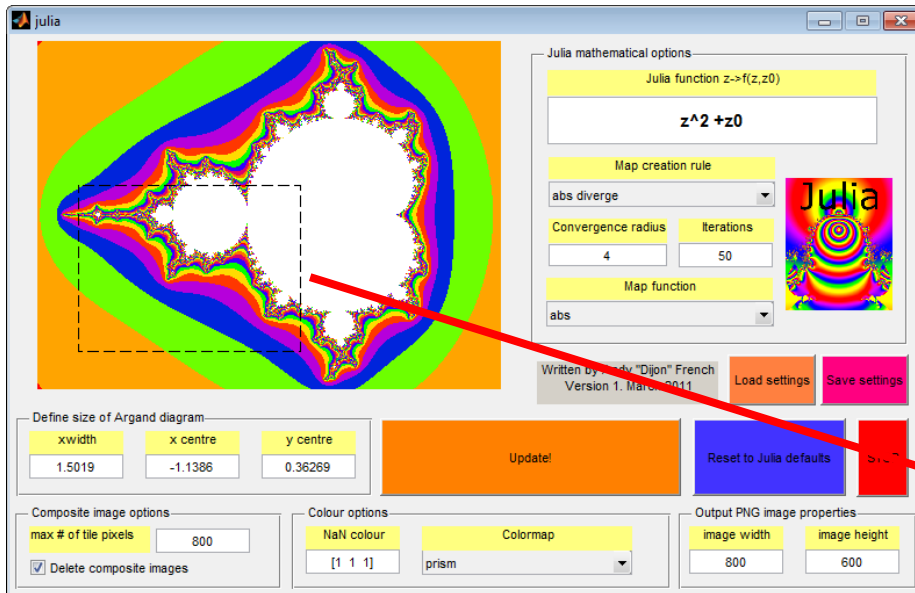




# Mandelbrot, complex numbers and iteration

The *Mandelbrot Set* has infinite complexity!

... But a recursive *fractal geometry*



Benoit Mandelbrot (1924-2010)



# Mandlebrot transformations of **complex numbers**

$$i^2 = -1$$

$$z = x + iy$$

$$x = \operatorname{Re}(z)$$

$$y = \operatorname{Im}(z)$$

$$|z| = \sqrt{x^2 + y^2}$$

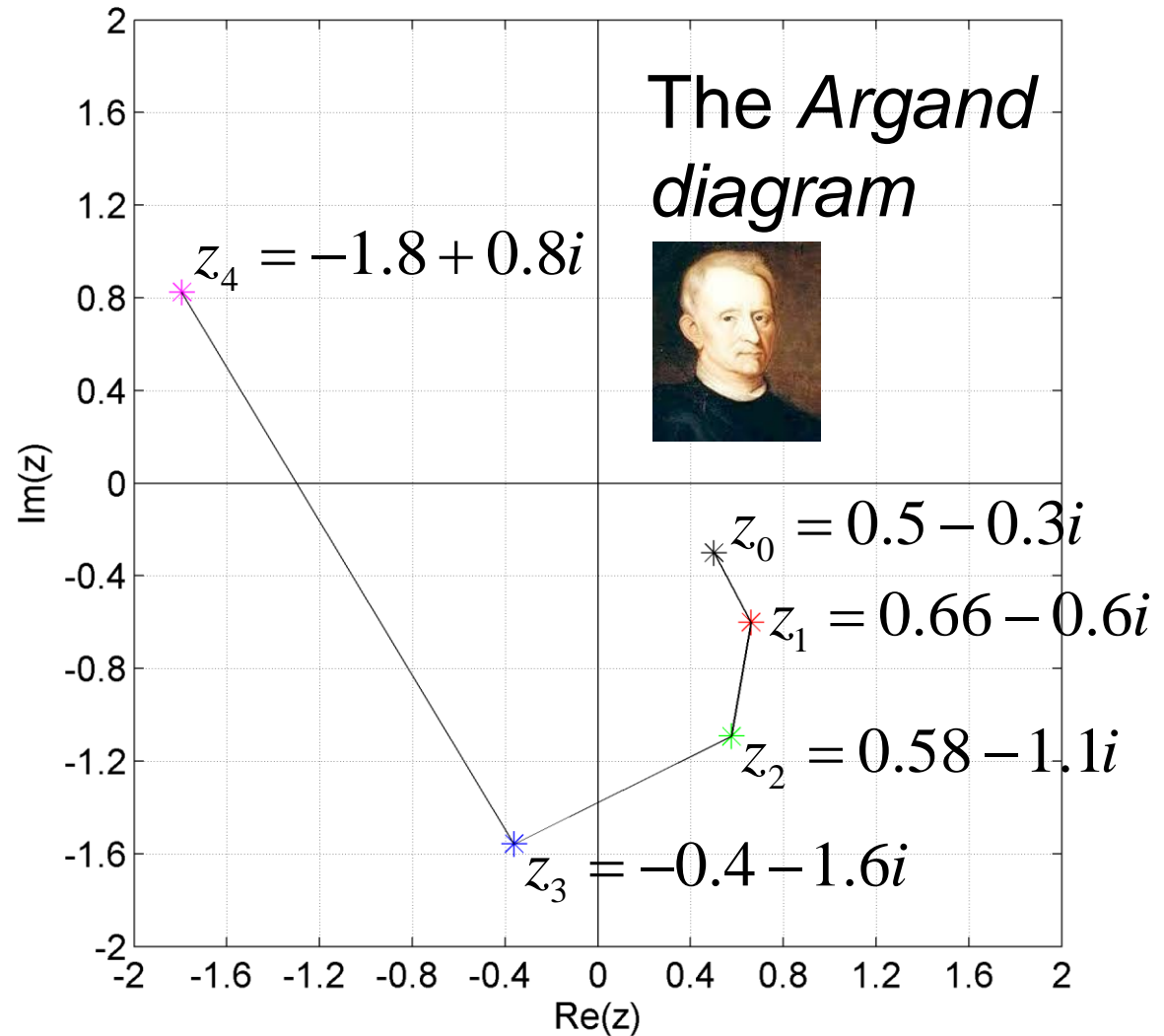
$$(1 + i)(1 + i)$$

$$= 1 + 2i + i^2$$

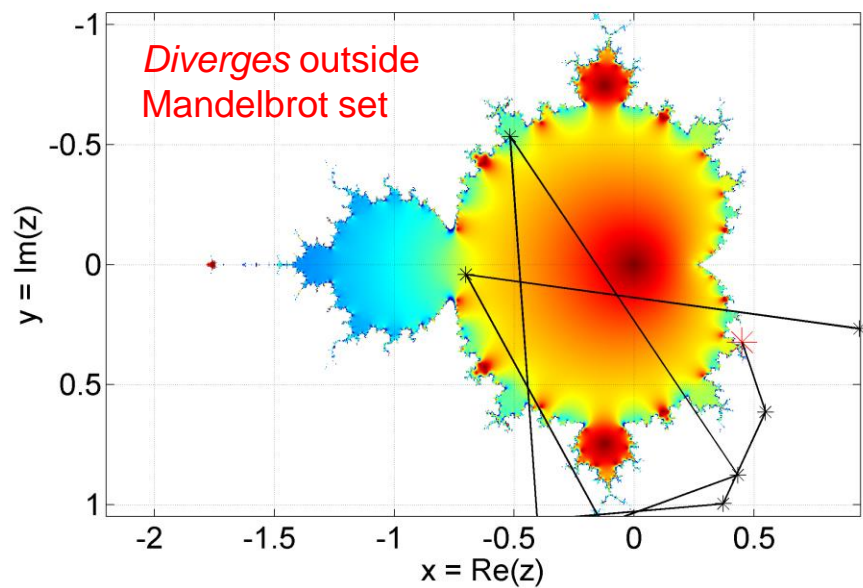
$$= 1 + 2i - 1$$

$$= 2i$$

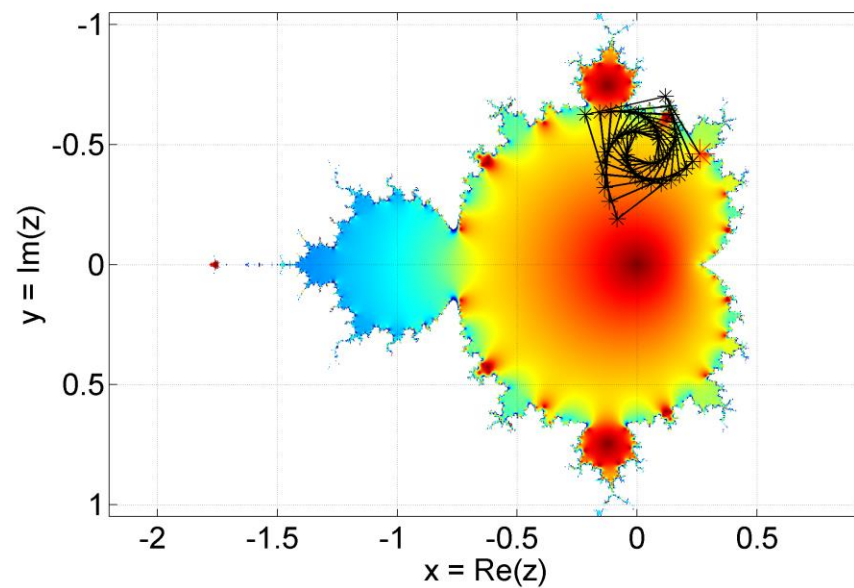
$$z_{n+1} = z_n^2 + z_0$$



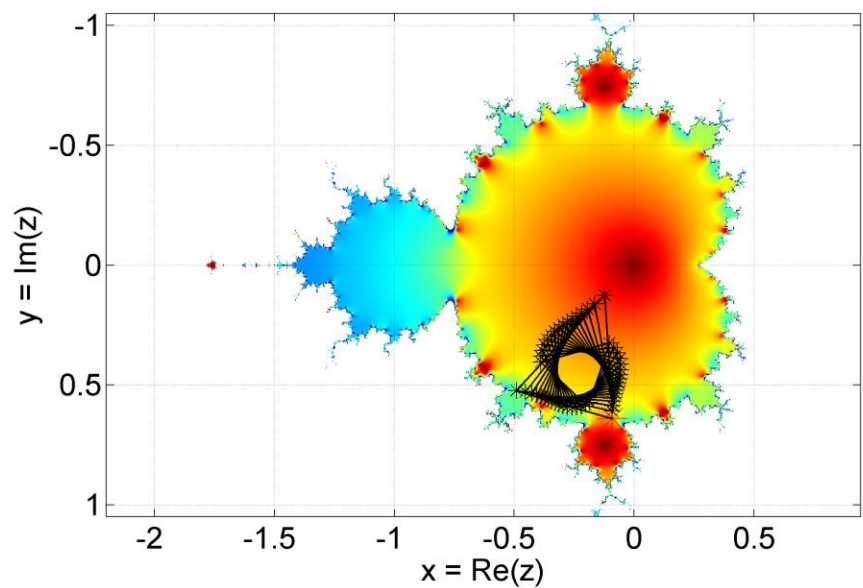
Mandelbrot  $z_{n+1} = z_n^2 + z_0$



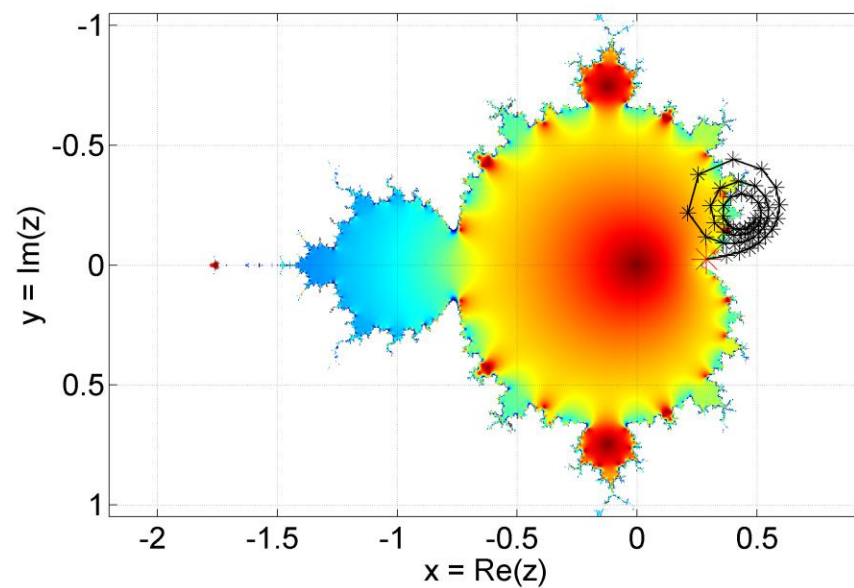
Mandelbrot  $z_{n+1} = z_n^2 + z_0$



Mandelbrot  $z_{n+1} = z_n^2 + z_0$



Mandelbrot  $z_{n+1} = z_n^2 + z_0$



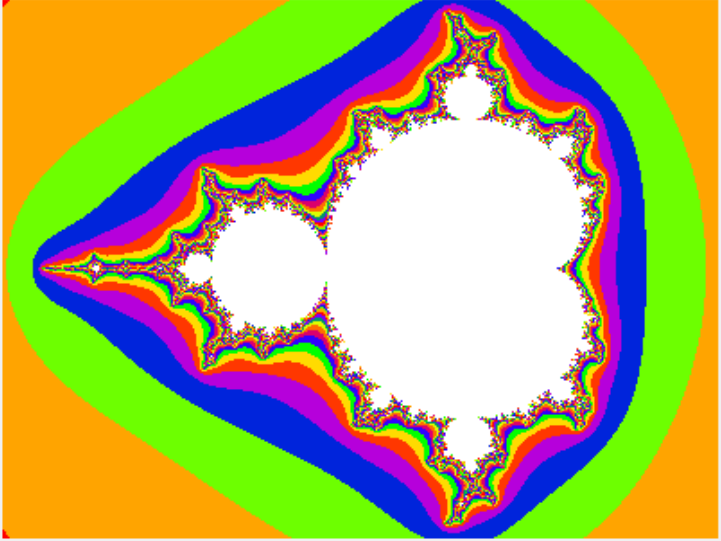


julia



Gaston Julia  
(1893-1978)

