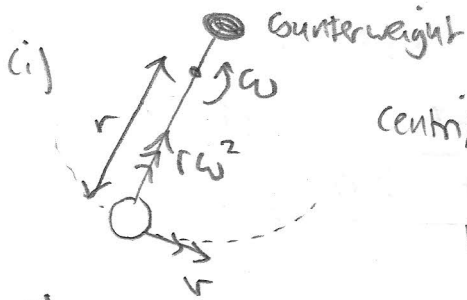


NON-UNIFORM CIRCULAR MOTION

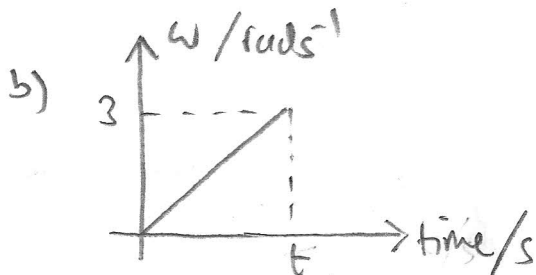


Centrifuge at NASA Ames

$$r\omega^2 = 12.5g$$

$$\omega = \sqrt{\frac{12.5g}{r}} = \frac{60}{2\pi} \sqrt{\frac{12.5 \times 9.81}{8.8}} \text{ RPM}$$

$$= \boxed{35.6 \text{ RPM}}$$



Tangential acceleration is $r\dot{\omega} = 0.5g$

$$\dot{\omega} = \frac{3}{t} \quad \text{and} \quad \dot{\omega} = \frac{0.5g}{r}$$

$$\therefore \frac{3}{t} = \frac{0.5g}{8.8}$$

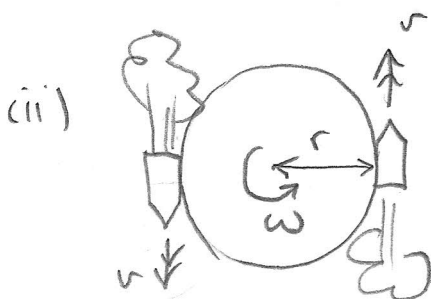
$$\therefore \frac{3 \times 8.8}{0.5 \times 9.81} = t$$

$$\therefore \boxed{5.38 \text{ s} = t}$$

c) $\theta = \int \omega dt$ i.e. area under $\omega(t)$ graph.

$$\text{So } \theta = \frac{1}{2}(3)(t) = \frac{1}{2}(3)(5.38) = 8.07 \text{ radians}$$

$$= \boxed{462.6^\circ} \quad (1.28 \text{ rotations})$$



$$r = 0.33 \text{ m}$$



$$a) \omega = \frac{600 \times 2\pi}{60 \times 5} \text{ rad s}^{-2}$$

$$= 4\pi \text{ rad s}^{-2}$$

$$\approx \boxed{12.6 \text{ rad s}^{-2}}$$

$$b) \text{ At } 5.0 \text{ s, } v = r\omega = 0.33 \times \frac{600 \times 2\pi}{60}$$

$$= \boxed{20.7 \text{ m/s}}$$

c) Total angle of turn is $\theta = \int_0^7 \omega dt =$

Since $\omega = \text{constant}$, $\theta = \frac{1}{2}(4\pi) \times (7)^2$
 $\Rightarrow \theta = \frac{1}{2}\omega t^2$
 $= 307.9 \text{ radians or } 17640^\circ$
 $= \boxed{49 \text{ rotations}}$

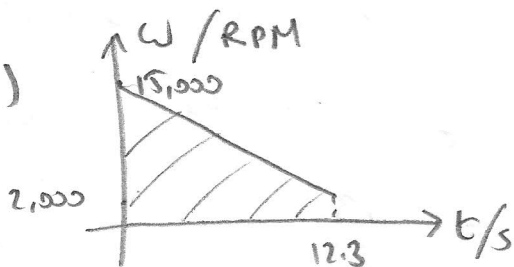
{ In our case, since $\dot{\omega} = 4\pi \text{ rads}^{-2}$

$$\theta = \frac{1}{2}(4\pi)t^2$$

$$\frac{\theta}{2\pi} = t^2$$

So $\boxed{\# \text{ rotations} = t^2}$

iii)



