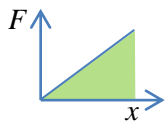
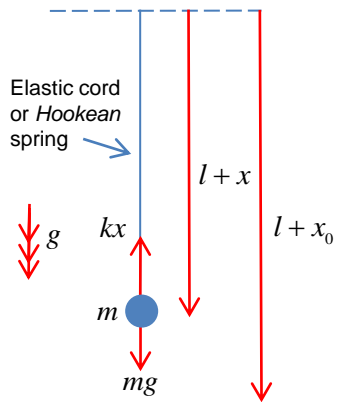


Hookean springs

If a spring or elastic cord obeys **Hooke's Law**, then the restoring force experienced is in direct proportion to the amount it is stretched x beyond its natural length l



$$F = kx = \lambda \frac{x}{l}$$

k is the spring constant
 λ is the elastic modulus

$$\lambda = kl$$

When a spring is stretched, the **work done** to achieve this is

$$W = \int_0^x F dx = \int_0^x kx dx = \frac{1}{2} kx^2 \quad \text{i.e. the area of the green triangle!}$$

The **potential energy** in a stretched spring is therefore

$$\frac{1}{2} kx^2$$

If the spring hangs in equilibrium $mg = kx_0 \Rightarrow x_0 = \frac{mg}{k}$

The equilibrium displacement from the hanging point of the mass is therefore $l + \frac{mg}{k}$

The total energy of the mass-spring system above is:

$$E = \frac{1}{2} m\dot{x}^2 + mg \left(l + \frac{mg}{k} - l - x \right) + \frac{1}{2} kx^2 = \frac{1}{2} m\dot{x}^2 + mg \left(\frac{mg}{k} - x \right) + \frac{1}{2} kx^2$$

$$E = \frac{1}{2} m\dot{x}^2 + mg \left(\frac{mg}{k} - x \right) + \frac{1}{2} kx^2$$

$$\dot{E} = m\dot{x}\ddot{x} - mg\dot{x} + kx\dot{x} \quad \leftarrow \text{differentiate with respect to time}$$

$$\dot{E} = m\dot{x} \left(\ddot{x} - g + \frac{kx}{m} \right)$$

Assume system is lossless

$$\therefore \dot{E} = 0$$

$$\Rightarrow \ddot{x} - g + \frac{kx}{m} = 0$$

$x = z + \frac{mg}{k}$ Define a new displacement, from the equilibrium position
 $\ddot{x} = \ddot{z}$

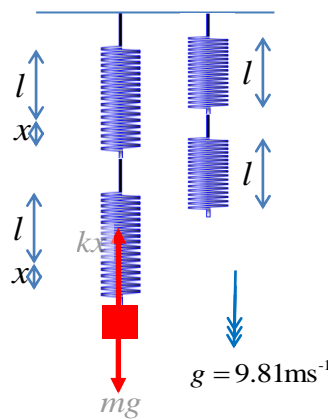
$$\ddot{z} - g + \frac{kx}{m} = 0$$

$$\Rightarrow \ddot{z} - g + \frac{k}{m} \left(z + \frac{mg}{k} \right) = 0$$

$$\therefore \ddot{z} = -\frac{k}{m} z$$

$\ddot{\theta} = -\left(\frac{2\pi}{T} \right)^2 \theta$ Compare to Simple Harmonic Motion (SHM)

Series springs – each stretches the same



$$kx = mg \quad \therefore x = \frac{mg}{k}$$



Robert Hooke
1635-1703
Born in Freshwater
Isle of Wight

Hence spring oscillations will have period

$$\left(\frac{2\pi}{T} \right)^2 = \frac{k}{m}$$

$$\therefore T = 2\pi \sqrt{\frac{m}{k}}$$

Note in this case, **Newton's Second Law** can also be used to derive the equation of motion in a fairly straightforward fashion. In this case it is the most efficient method!