<Student Version> : julia



Julia mathematical options

Julia function  $z \rightarrow f(z, z_0)$

$z^2 + z_0$


Map creation rule

abs diverge

Convergence radius: 4      iterations: 50

Map function

abs



Written by Andy "Dijon" French  
Version 1.2 Feb 2012

Load settings      Save settings

Reset to Julia defaults

STOP

Define size of Argand diagram

xwidth: 3.14      x centre: -0.6      y centre: 0

Make julia map

Composite image options

max # of tile pixels: 800

Delete composite images

Colour options

NaN colour: [1 1 1]      Colour range: [0 1]      Colormap: prism

Output PNG image properties

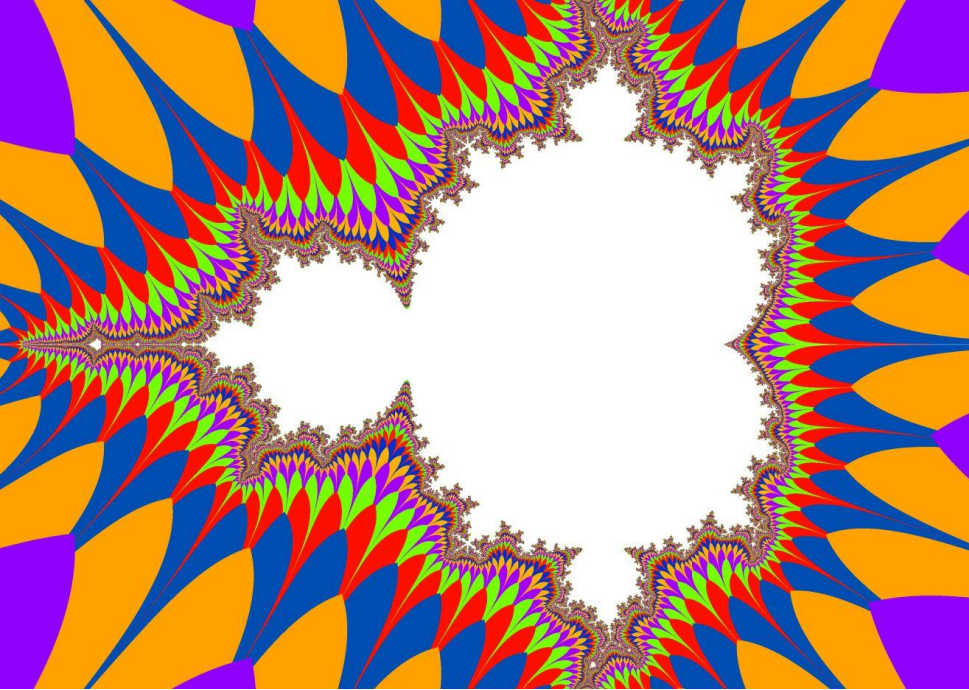
image width: 800      image height: 600

DPI: 600

Plot all iterations

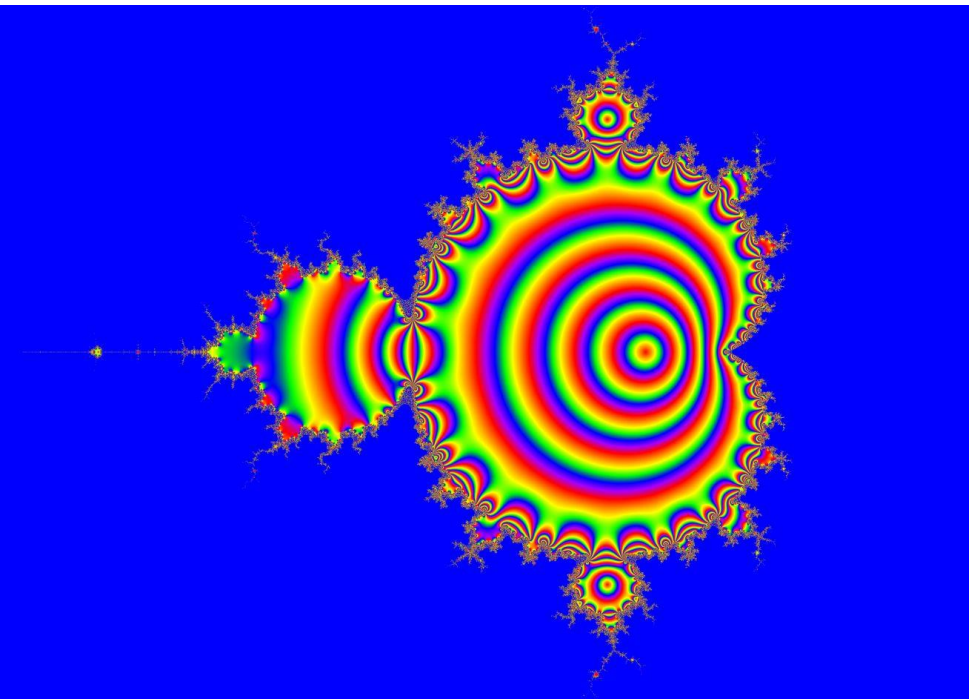
3D surface

3D & 2D surface



`julia.m plot option abs diverge`  
 Plot a surface with height  $h(x,y)$ . This is the *iteration number* when  $|z/|$  exceeds a certain value e.g. 4

In this case *colours* indicate height  $h(x,y)$ . It is a 'colour-map'.

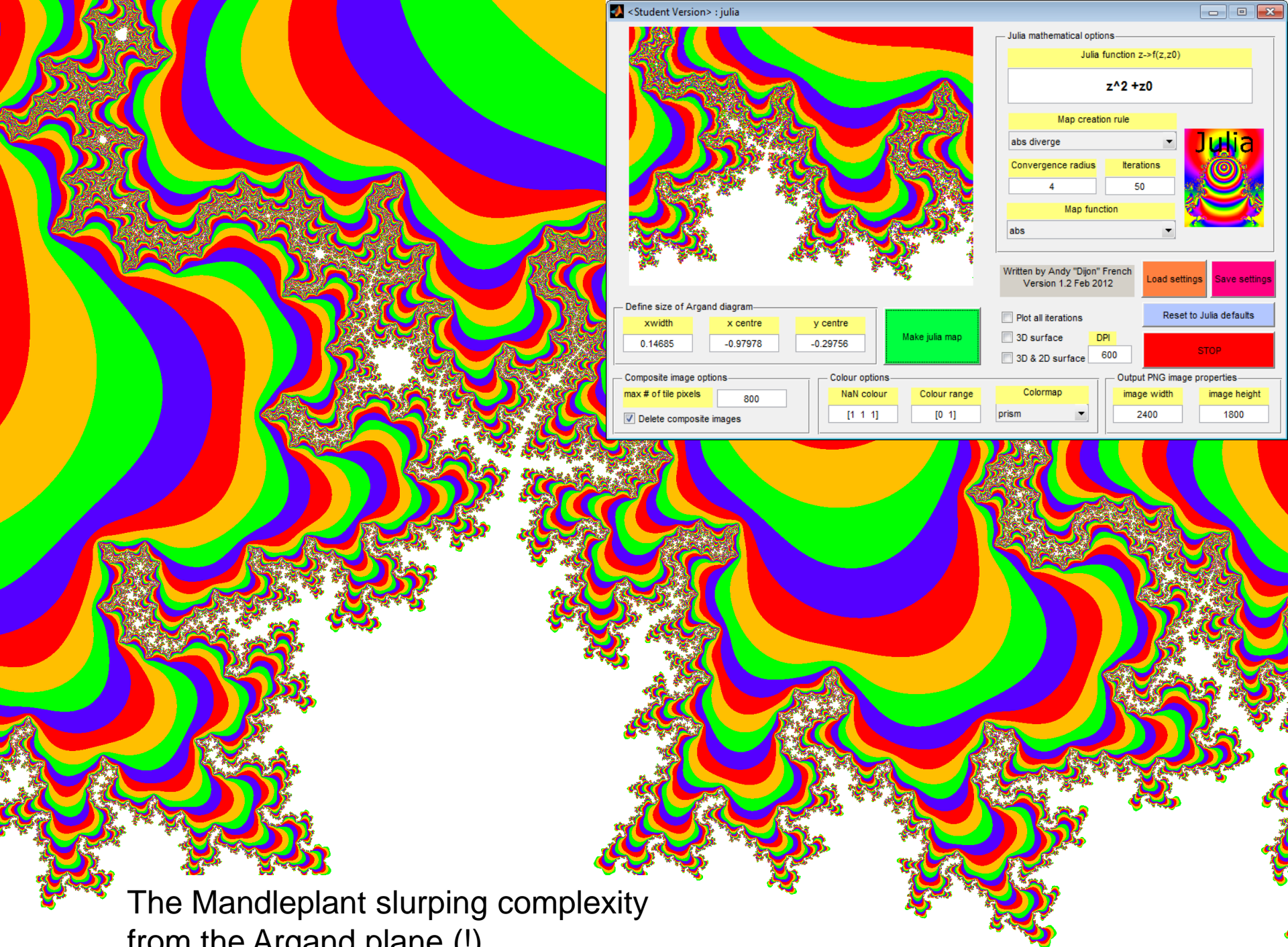


`julia.m plot option plot z`

Plot a surface with height  $h(x,y)$

$$x = \text{Re}(z), \quad y = \text{Im}(z)$$

$$h(x, y) = e^{-\sqrt{x^2 + y^2}}$$



<Student Version> : julia

Julia mathematical options

Julia function  $z \rightarrow f(z, z_0)$

$z^2 + z_0$

Map creation rule

abs diverge

Convergence radius: 4      Iterations: 50

Map function

abs

Written by Andy "Dijon" French  
Version 1.2 Feb 2012

Load settings    Save settings

Reset to Julia defaults

STOP

Define size of Argand diagram

xwidth: 0.14685      x centre: -0.97978      y centre: -0.29756

Make julia map

Composite image options

max # of tile pixels: 800

Delete composite images

Colour options

NaN colour: [1 1 1]      Colour range: [0 1]      Colormap: prism

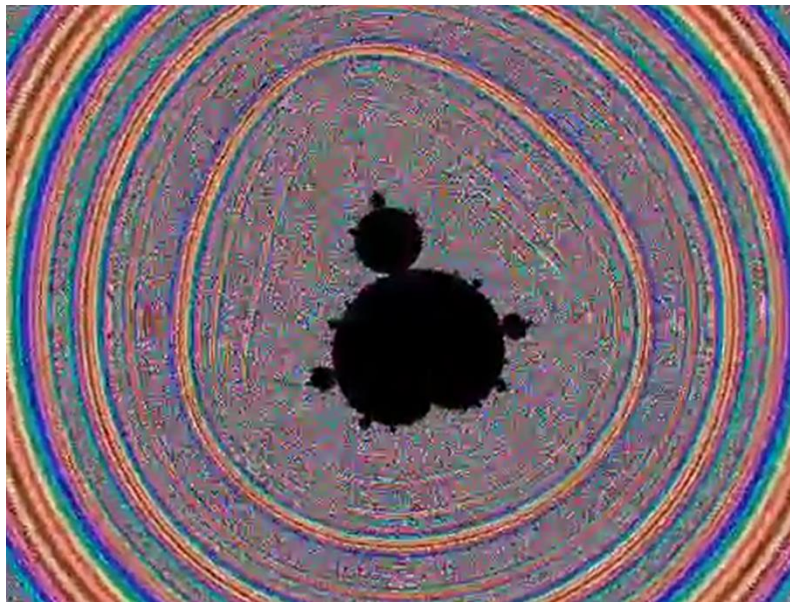
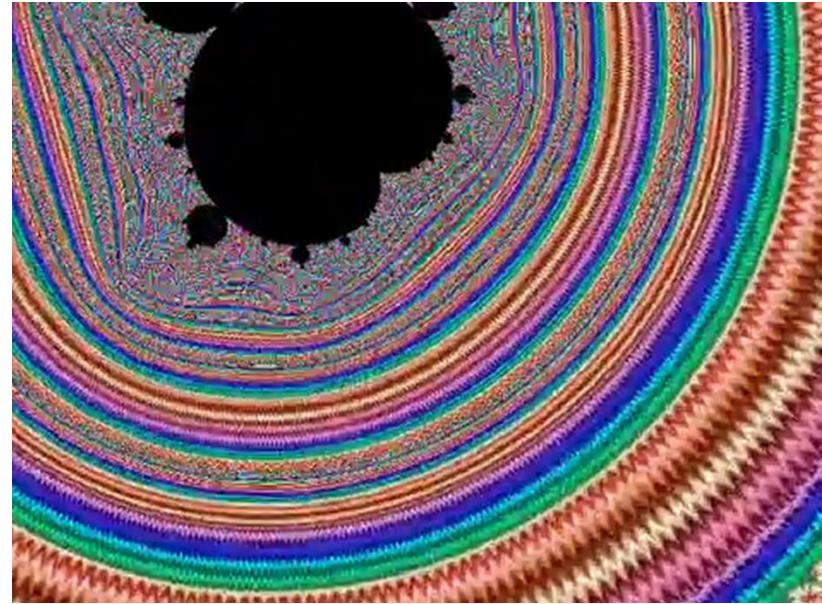
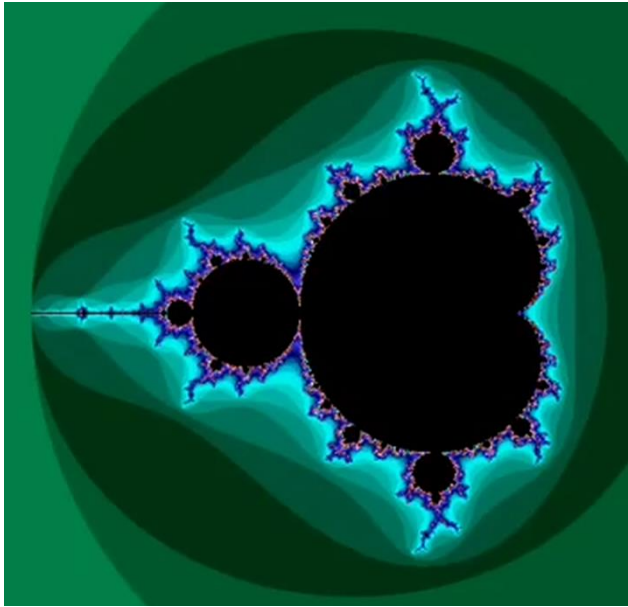
Output PNG image properties

image width: 2400      image height: 1800

The Mandelplant slurping complexity from the Argand plane (!)