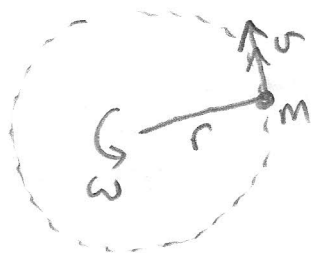
Total angle of turn is area under ω, t graph

$$= \frac{1}{2}(12.3)(15,000 + 2,000) \times \frac{2\pi}{60} \text{ (rad)}$$

$$= 1.09 \times 10^4 \text{ rad}$$

$$= \boxed{627,300^\circ}$$

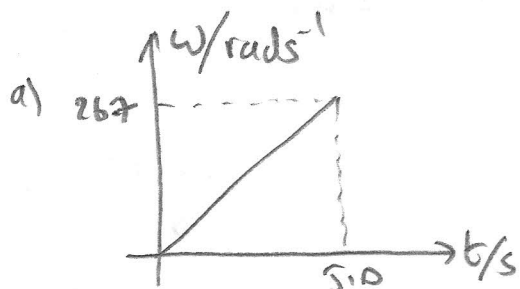
iv)



radius of ball $r = 0.75 \text{ m}$, $m = 0.20 \text{ kg}$

$$v = r\omega \quad \therefore \omega = \frac{v}{r}$$

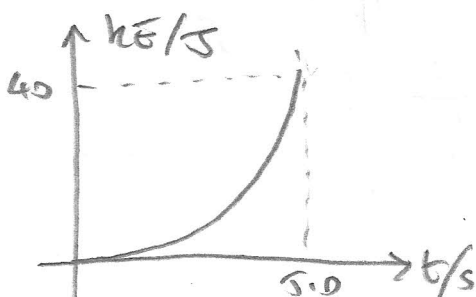
when $v = 20 \text{ m/s}$, $\omega = \frac{20}{0.75} = \boxed{26.7 \text{ rads}^{-1}}$



b)

$$KE = \frac{1}{2}mv^2$$

$$KE = \frac{1}{2}mr^2\omega^2$$



At 5.0s, $KE = \frac{1}{2}(0.2)(0.75)^2(26.7)^2$
 $= \boxed{40 \text{ J}}$

2)

c) Angle of turn $\theta = \frac{1}{2} \left(\frac{20}{0.75} \right) (5)$

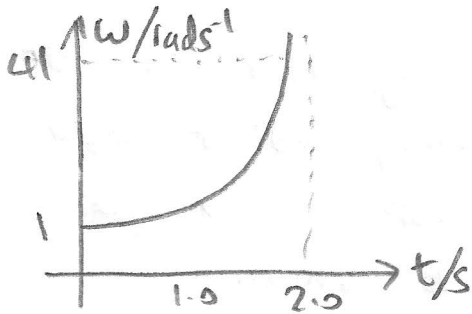
\approx area under (t, ω) graph = 66.7 radians

= 10.6 rotations.