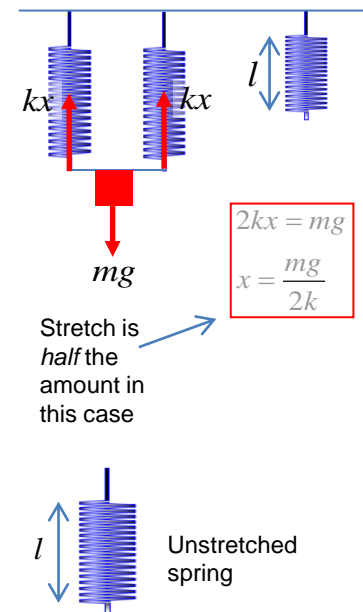
$$m\ddot{x} = mg - kx$$

$$x = z + \frac{mg}{k} \quad z \text{ is the displacement from equilibrium}$$

$$\therefore m\ddot{z} = mg - k \left(z + \frac{mg}{k} \right)$$

$$\ddot{z} = -\frac{k}{m} z$$

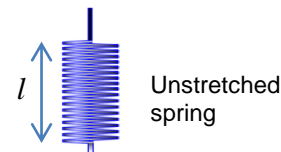
Parallel springs – load is shared



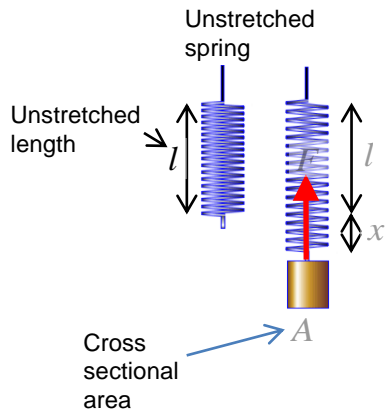
$$2kx = mg$$

$$x = \frac{mg}{2k}$$

Stretch is *half* the amount in this case



Stress and strain



$$\text{stress} = \frac{\text{force}}{\text{area}}$$

$$\sigma = \frac{F}{A}$$

$$\text{strain} = \frac{\text{extension}}{\text{original length}}$$

$$\epsilon = \frac{x}{l}$$

Young's Modulus

$$Y = \frac{\text{Stress}}{\text{Strain}} = \frac{\sigma}{\epsilon}$$

$$\therefore \sigma = Y\epsilon$$

Elastic strain energy per unit volume

$$U = \frac{E}{Al} = \frac{\frac{1}{2}kx^2}{Al}$$

$$U = \frac{1}{2} \frac{kx}{A} \times \frac{x}{l}$$

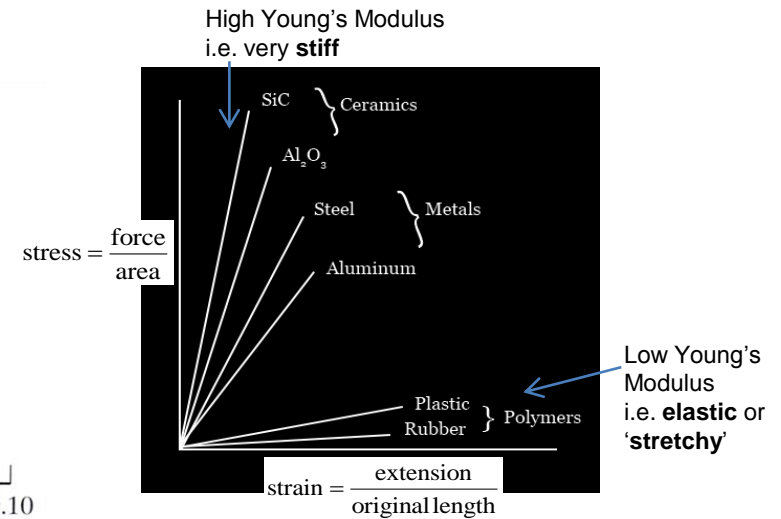
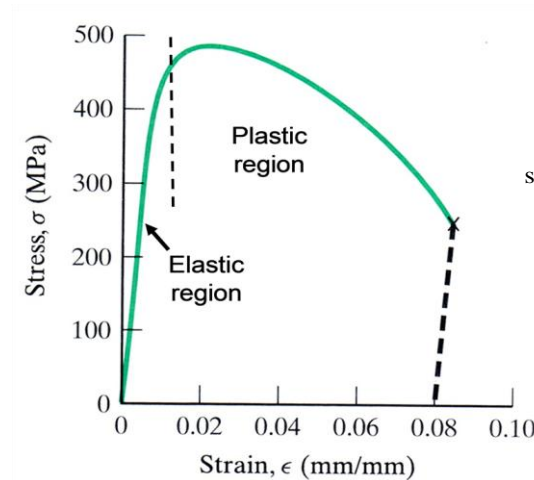
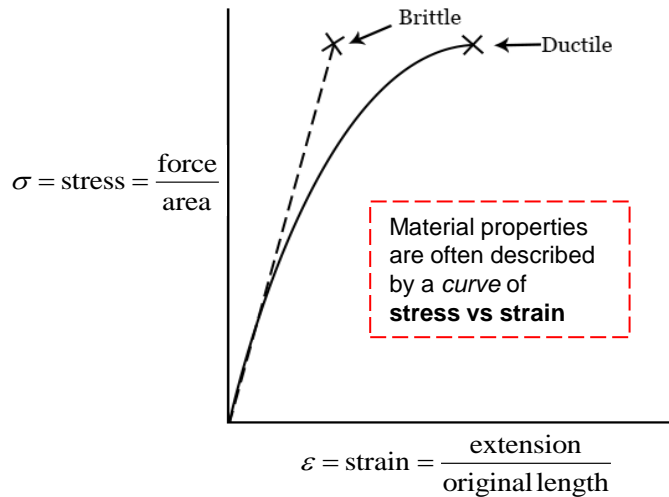
$$U = \frac{1}{2} \times \frac{\text{force}}{\text{area}} \times \frac{\text{extension}}{\text{original length}}$$