# Mandelbrot Deep Zoom

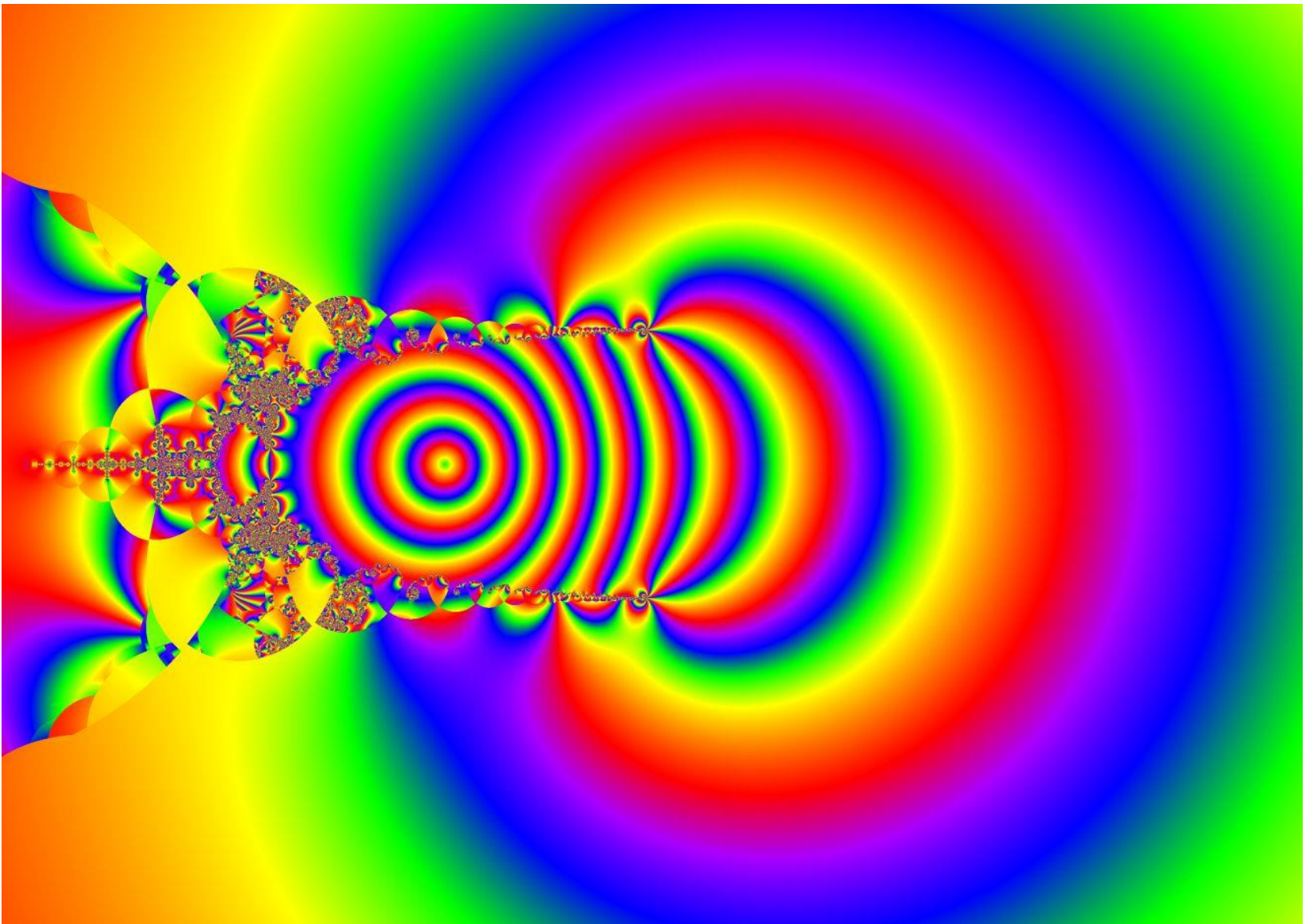




The

Mandelbrot

Variations

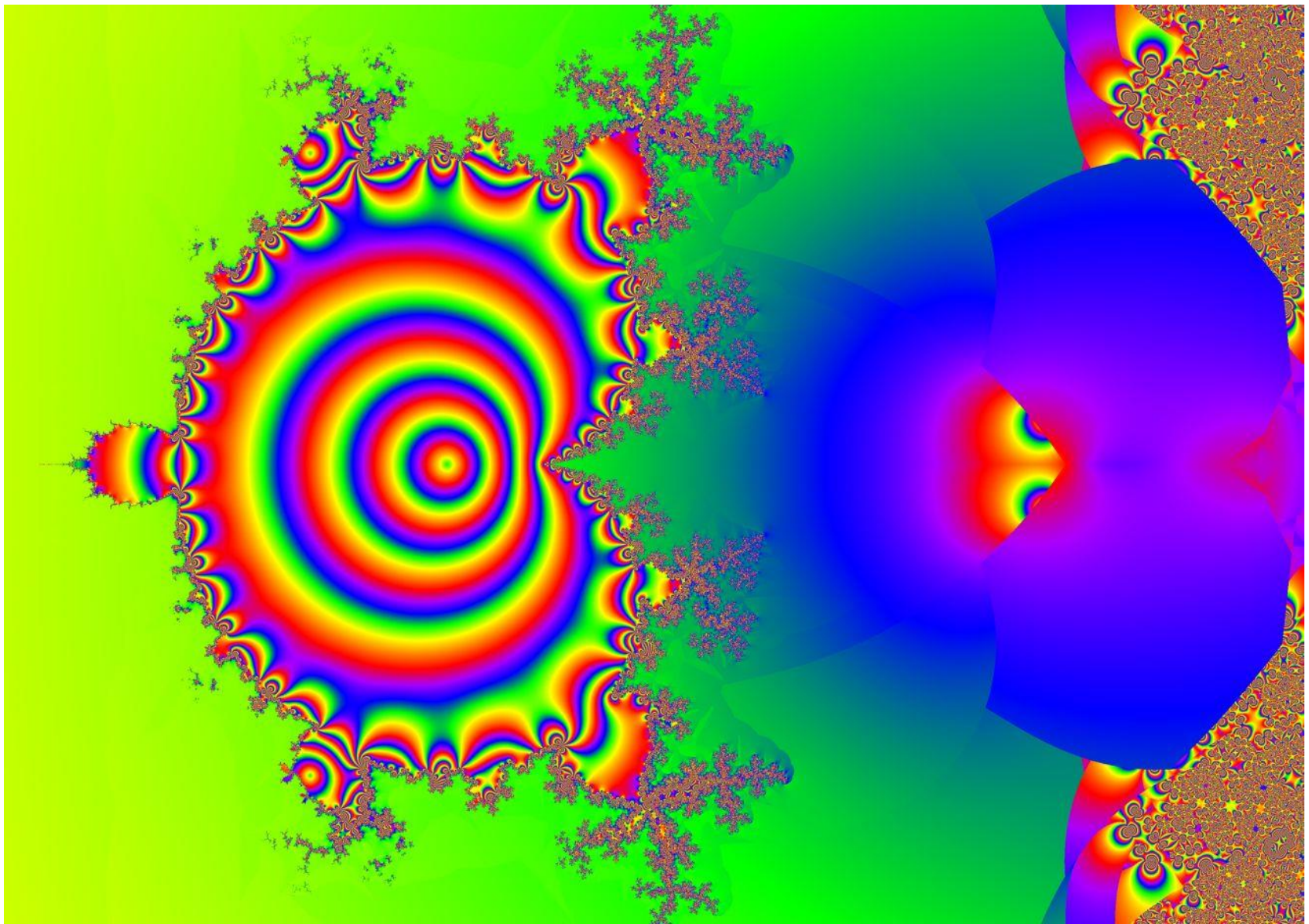


The light bulb

$$z_{n+1} = \log(z_n^2 + z_0)$$

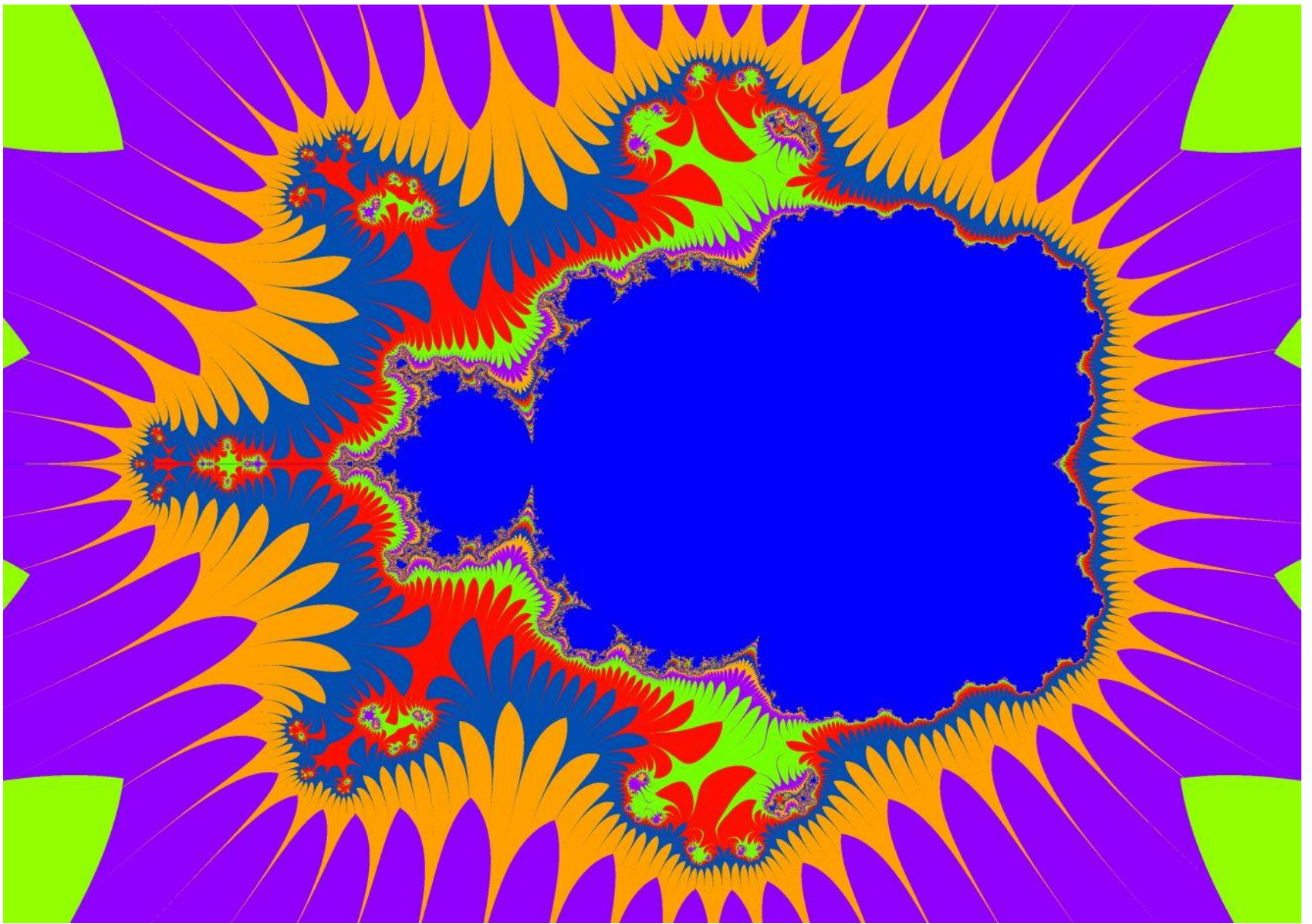


7 steps to enlightenment  $z_{n+1} = \tan^{-1} \left( z_n^2 + z_0 \right)$



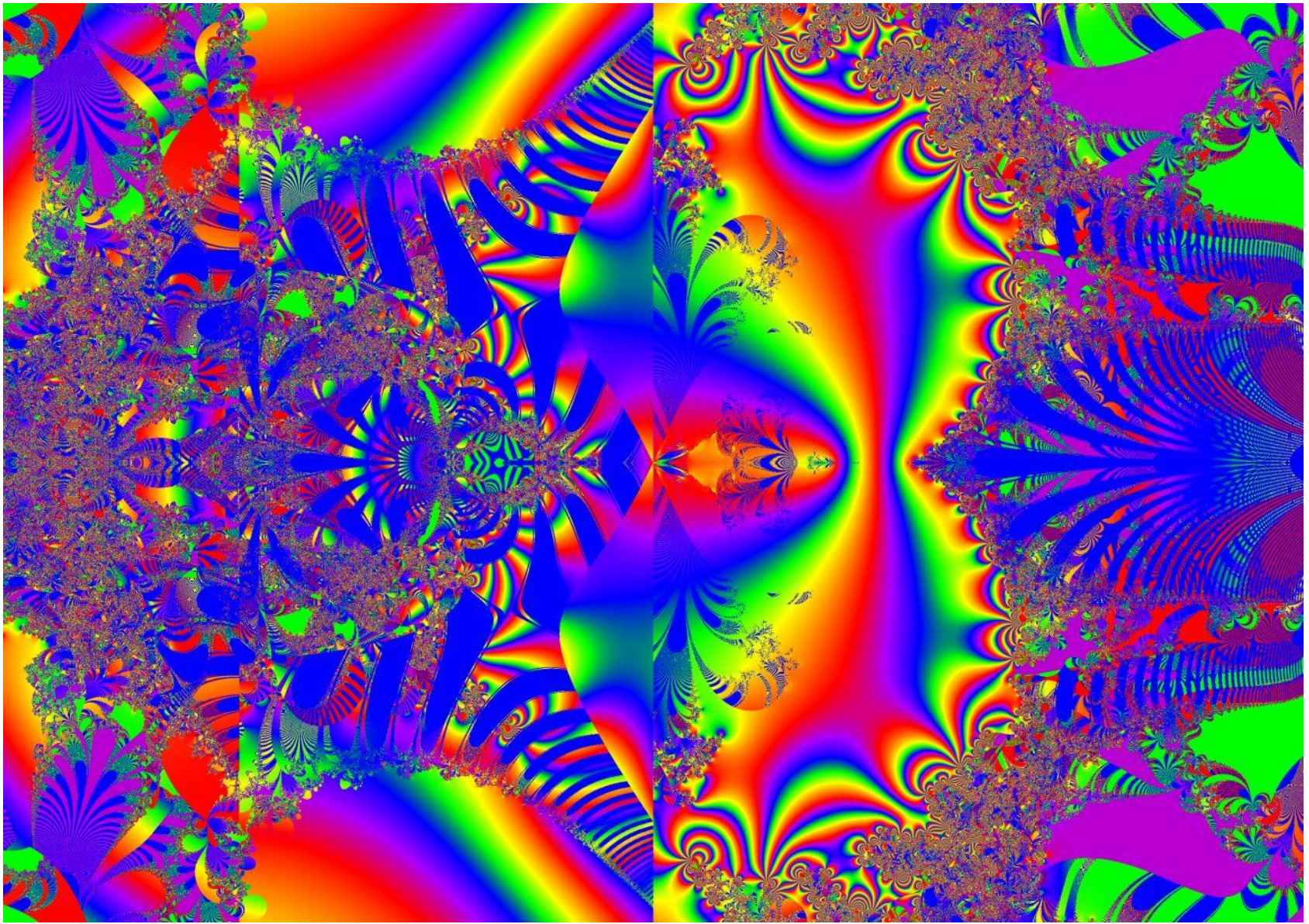