So

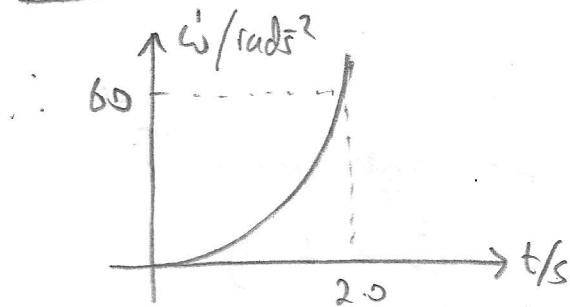
$\boxed{10 \text{ complete rotations}}$

(v) a) $\boxed{\omega = 1 + 5t^3}$ for ice-skater.



when $t = 2.0\text{s}$, $\omega = 41 \text{ rad/s}$

$\boxed{\dot{\omega} = 15t^2}$ ($\approx \frac{d\omega}{dt}$)

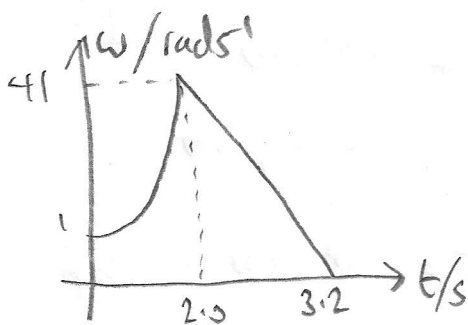


b) $\theta = \int_0^2 \omega dt = \left[t + \frac{5}{4} t^4 \right]_0^2 = 2 + \left(\frac{5}{4} \right) (16) = \boxed{22 \text{ rad}}$

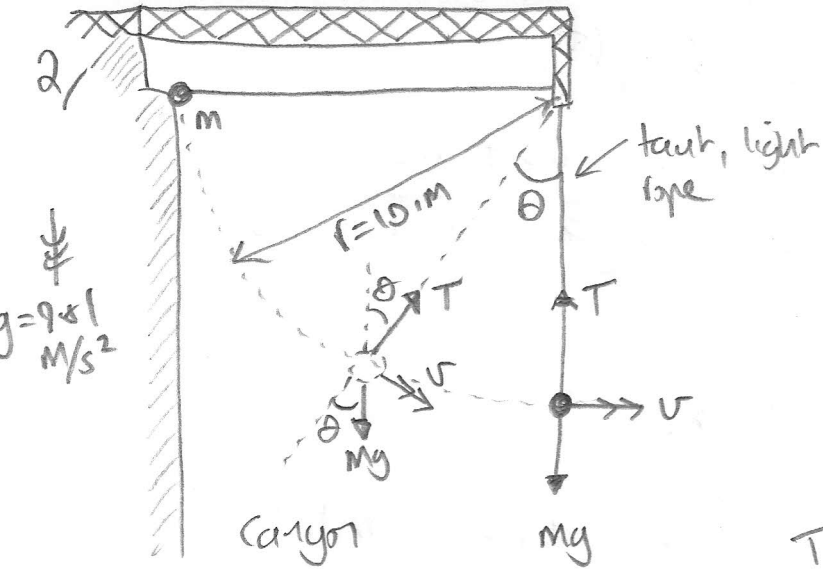
\approx 3.50 rotations. (She lands backwards!)

c) After 2.0s she brakes at constant angular acceleration $\dot{\omega}$

At 2.0s, $\omega = 41 \text{ rad/s}$



$\dot{\omega} = -\frac{41}{1.2} = \boxed{-34.2 \text{ rad/s}^2}$



Newton II radially inward

$$\frac{mv^2}{r} = T - mg \cos \theta$$

$$T = mg \cos \theta + \frac{mv^2}{r}$$

T is clearly largest when $\theta = 0$ (i.e. vertical) and v largest (when max GPE $\rightarrow \frac{1}{2}mv^2$)
 \hookrightarrow Also vertical.

