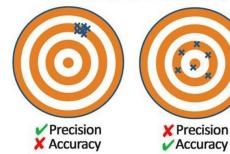
# Basic ideas of precision, accuracy and error analysis

### PRECISION VS ACCURACY



 $x_{-} \le x \le x_{+}$ ,  $y_{-} \le y \le y_{+}$ 



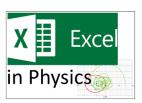


$$\overline{x} = \frac{1}{N} \sum_{i=1}^{N} x_i$$

$$\sigma_{x} = \sqrt{\frac{1}{N-1}} \sum_{i=1}^{N} \left( x_{i} - \overline{x} \right)^{2}$$

$$x_{-}^{2}y_{-} \le x^{2}y \le x_{+}^{2}y_{+}$$
 and  $x_{-}^{2}/y_{+} < x^{2}/y < x_{+}^{2}/y_{-}$ 

$$x = \overline{x} \pm \sigma_{x}$$



## Standard form

Very small and very large quantities are tedious (and error prone) to write out using full decimal notation.

Standard form: e.g.  $6.67 \times 10^{-11}$  is an *integer* between 1 and 9 followed by N - 1 digits, where N is the number of **significant figures** of the quantity.

The power of 10 (the 'exponent') gives you an immediate sense of scale.

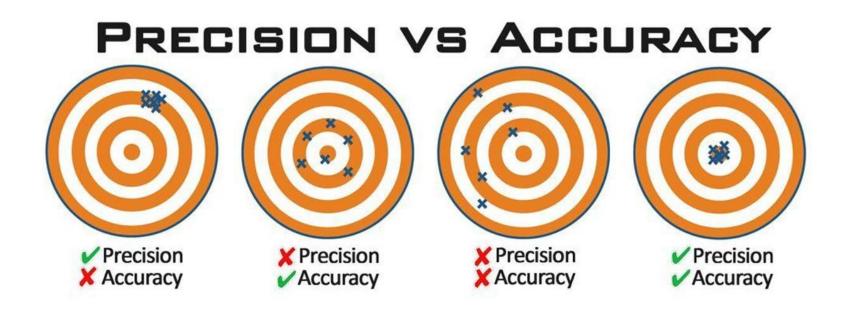
**Precision.** A precise measurement is performed to a high number of significant figures. This means the *random error* in the measurement (i.e. the *standard deviation*) is *very small* compared to the *mean value*. In calculations, one should quote a answer to the *worst precision* (i.e. lowest number of significant figures) of the *input values*.

$$x = 123.4$$
,  $y = 56.7$ ,  $z = 8.9$   

$$x = 1.234 \times 10^{2}$$
,  $y = 5.67 \times 10^{1}$ ,  $z = 8.9$  lowest precision i.e. 2 s.f.
$$a = \frac{xy}{z} = \frac{123.4 \times 56.7}{8.9} = 786.1550...$$
 (unrounded)

 $a = 7.9 \times 10^2$  to 2.s.f

**Accuracy** relates to the degree of *systematic error*. A time of 12.345s may be *very precise*, but could easily be 2.000s out from a true value of 10.345s if there is some form of accidental offset in the timing system.



# Mean and standard deviation

If you have a *sample* of data, which you believe represents a quantity xsubject to random error:

$$\overline{x} = \frac{1}{N} \sum_{i=1}^{N} x_i$$

is an *unbiased estimator* of the **mean value** of the quantity x. N is the number of measurements, and  $x_i$  is the  $i^{th}$  measurement.

$$\sigma_{x} = \sqrt{\frac{1}{N-1} \sum_{i=1}^{N} \left( x_{i} - \overline{x} \right)^{2}}$$

is an unbiased estimator of the error in this measurement. This is not quite the standard deviation, which involves an N factor rather than N-1 in the fraction preceding the sum.