The Mandlerocket!

$$z_{n+1} = \sin^{-1} \left( z_n^2 + z_0 \right)$$



Micro mandlebeast

$$z_{n+1} = \left( z_n^2 + z_0 \right)^2$$

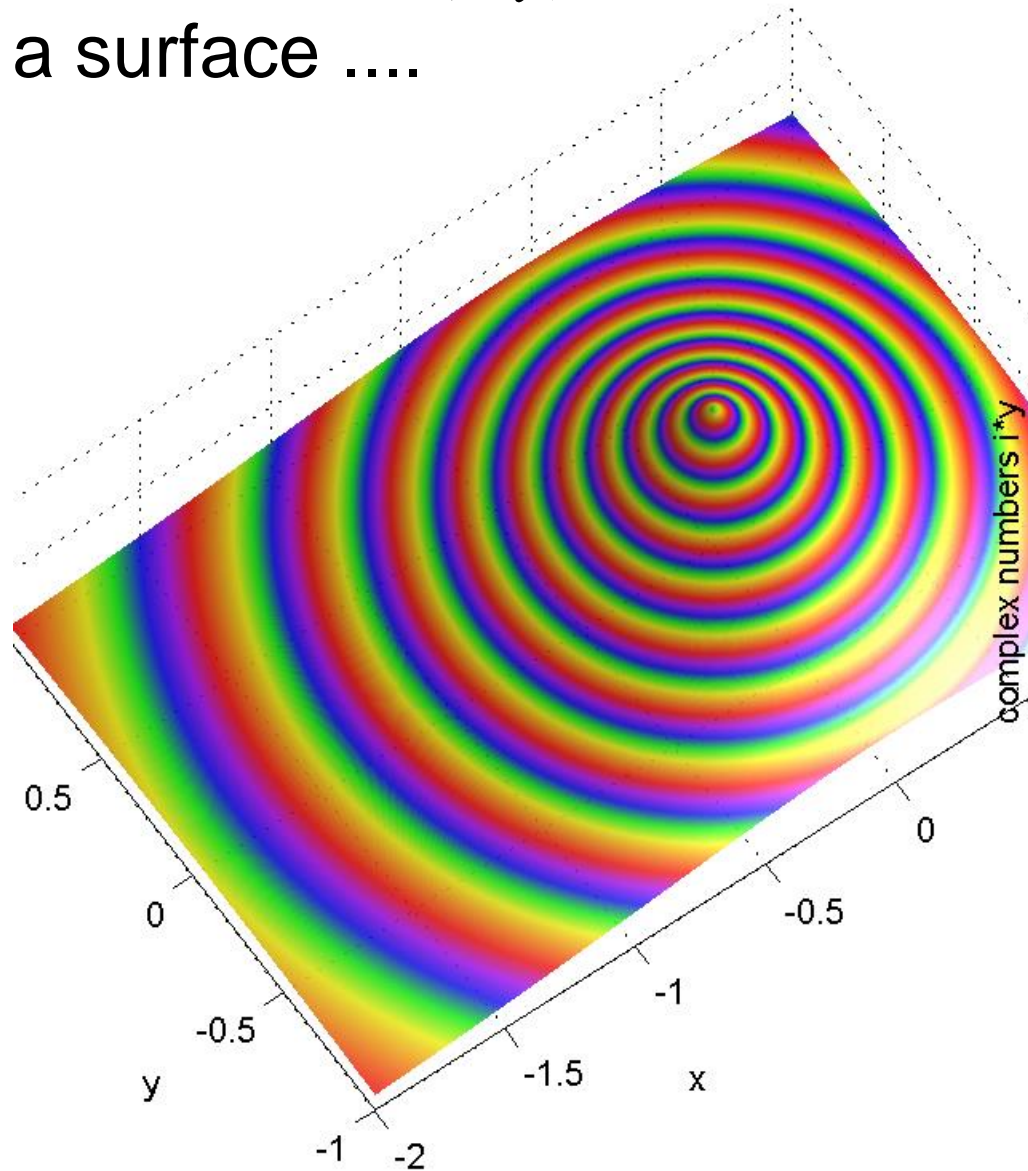


The profusion of power

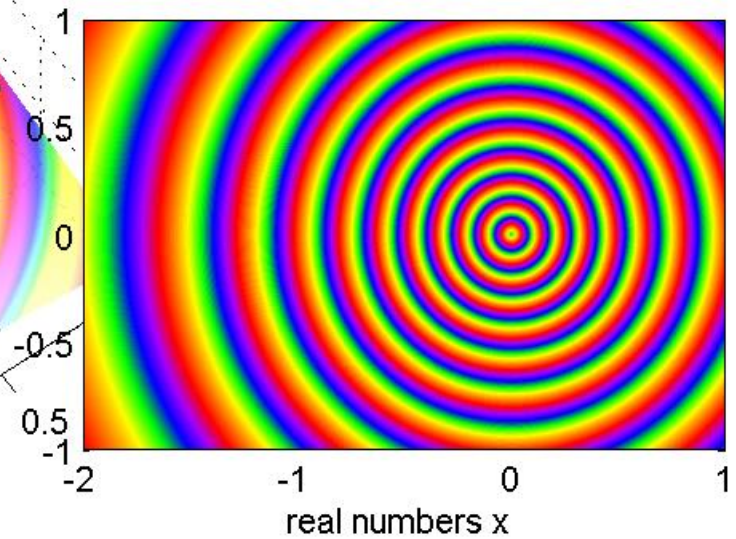
$$z_{n+1} = \left( z_n^2 + z_0 \right)^{z_n}$$

Remember  $h(x,y)$  is a surface ....