So max rope tension T is when $\theta = 0$; $\frac{1}{2}mv^2 = mgr$

$$\Rightarrow \frac{mv^2}{r} = 2mg \quad \therefore \text{max } T \text{ is } \boxed{3mg}$$

If $m = 85 \text{ kg}$, $(r = 10.0 \text{ m})$

$$3mg = 3 \times 85 \times 9.81 = \boxed{2501.6 \text{ N}}$$

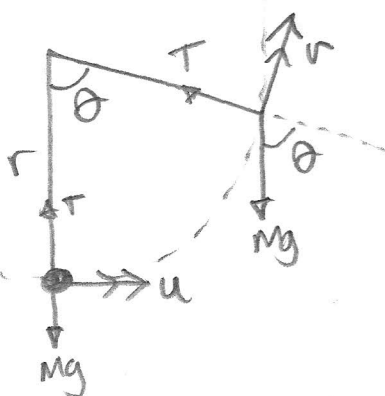
\uparrow
 Doesn't factor in max T

So if max tension is 2500N, it might be nice for Sophie's dad to try the swing!

3/

$$g = 9.81 \text{ m/s}^2$$

"Swingball"



Newton II radially inward:

$$\frac{mv^2}{r} = T - mg \cos \theta$$

$$\therefore T = mg \cos \theta + \frac{mv^2}{r}$$

Conservation of energy:

$$\frac{1}{2}mv^2 = \frac{1}{2}mv^2 + mgr(1 - \cos \theta)$$

$$\therefore \frac{mv^2}{r} = \frac{mv^2}{r} - 2mg(1 - \cos \theta)$$

(4)

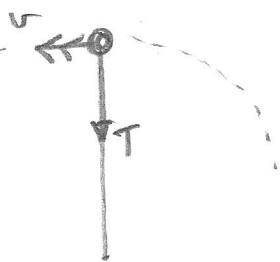
$$\therefore T = mg \cos \theta + \frac{mu^2}{r} - 2mg(1 - \cos \theta)$$

$$\therefore T = 3mg \cos \theta - 2mg + \frac{mu^2}{r}$$

$$\therefore \boxed{T = mg(3 \cos \theta - 2) + \frac{mu^2}{r}}$$

New ball spins in a vertical circle if $T > 0 \quad \forall \theta$
in range $0 \leq \theta \leq 2\pi$

Smallest T is when $\cos \theta = -1$ i.e. $\theta = \pi$ (180°)



$$\text{i.e. } mg(-3 - 2) + \frac{mu^2}{r} > 0$$

for a full circle with taut rope.

$$\therefore \frac{u^2}{r} > 5g$$

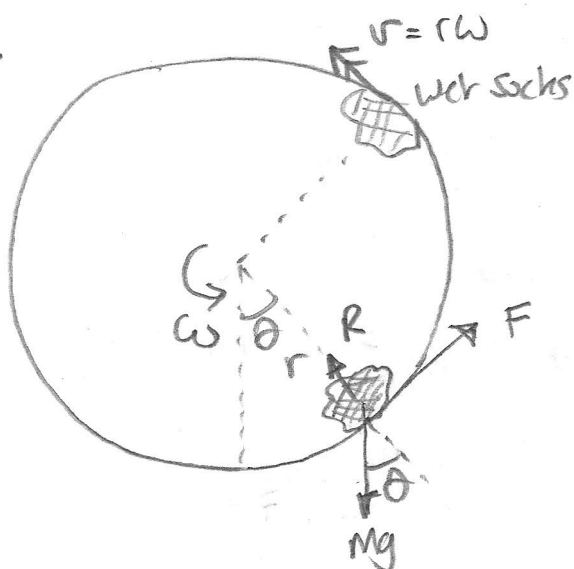
$$\therefore u^2 > 5gr$$

$$\therefore \boxed{u > \sqrt{5gr}}$$

So Boris' impulse mu must exceed:

$$\frac{58.0}{1000} \times \sqrt{5 \times 9.81 \times 1.40} = \boxed{0.48 \text{ kg m/s}}$$