$$U = \frac{1}{2} \text{stress} \times \text{strain}$$

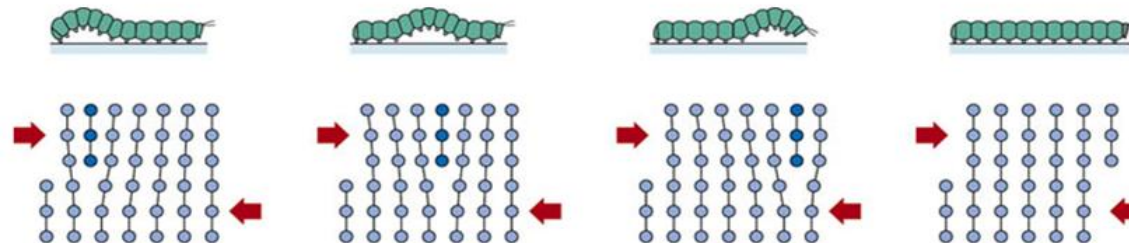
$$U = \frac{1}{2} Y \epsilon^2$$

The energy U stored by a system undergoing deformation, per unit volume. When the load is removed, strain energy is released as the system returns to its original shape.

$$\sigma = Y\epsilon$$



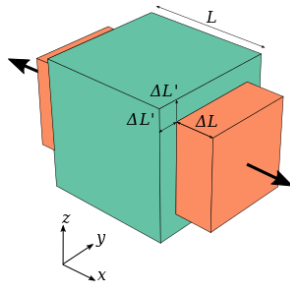
For small strains we often have a linear, *elastic* region. i.e. force is proportional to extension or stress/strain is a constant. The constant is called the **Young's Modulus**



Poisson's ratio

$$\nu = -\frac{\text{transverse strain change}}{\text{axial strain change}} \approx \frac{\Delta L'}{\Delta L}$$

i.e. most materials will shrink *transversely* as they are stretched. This is a *positive* Poisson ratio.



Young's Modulus

$$Y = \frac{\sigma}{\epsilon}$$

Stress

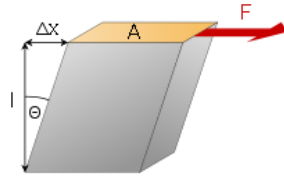
Strain

For isotropic materials

$$Y = 2G(1 + \nu)$$

Shear modulus

$$G = \frac{\text{shear stress}}{\text{shear strain}} = \frac{Fl}{A\Delta x}$$



Note fluids and gases *flow* rather than shear. So a fluid or gas will have a shear modulus of zero.

Speed of sound in elastic solids

$$c_p = \sqrt{\frac{K + \frac{4}{3}G}{\rho}} = \sqrt{\frac{Y(1-\nu)}{\rho(1+\nu)(1-2\nu)}}$$

$$c_s = \sqrt{\frac{G}{\rho}}$$

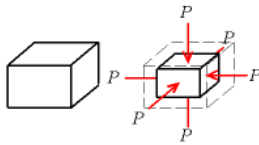
Pressure (P) waves

Shear (S) waves

Note speed of sound in air is about 330ms⁻¹ and 1480ms⁻¹ in water

Bulk modulus

$$K = -V \frac{dP}{dV} = \rho \frac{dP}{d\rho}$$



This is the *compressibility* of a material i.e. the ratio of a change in pressure *P* applied to the consequential fractional change in volume *V*

For *isotropic* materials (i.e. movement in any direction is the *same*, there is no particular direction where the material is weaker or stronger or more stretchy..)

$$K = \frac{Y}{3(1-2\nu)}$$

Typical elastic moduli for materials

(assumed to be isotropic)

$$K = \frac{Y}{3(1-2\nu)} \text{ used where data unavailable}$$

Material	Young's modulus <i>Y</i> /GPa	Poisson ratio ν	Shear modulus <i>G</i> /GPa	Bulk modulus <i>K</i> /GPa	Density ρ /kgm ⁻³	Speed* of sound <i>c_p</i> /ms ⁻¹
Rubber	0.01	0.5	0.0006	1	801	1,120
Steel	200	0.3	79.3	160	7800	5,840
Copper	117	0.33	44.7	123	8960	4,510
Plastic	0.5-3	0.3-0.5	0.1	2.9	930	1,810
Concrete	30	0.1-0.2	21	14.3	2400	4,200
Diamond	1050-1210	0.07	478	443	3510	17,540
Wood	11	0.2-0.7	13	36.7	600-900	8,490
Glass	50-90	0.18-0.3	26.2	35-55	2500	5,560