$$z_{n+1} = z_n^2 + z_0$$



Mandelbrot surface: iteration 1

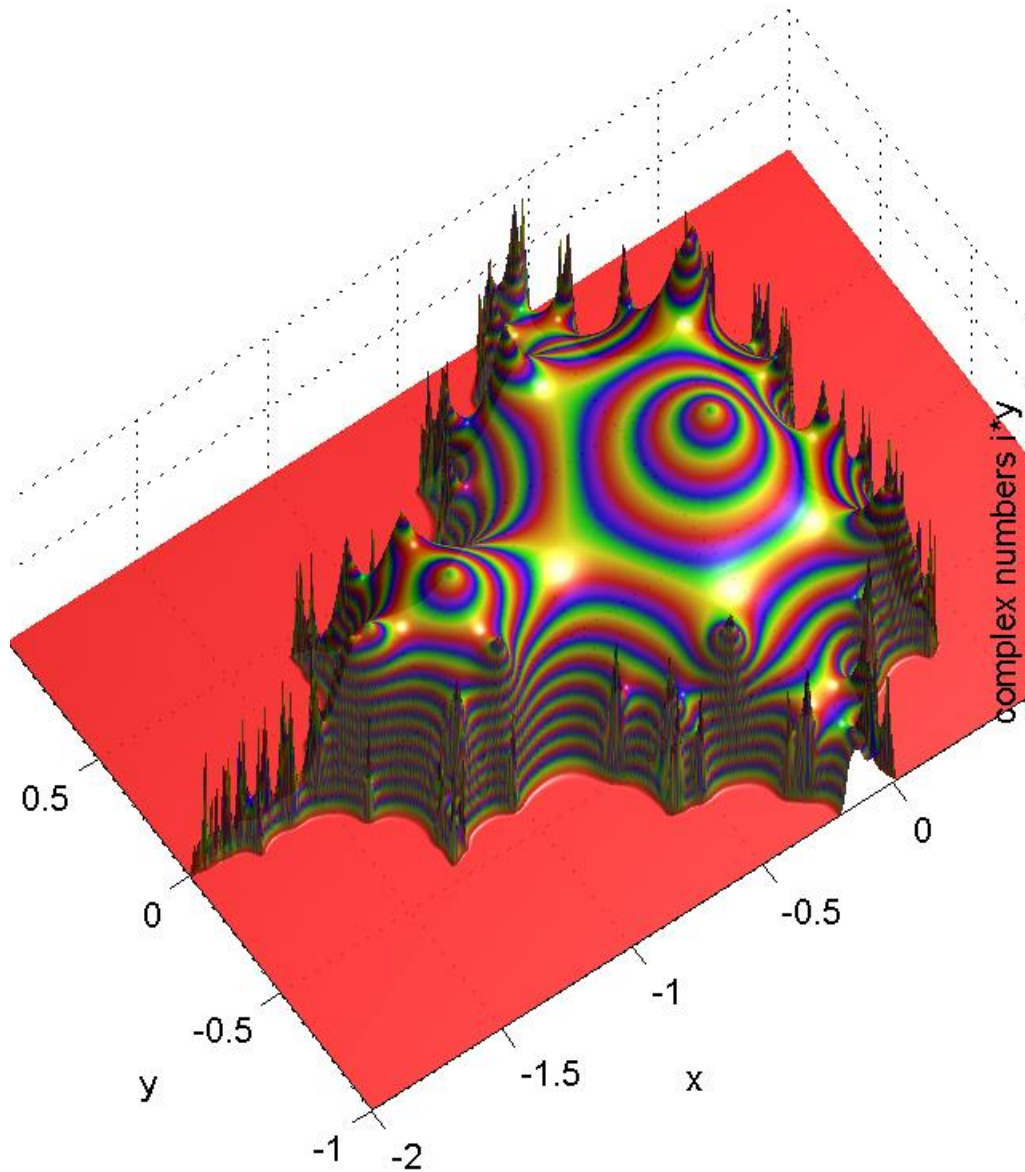


$$x = \text{Re}(z), \quad y = \text{Im}(z)$$

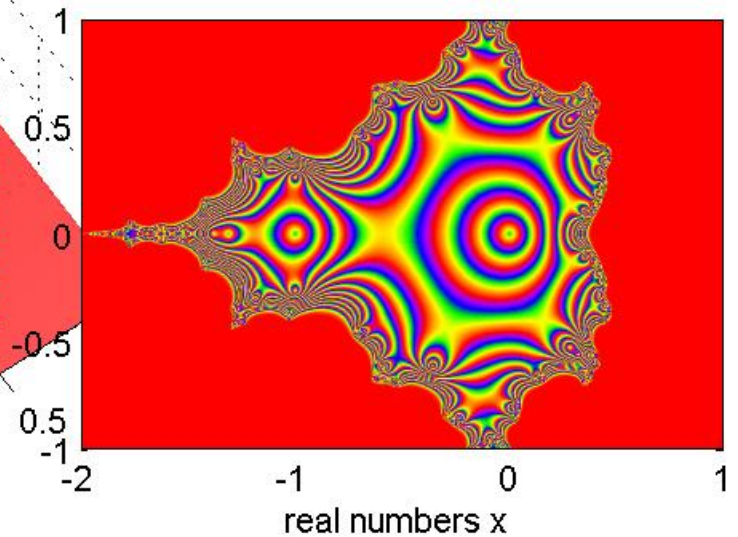
$$h(x,y) = e^{-\sqrt{x^2+y^2}}$$



$$z_{n+1} = z_n^2 + z_0$$



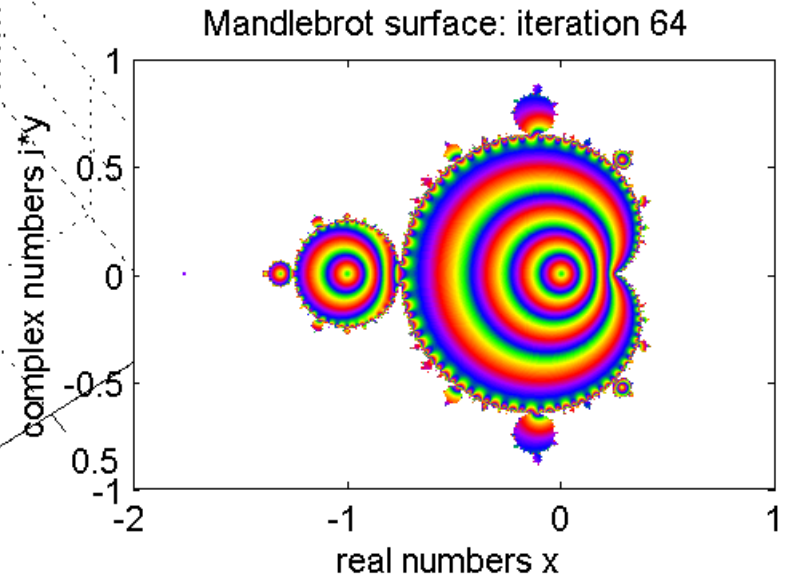
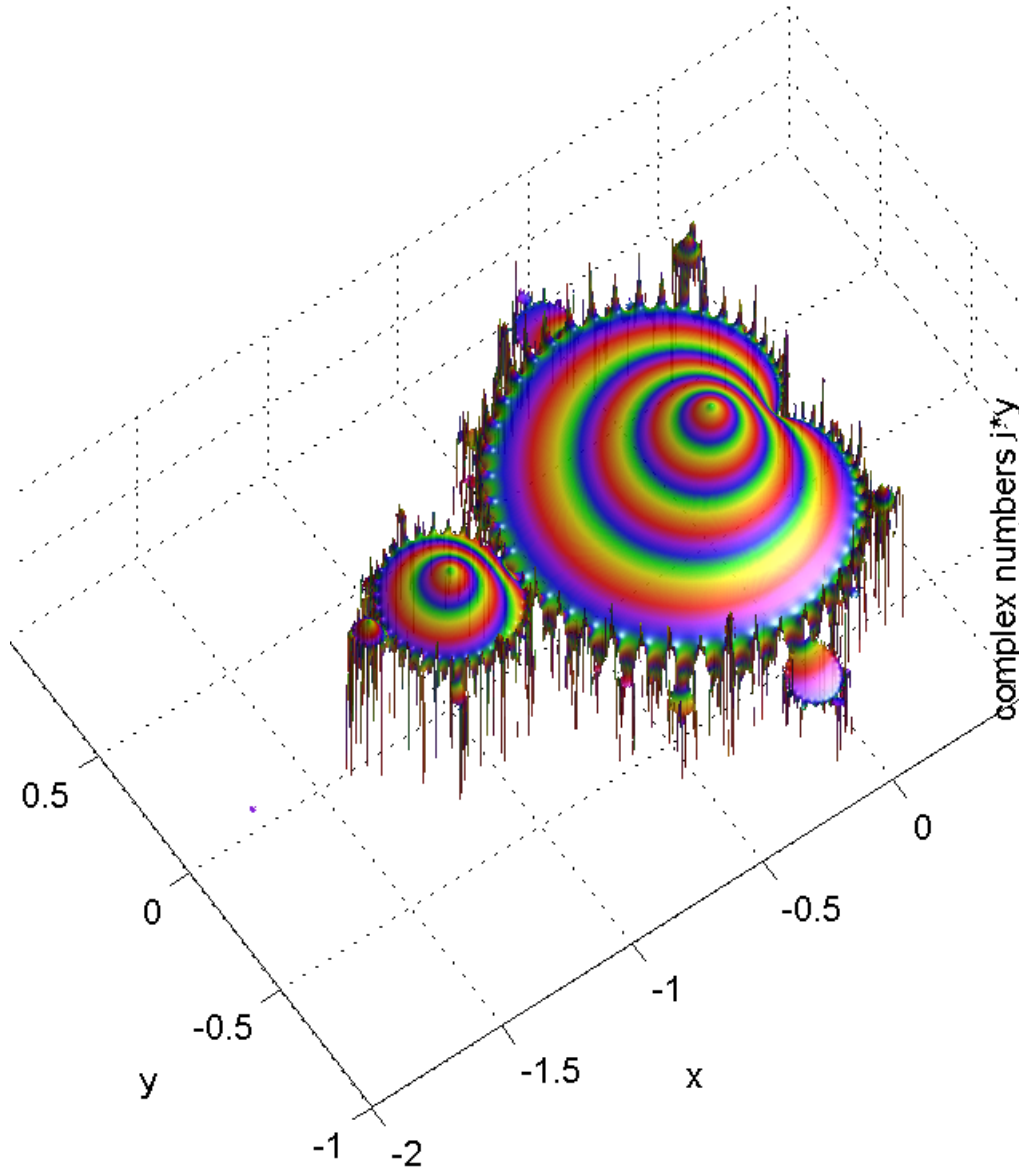
Mandelbrot surface: iteration 8



$$x = \operatorname{Re}(z), \quad y = \operatorname{Im}(z)$$

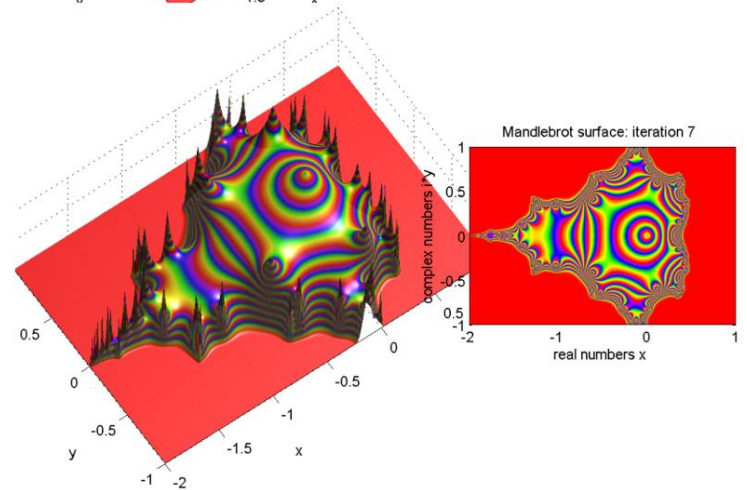
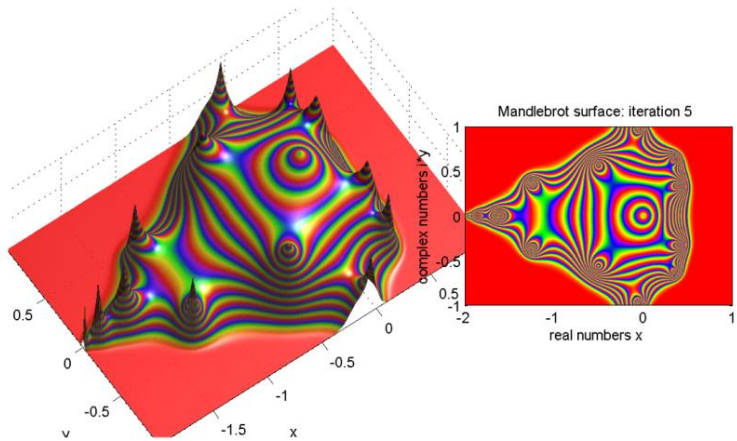
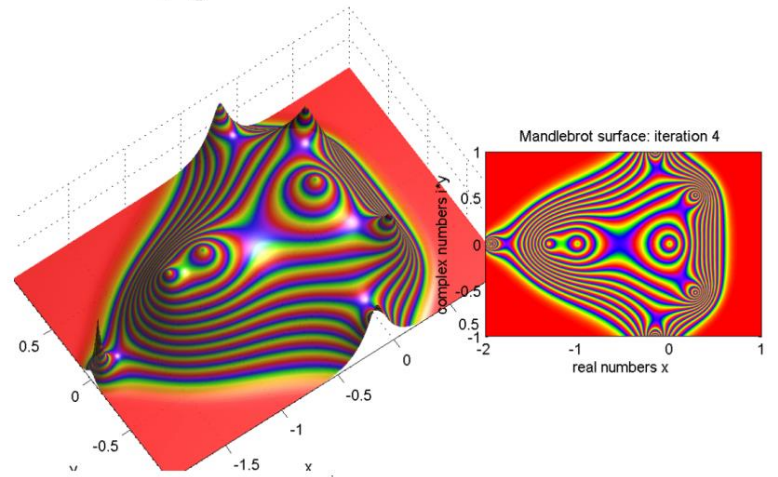
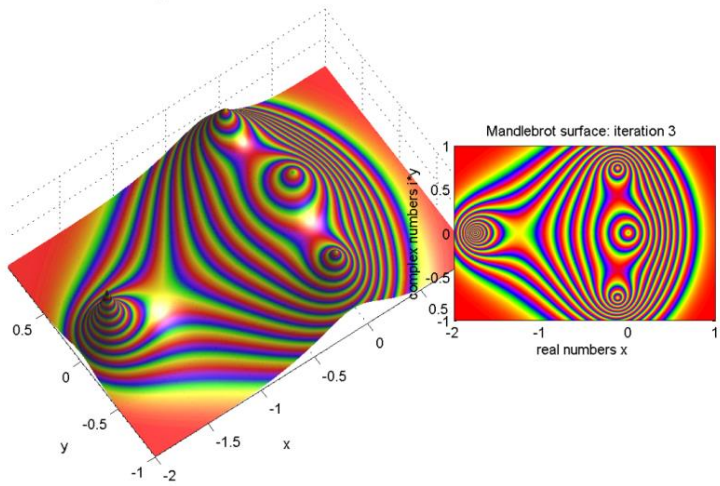
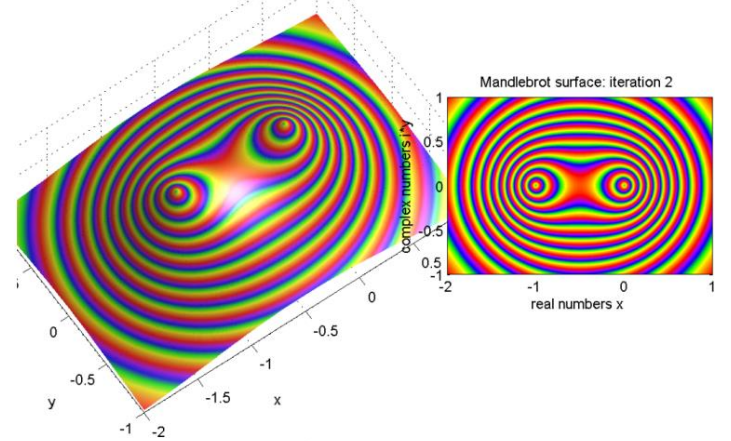
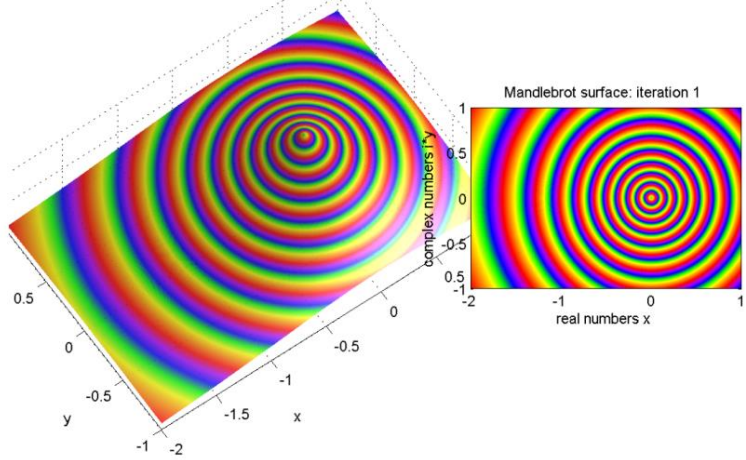
$$h(x, y) = e^{-\sqrt{x^2 + y^2}}$$