4/



Newton II radially inwards

$$Mr\omega^2 = R - mg \cos \theta$$

$$\therefore \boxed{R = Mr\omega^2 + mg \cos \theta}$$

Newton II tangentially, assuming no slip of wet socks

$$0 = F - mg \sin \theta$$

$$\therefore \boxed{F = mg \sin \theta}$$

Also $\boxed{F \leq MR}$

Assume $\omega = \text{constant}$

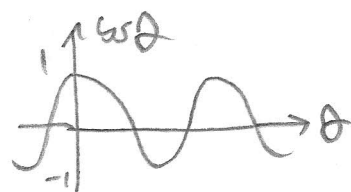
5

(i) To not lose contact with the drum, $R > 0$

$$\therefore \text{since } R = mr\omega^2 + mg\cos\theta$$

$$\Rightarrow r\omega^2 + g\cos\theta > 0$$

Now $-1 < \cos\theta < 1$



So if $r\omega^2 + g\cos\theta > 0$ when $\cos\theta = -1$ (i.e. $\theta = 180^\circ$) then it is true $\forall \theta$.

$\therefore r\omega^2 - g > 0$ for socks to not lose contact

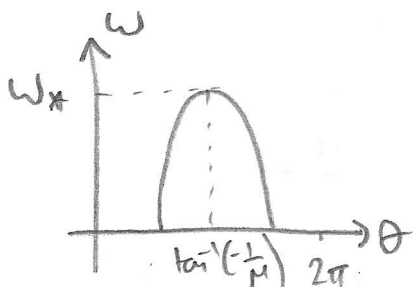
$$\Rightarrow \boxed{\omega > \sqrt{\frac{g}{r}}}$$

(ii) For no slip $F \leq \mu R$

$$\therefore mg\sin\theta \leq \mu (mr\omega^2 + mg\cos\theta)$$

$$\therefore \frac{g\sin\theta}{\mu r} \leq \omega^2 + \frac{g\cos\theta}{r}$$

$$\Rightarrow \boxed{\omega \geq \sqrt{\frac{g}{\mu r} (\sin\theta - \mu\cos\theta)}}$$



For never any slip, $\omega > \omega_*$

$$\omega = \omega_* \text{ when } \frac{d\omega}{d\theta} = 0$$

$$\frac{d\omega}{d\theta} = \sqrt{\frac{g}{\mu r}} \frac{1}{2} (\sin\theta - \mu\cos\theta)^{-\frac{1}{2}} (\cos\theta + \mu\sin\theta)$$

$$\text{So } \frac{d\omega}{d\theta} = 0 \text{ when } \cos\theta = -\mu\sin\theta \Rightarrow \boxed{\tan\theta = -\frac{1}{\mu}}$$

$$\text{So } \omega_* = \sqrt{\frac{g}{\mu r} (\sin\theta + \mu^2\sin\theta)^{\frac{1}{2}}}$$

$$\begin{aligned} \text{Now } \cos^2\theta &= \mu^2\sin^2\theta \\ 1 - \sin^2\theta &= \mu^2\sin^2\theta \\ 1 &= (1 + \mu^2)\sin^2\theta \end{aligned}$$

$$\text{so } \sin^2 \theta = \frac{1}{1+\mu^2} \quad \therefore \sqrt{\sin \theta} = (1+\mu^2)^{-\frac{1}{4}}$$