The measurement x can therefore be quoted:  $x = \overline{x} \pm \sigma_{x}$ 

$$x = \overline{x} \pm \sigma_{x}$$

#### **ERROR CALCULATION**

ACTUAL X VALUE 123

#### X VALUES WITH RANDOM ERROR

Ν

10

$$\begin{array}{c|c} \mathbf{MEAN} \ \mathbf{X} & \overline{x} = \frac{1}{N} \sum_{i=1}^{N} x_i \\ \hline \mathbf{122} & \end{array}$$

$$\left(x_i - \overline{x}\right)^2$$

ERROR IN X 
$$\sigma_x = \sqrt{\frac{1}{N-1} \sum_{i=1}^{N} (x_i - \overline{x})^2}$$

SO: 
$$X = (122 + / - 3)$$

**Errors.** All measurable quantities will be subject to *uncertainty*. If quantities x,y... are within a known range, we can use **upper and lower bounds** to determine the range of combined quantities.

e.g. 
$$x_{-} \leq x \leq x_{+}$$
  $y_{-} \leq y \leq y_{+}$ 

Therefore: 
$$x_{-}^{2}y_{-} \le x_{-}^{2}y \le x_{+}^{2}y_{+}$$
  $x_{-}^{2}/y_{+} < x_{-}^{2}/y_{-} < x_{+}^{2}/y_{-}$ 

Note the mixing of *upper and lower bounds* in the last example.

Example: 
$$1.23 \le x \le 4.56$$
,  $7.89 \le y \le 11.2$ 

$$z = \frac{\sqrt{y}}{x}$$

$$\frac{\sqrt{7.89}}{4.56} < z < \frac{\sqrt{11.2}}{1.23}$$

$$0.616 < z < 2.721$$

## Laws of Errors – but only if you think errors are normally distributed

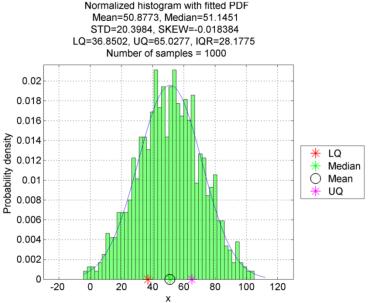
If errors are *normally distributed*, the 'Law of Errors' can be useful (although may result in an artificially tighter uncertainty than upper and lower bounds). Let f(x, y, z..) be a function of measureable quantities e.g.  $x = \overline{x} \pm \sigma_x$ .

$$f = \overline{f} \pm \sigma_f \text{ where } \overline{f} = f(\overline{x}, \overline{y}, \overline{z}...) : \qquad \sigma_f^2 = \left(\frac{\partial f}{\partial x}\sigma_x\right)^2 + \left(\frac{\partial f}{\partial y}\sigma_y\right)^2 + \left(\frac{\partial f}{\partial z}\sigma_z\right)^2 + ...$$

If 
$$f(x, y...) = kx^a y^b... \Rightarrow \left(\frac{\sigma_f}{f}\right)^2 = \left(\frac{a\sigma_x}{x}\right)^2 + \left(\frac{b\sigma_y}{y}\right)^2 + ...$$
 You add the (power weighted) squares of fractional errors.

If a quantity x is subject to random error and N independent measurements  $\{x_i\}$  are made, the *unbiased estimate* of the mean value of x is:  $\overline{x} = \frac{1}{N} \sum_{i=1}^{N} x_i$ . Since the mean value is used in the calculation of the *standard deviation*, the unbiased

estimate of the standard deviation in x (i.e. the 'error' in x) is:  $\sigma_x = \sqrt{\frac{1}{N-1} \sum_{i=1}^{N} (x_i - \overline{x})^2}$ . We can quote:  $x = \overline{x} \pm \sigma_x$ 



Example:

$$z = 3x^{2}y^{-\frac{1}{2}}, \quad x = 20 \pm 3, \quad y = 40 \pm 5$$

$$\therefore \left(\frac{\sigma_{z}}{\overline{z}}\right)^{2} = \left(\frac{2\sigma_{x}}{\overline{x}}\right)^{2} + \left(\frac{\frac{1}{2}\sigma_{y}}{\overline{y}}\right)^{2}$$

$$\overline{z} = 3 \times 20^{2} \times 40^{-\frac{1}{2}} = 189.7366...$$

$$\therefore \sigma_{z} = \overline{z}\sqrt{\left(\frac{2 \times 3}{20}\right)^{2} + \left(\frac{\frac{1}{2}5}{40}\right)^{2}} = 58.14...$$

$$\therefore z = (1.9 \pm 0.6) \times 10^{2}$$