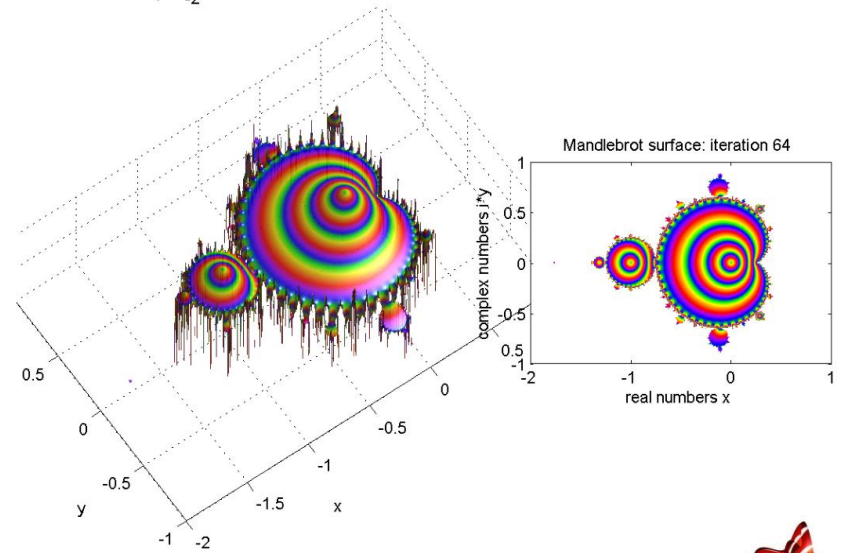
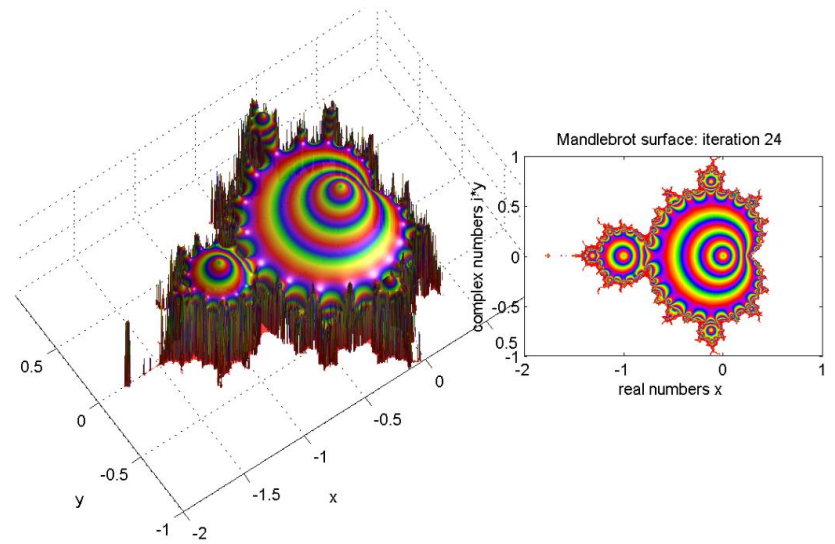
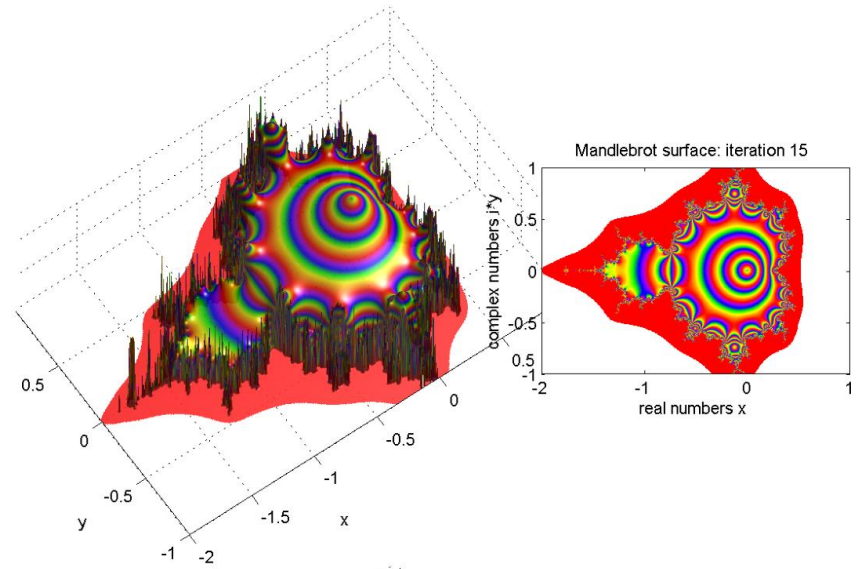
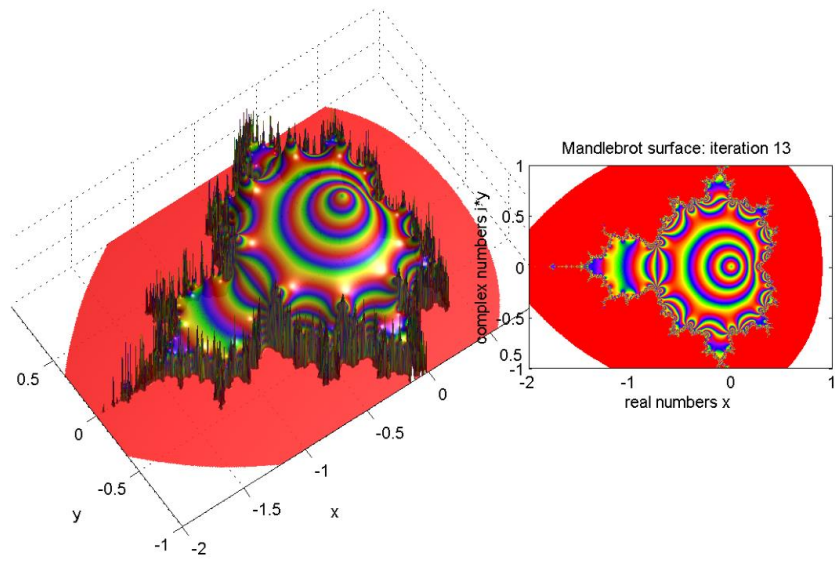
$$z_{n+1} = z_n^2 + z_0$$



$$x = \text{Re}(z), \quad y = \text{Im}(z)$$

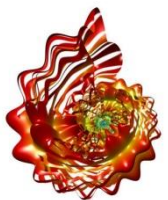
$$h(x, y) = e^{-\sqrt{x^2 + y^2}}$$





Selection from *Day of Julia*.