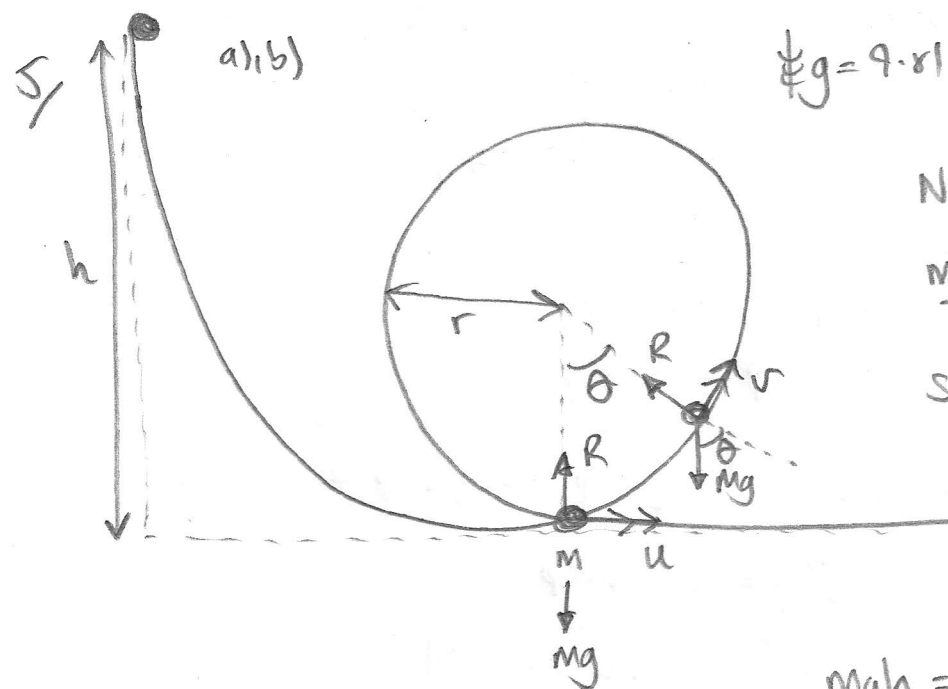
$$\therefore \omega_{*} = \sqrt{\frac{g}{\mu r}} (1+\mu^2)^{\frac{1}{2}} \left(\frac{1}{1+\mu^2} \right)^{-\frac{1}{4}}$$

$$\therefore \text{for no slip } \boxed{\omega > \sqrt{\frac{g}{\mu r}} (1+\mu^2)^{\frac{1}{4}}}$$

(iii) let $r = 0.3M$, $\mu = \frac{1}{\sqrt{3}}$

$$\therefore \sqrt{\frac{g}{r}} = \sqrt{\frac{9.81}{0.3}} = 5.72 \text{ rads}^{-1} = \boxed{54.6 \text{ RPM}}$$

$$\begin{aligned} \therefore \sqrt{\frac{g}{\mu r}} (1+\mu^2)^{\frac{1}{4}} &= \sqrt{\frac{9.81}{0.3}} \sqrt{3} \left(1 + \frac{1}{3}\right)^{\frac{1}{4}} \\ &= 8.09 \text{ rads}^{-1} = \boxed{77.2 \text{ RPM}} \end{aligned}$$



$$\ddagger g = 9.81 \text{ N/kg}$$

Newton II radially inward:

$$\frac{mv^2}{r} = R - mg \cos \theta$$

$$\text{so } \boxed{R = \frac{mv^2}{r} + mg \cos \theta}$$

Now by conservation of energy:

$$mgh = \frac{1}{2}mu^2 = \frac{1}{2}mv^2 + mgr(1 - \cos \theta)$$

$$\therefore \frac{mv^2}{r} = \frac{2mgh}{r} - 2mg(1 - \cos \theta) \Rightarrow \text{Also } \downarrow 2gh = v^2 + 2gr(1 - \cos \theta)$$

$$\therefore \boxed{R = \frac{2mgh}{r} - 2mg + 3mg \cos \theta} \text{ and } \boxed{v = \sqrt{2gh \left(1 - \frac{r}{h}(1 - \cos \theta)\right)^{\frac{1}{2}}}$$

c) Car is in contact with the loop if $R > 0$

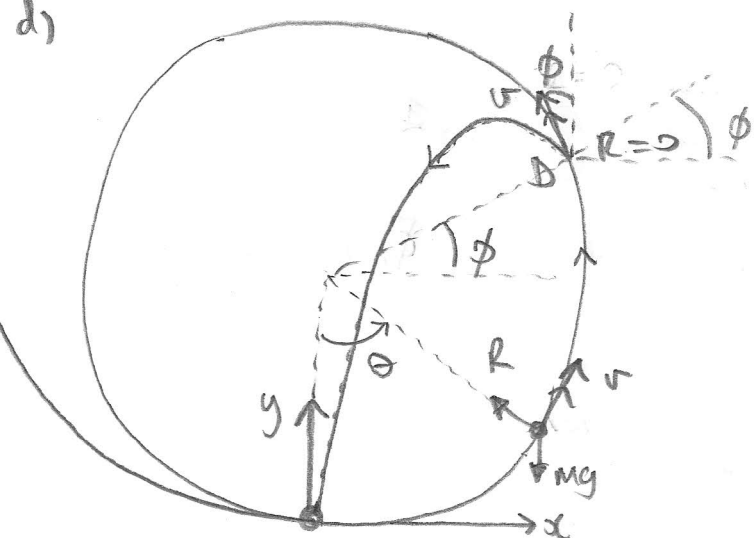
$$\frac{R}{mg} = 3\cos\theta - 2 + \frac{2h}{r}$$

$$\Rightarrow 3\cos\theta - 2 + \frac{2h}{r} > 0 \quad \forall \theta$$

$$1 < \cos\theta < 1 \quad \text{so} \quad -3 - 2 + \frac{2h}{r} > 0 \quad \text{for this to be true}$$

$$\Rightarrow \boxed{h > \frac{5}{2}r}$$

d)



$$R=0 \text{ when } 3\cos\theta - 2 + \frac{2h}{r} = 0$$

$$\Rightarrow \boxed{\cos\theta = \frac{2}{3}(1 - \frac{h}{r})}$$

$$\text{Let } k = \frac{h}{r} \Rightarrow \cos\theta = \frac{2}{3}(1 - k)$$

(we are trying to prove (0,0) is on the projectile path trajectory when $k = \frac{7}{4}$)

Projectile path:
($t=0$ at point of departure 0)

$$x = r\cos\phi - v\sin\phi t$$

$$y = r + r\sin\phi + v\cos\phi t - \frac{1}{2}gt^2$$

$$\text{Now } \theta = \frac{\pi}{2} + \phi$$

$$\text{So } \cos\theta = \cos\frac{\pi}{2}\cos\phi - \sin\frac{\pi}{2}\sin\phi = -\sin\phi$$

$$\therefore \boxed{\sin\phi = \frac{2}{3}(k-1)}$$

$$\cos^2\phi = 1 - \sin^2\phi$$

$$\therefore \boxed{\cos^2\phi = 1 - \frac{4}{9}(k-1)^2}$$

$$\text{Now at } (0,0) \quad r\cos\phi = v\sin\phi t \Rightarrow t = \frac{r\cos\phi}{v\sin\phi}$$

$$\therefore \text{using } y=0: \quad 0 = r(1 + \sin\phi) + \frac{v\cos\phi r\cos\phi}{v\sin\phi} - \frac{1}{2}g \frac{r^2 \cos^2\phi}{v^2 \sin^2\phi}$$

8

$$\therefore 0 = r \left(1 + \frac{2}{3}(k-1) \right) + r \frac{\left(1 - \frac{4}{9}(k-1)^2 \right)}{\frac{2}{3}(k-1)} - \frac{\frac{1}{2}gr^2}{v^2} \frac{\left(1 - \frac{4}{9}(k-1)^2 \right)}{\frac{4}{9}(k-1)^2}$$