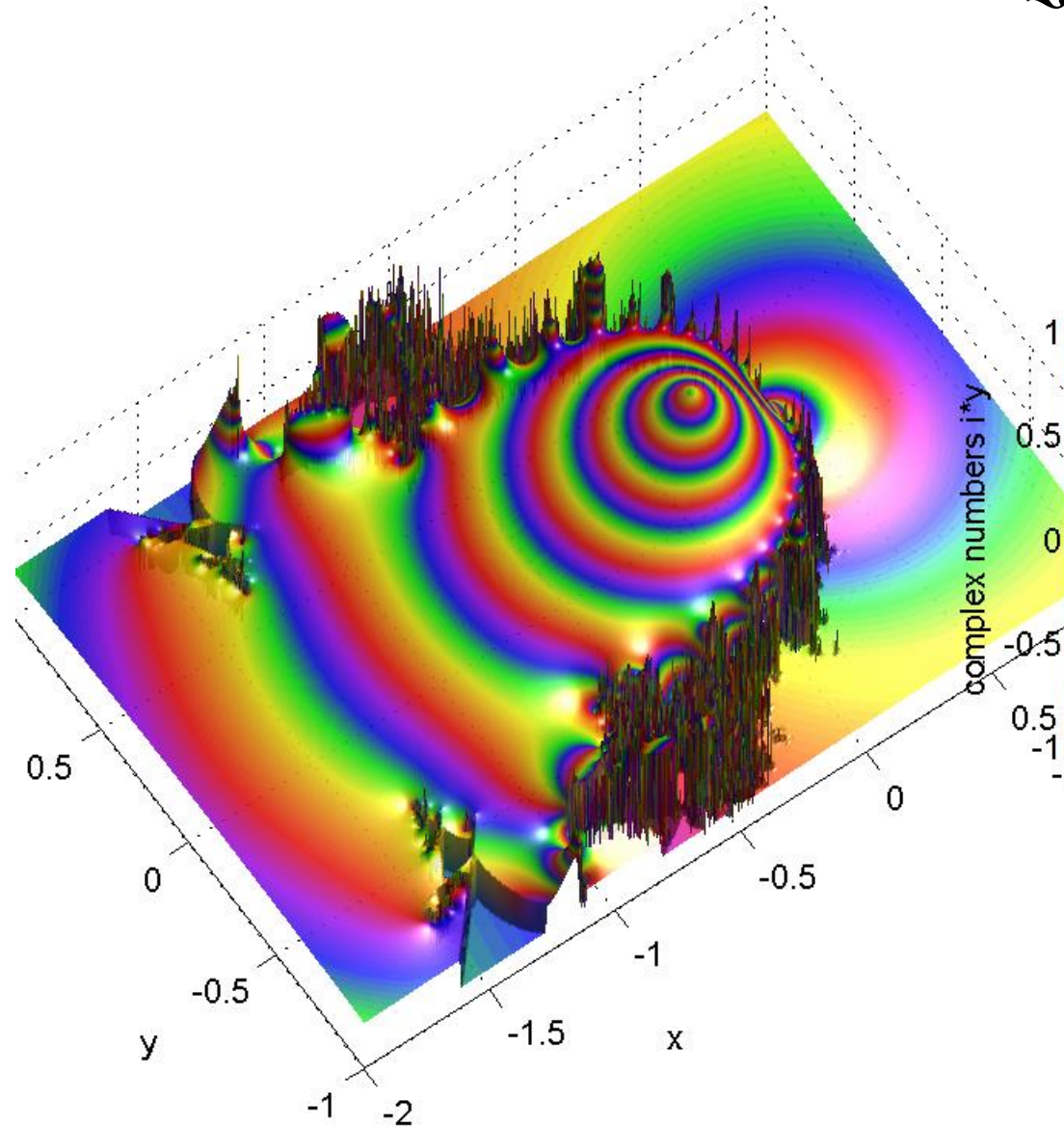
Mathematicon Exhibition, 2014



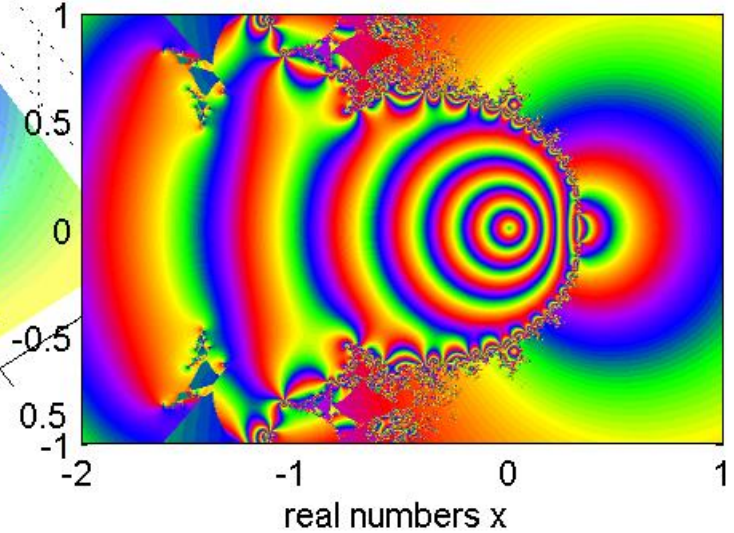
$\mu$  mathematicon

7 steps to enlightenment

$$z_{n+1} = \tan^{-1} \left( z_n^2 + z_0 \right)$$



Mandelbrot surface: iteration 24

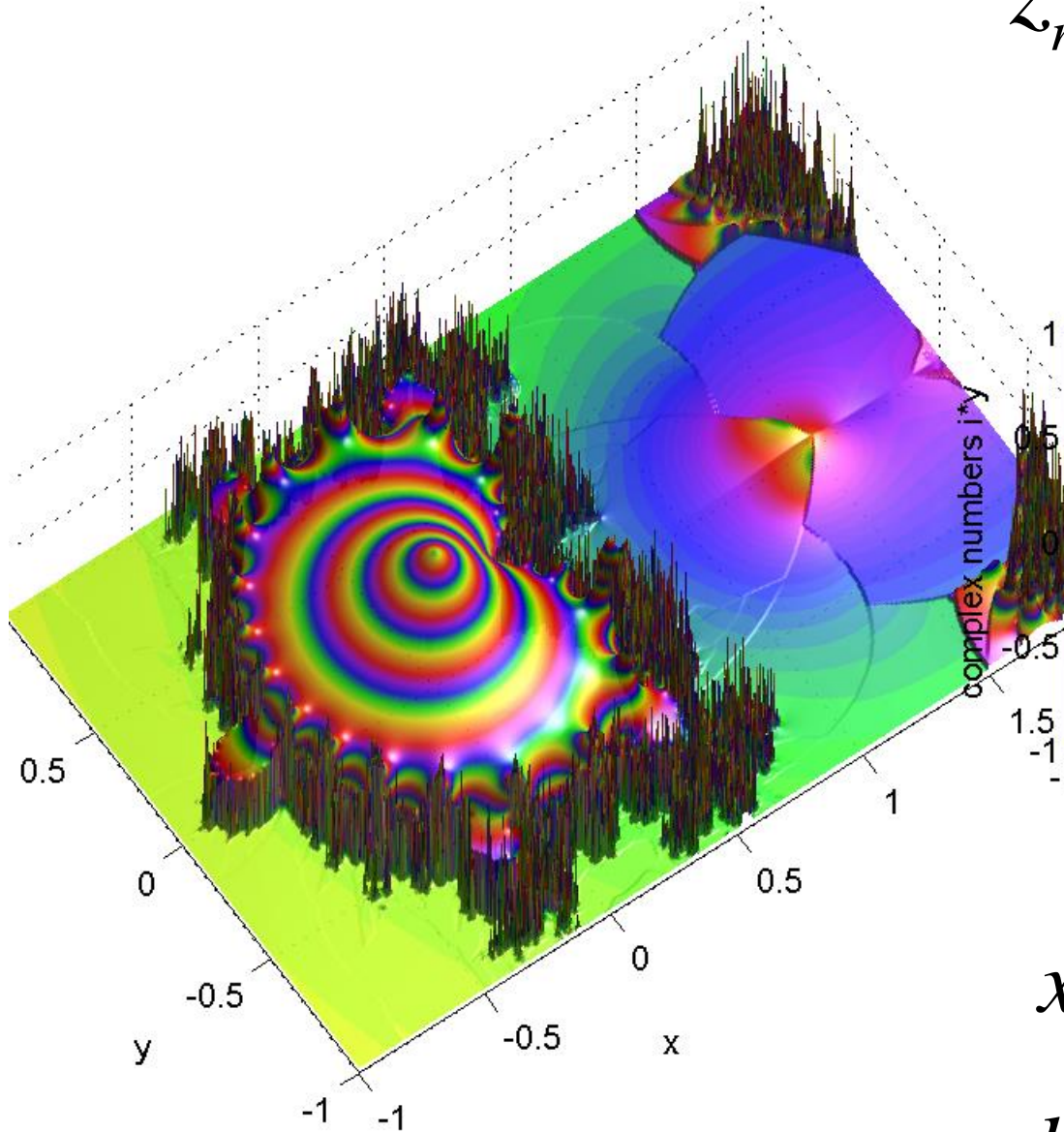


$$x = \text{Re}(z), \quad y = \text{Im}(z)$$

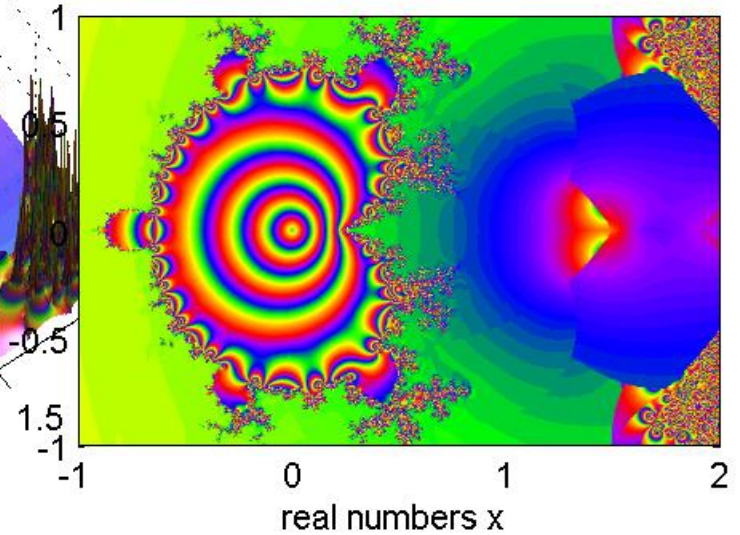
$$h(x, y) = e^{-\sqrt{x^2 + y^2}}$$

# The Mandlerocket

$$z_{n+1} = \sin^{-1} \left( z_n^2 + z_0 \right)$$



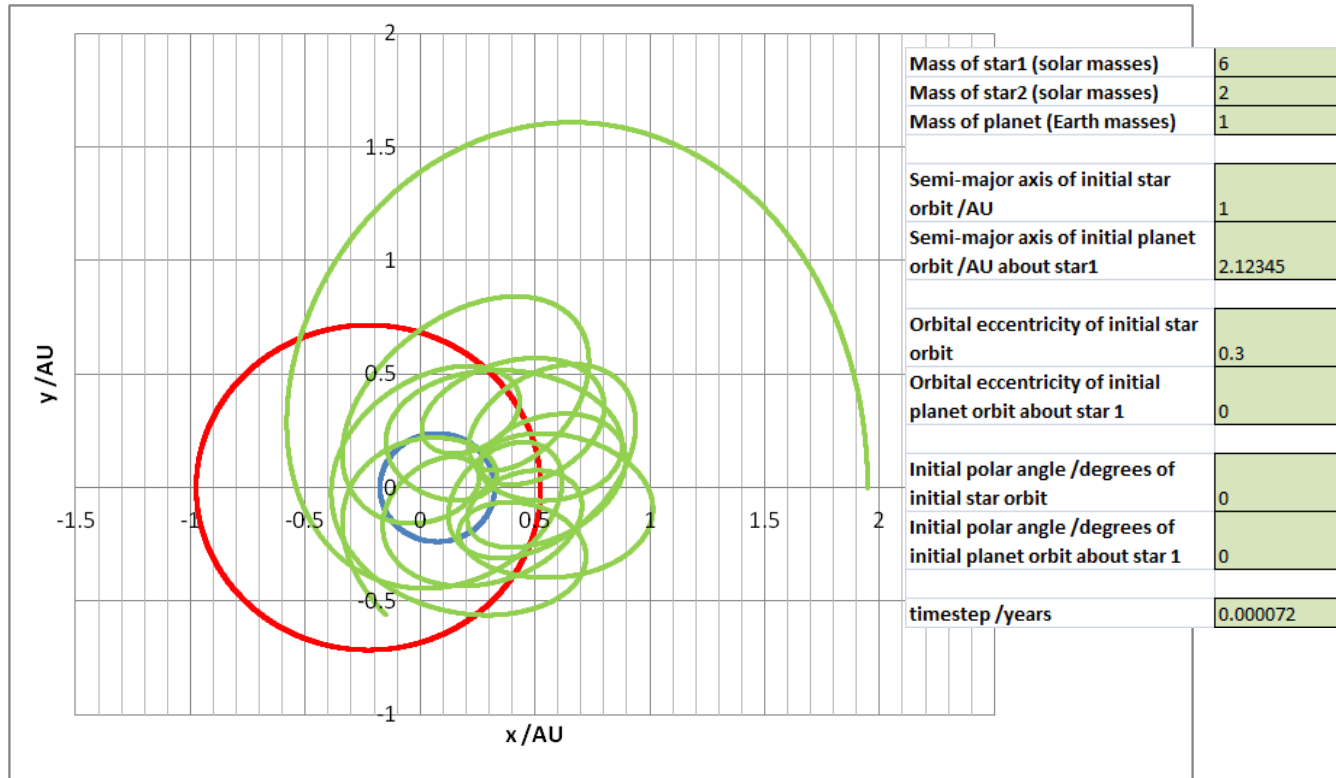
Mandlebrot surface: iteration 25



$$x = \text{Re}(z), \quad y = \text{Im}(z)$$

$$h(x, y) = e^{-\sqrt{x^2 + y^2}}$$

# Chaos in planetary systems



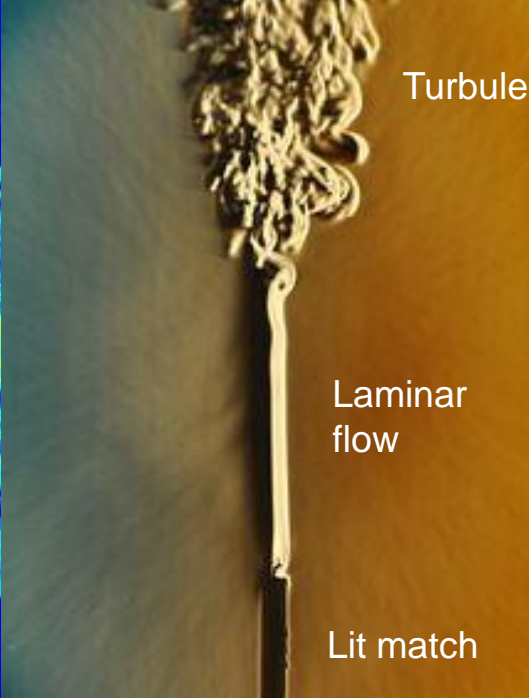
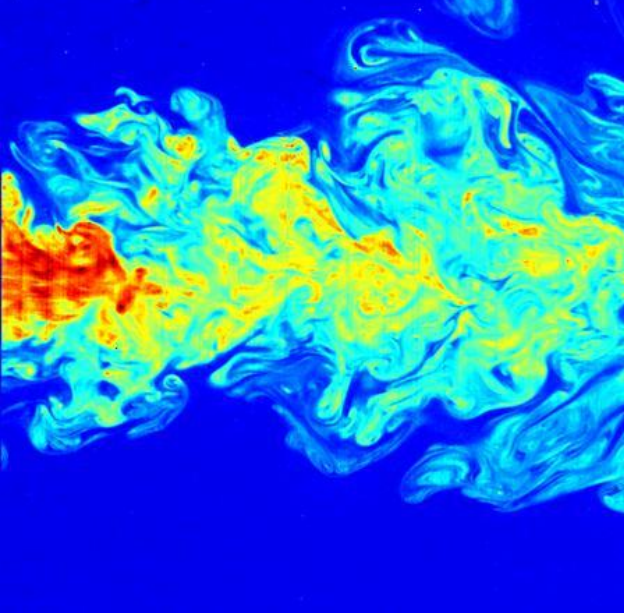
The motion of a planet in a close binary star system can be chaotic

The 'three body problem' has no closed form solution!

The small moons of **Pluto** (Nix, Hydra, Styx, and Kerberos) *rotate chaotically* →



# Chaos in fluid flow



Turbulence

Laminar flow

Lit match



<https://en.wikipedia.org/wiki/Turbulence>



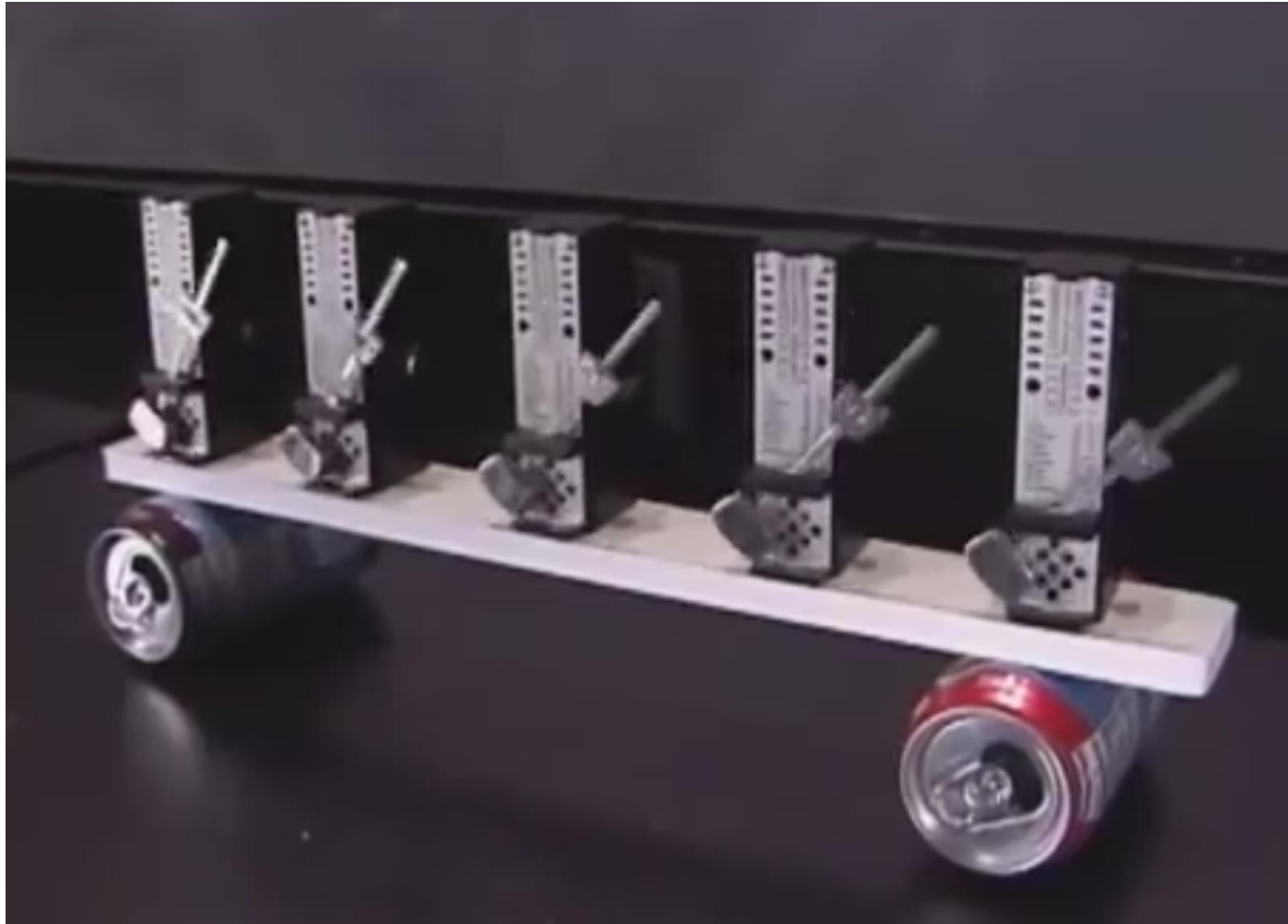
Leonardo da Vinci



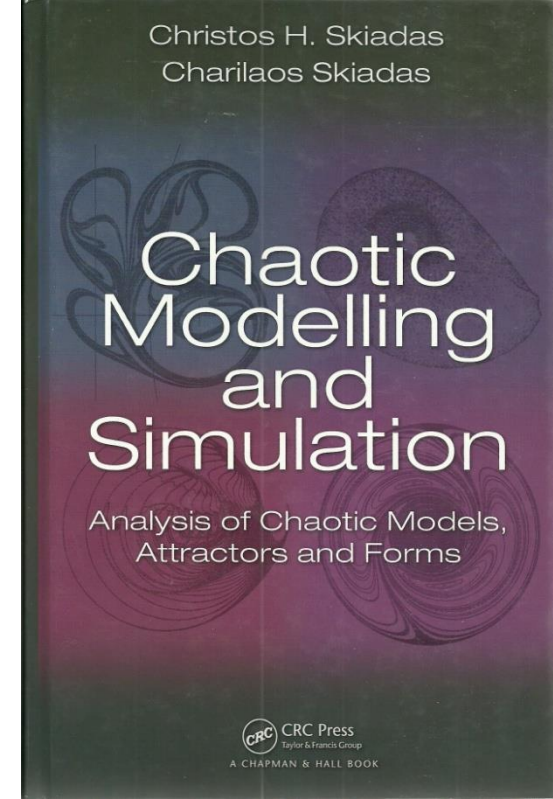
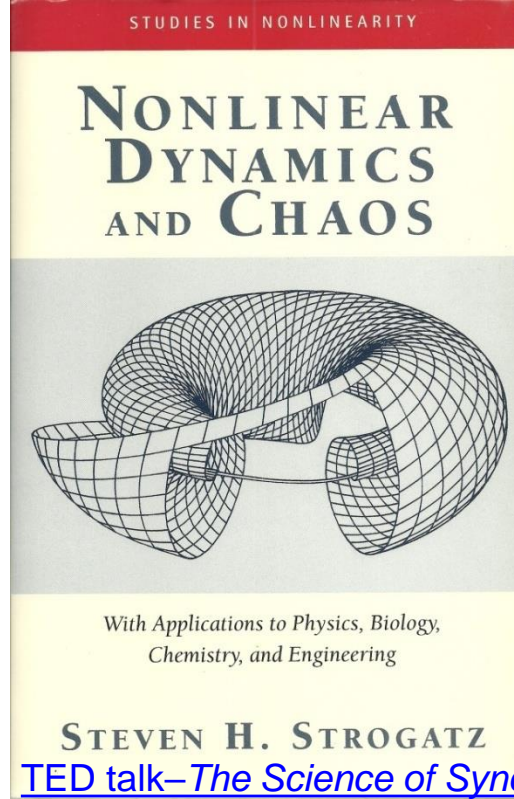
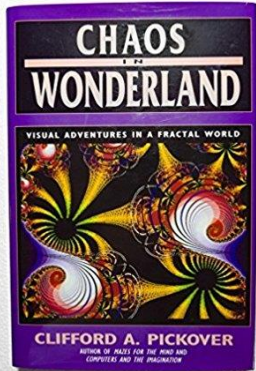
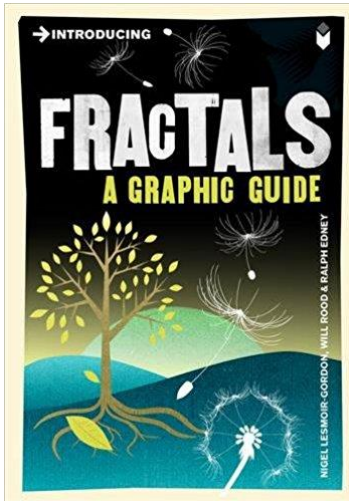
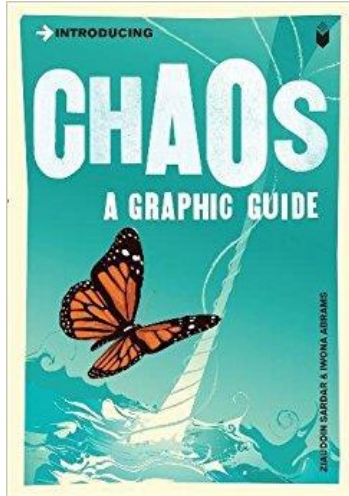
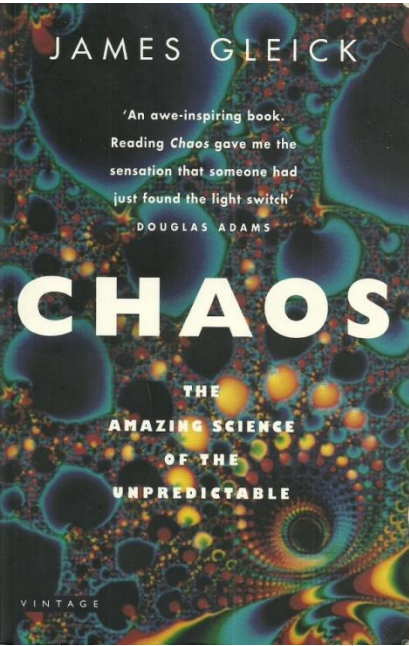
Vincent Van Gogh *Starry Night* (1889)



# Phase locking - spontaneous *order* from chaos due to 'nonlinear feedback'



# Further reading



Shaw *et al*, "Chaos",  
Scientific American 54:12  
(1986) 46-57



ISLE OF WIGHT  
Directgov  
BBC  
WIKIPEDIA  
The Free Encyclopedia  
WolframAlpha  
the guardian  
DATABLOG  
Facts are sacred  
Google

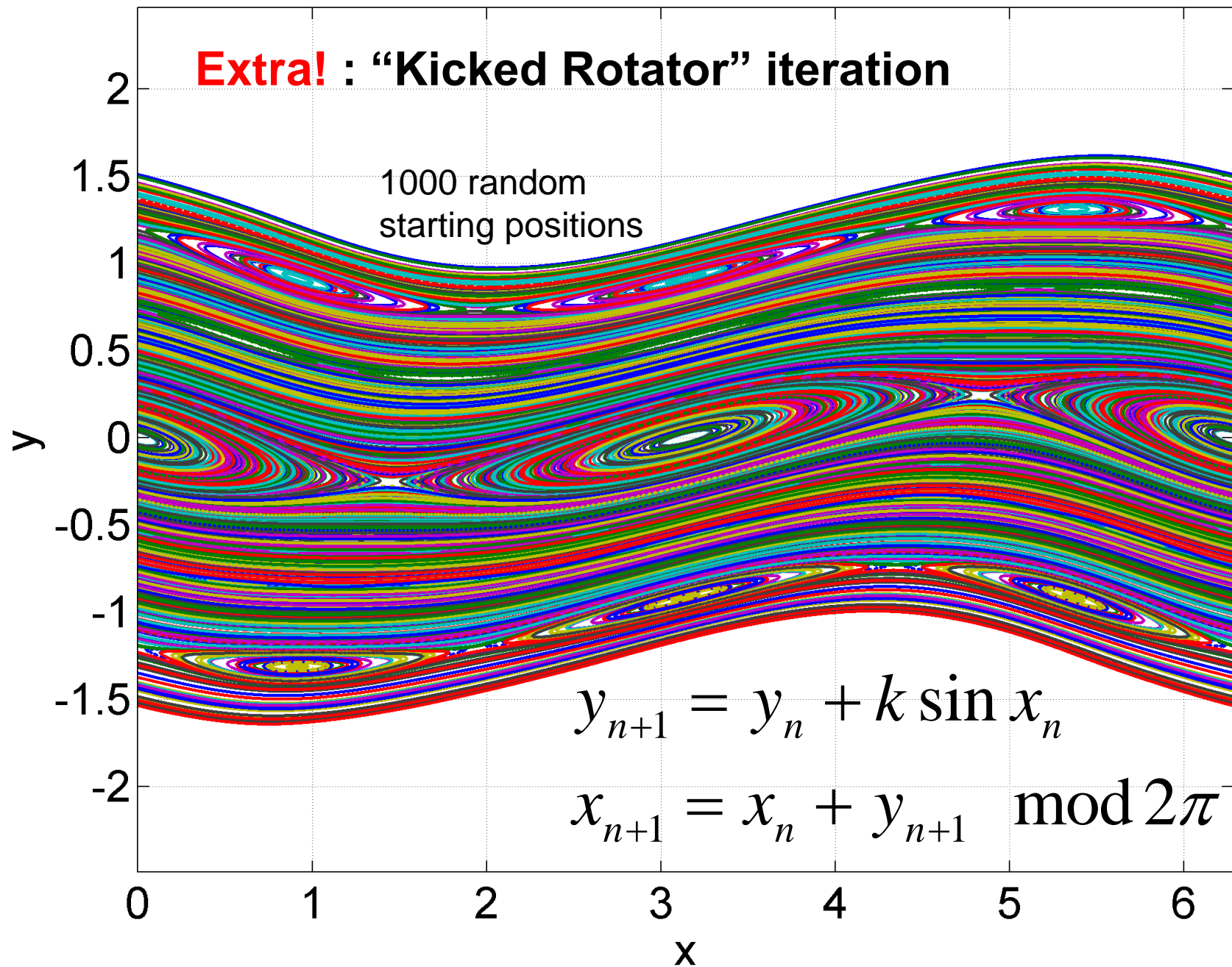


BBC RADIO 1  
BBC RADIO 2  
BBC RADIO 3  
BBC RADIO 4  
BBC RADIO 5 live  
BBC RADIO 6 music  
PLANET ROCK  
WHERE YOUR LIVES

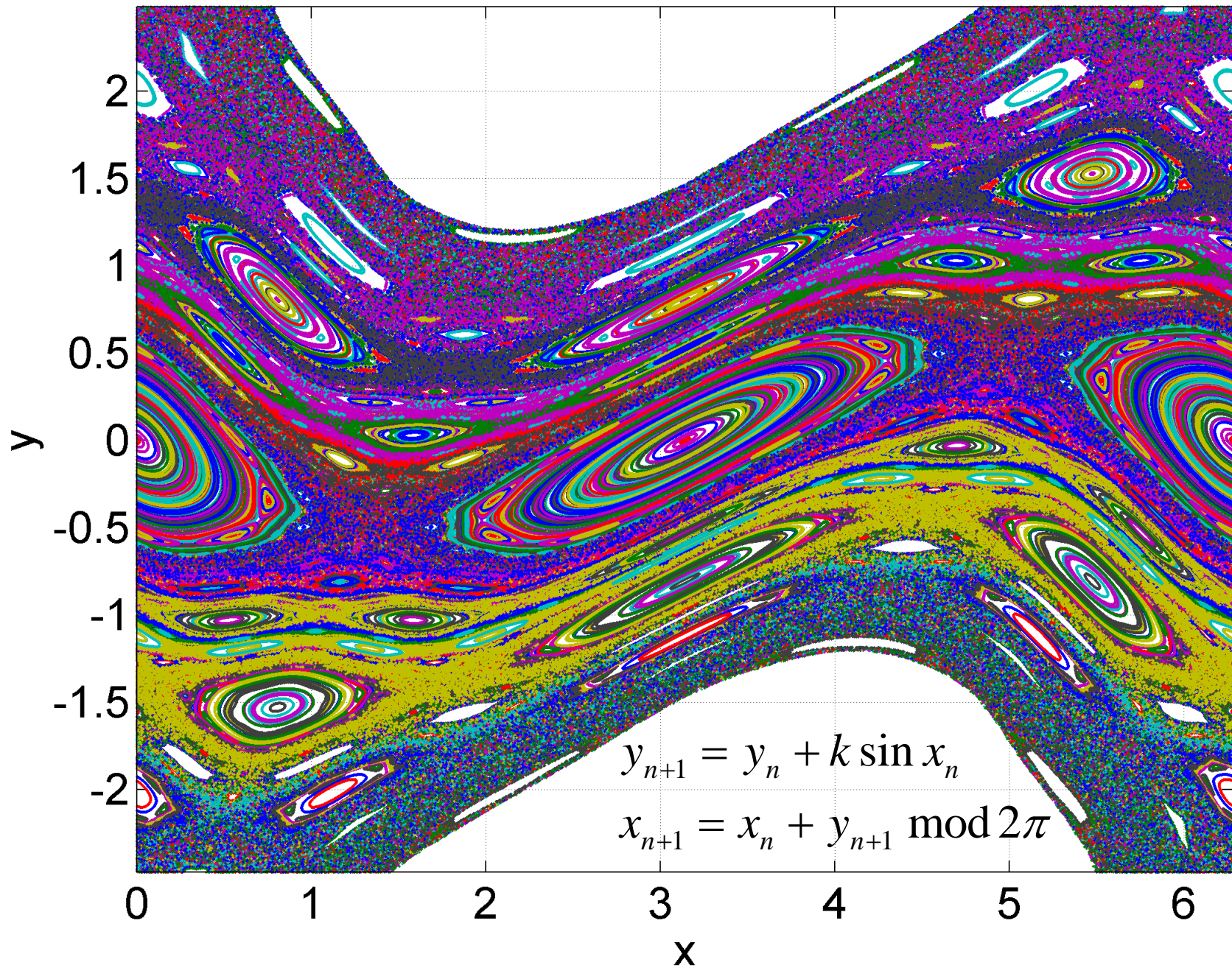


[www.eclecticon.info](http://www.eclecticon.info)

# Kicked rotor iteration. $N = 10000$ , $k = 0.5$



Kicked rotor iteration.  $N = 10000$ ,  $k = 1$



# Kicked rotor iteration. $N = 10000$ , $k = 1.5$