Now $mgh = \frac{1}{2}mv^2 + mgr(1 - \cos\theta)$ (conservation of energy)

$$\Rightarrow v^2 = 2gh - 2gr(1 - \cos\theta)$$

So if $\cos\theta = \frac{2}{3}\left(1 - \frac{h}{r}\right)$

$$\Rightarrow \text{at } D: v^2 = 2gh - 2gr\left(1 - \frac{2}{3} + \frac{2h}{3r}\right)$$

$$v^2 = 2gh - 2gr + \frac{4gr}{3} - \frac{4gh}{3}$$

$$v^2 = \frac{2}{3}gh - \frac{2gr}{3}$$

$$\boxed{v^2 = \frac{2}{3}g(h-r)}$$

so $\frac{gr}{v^2} = \frac{gr}{\frac{2}{3}gr\left(\frac{h}{r} - 1\right)} = \frac{3}{2(k-1)}$

$$\therefore 0 = 1 + \frac{2}{3}(k-1) + \frac{1 - \frac{4}{9}(k-1)^2}{\frac{2}{3}(k-1)} - \frac{\frac{3}{4} \frac{1}{k-1} \left(1 - \frac{4}{9}(k-1)^2 \right)}{\frac{4}{9}(k-1)^2}$$

let $z = \frac{2}{3}(k-1)$

$$\therefore 0 = 1 + z + \frac{1 - z^2}{z} - \frac{1}{2} \frac{1}{z} \frac{1 - z^2}{z^2}$$

$$\therefore 0 = 2z^3 + 2z^4 + 2z^2(1 - z^2) - 1 + z^2 \quad (+2z^3)$$

$$\therefore 0 = 2z^3 + 2z^4 + 2z^2 - 2z^4 - 1 + z^2$$

$$\therefore 0 = 2z^3 + 3z^2 - 1 \quad z = -1 \text{ is a factor}$$

$$\text{so } 2z^3 + 3z^2 - 1 = (z+1)(2z^2 + az + b)$$

$$= 2z^3 + (2+a)z^2 + z(a+b) + b$$

$a=1, b=-1$

$$\therefore 0 = (z+1)(2z^2 + z - 1) = (z+1)(2z-1)(z+1)$$

$$\therefore 0 = (2z-1)(z+1)^2$$

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$$\therefore \text{if } (z+1)^2(2z-1) = 0 \Rightarrow z = -1 \text{ or } z = \frac{1}{2}$$

$$z = \frac{2}{3}(k-1) \quad \therefore \boxed{k = \frac{3z}{2} + 1}$$

if $z = -1$, $k = -\frac{1}{2}$
which has no physical significance
since $k = \frac{h}{r}$

So for our problem: $\boxed{z = \frac{1}{2}} \Rightarrow k = \frac{3}{4} + 1 = \boxed{\frac{7}{4}}$ as required

Now $\sin\phi = \frac{2}{3}(k-1)$ so when $z = \frac{1}{2}$, $\boxed{\phi = 30^\circ \text{ or } \frac{\pi}{6}}$

e) if projectile phase (from D to (0,0))

$$x = r \cos\phi - v \sin\phi t$$

so $x = 0$ when $\boxed{t = \frac{r \cos\phi}{v \sin\phi}}$

$\phi = \frac{\pi}{6}$ so $t = \frac{r}{v} \frac{\cos 30^\circ}{\sin 30^\circ} = \frac{r}{v} \frac{\sqrt{3}/2}{1/2} = \frac{r}{v} \sqrt{3}$

Now $v^2 = \frac{2}{3}g(h-r)$ so if $h = \frac{7}{4}r$

$$\Rightarrow v^2 = \frac{2}{3}gr \left(\frac{7}{4} - 1\right) = \frac{1}{2}gr$$

$$\therefore \boxed{v = \sqrt{\frac{gr}{2}}}$$

$$\therefore t = \frac{r\sqrt{3}}{\sqrt{gr}/\sqrt{2}} = \boxed{\sqrt{\frac{r}{g}} \sqrt{6}}$$

Now in phase (0,0) \rightarrow D in contact with track:

$$v = \sqrt{2gh} \left(1 - \frac{r}{h}(1 - \cos\theta)\right)^{\frac{1}{2}}$$

(b)

Now $v = r\dot{\theta}$

So $\dot{\theta} = \sqrt{\frac{2gh}{r}} \left(1 - \frac{r}{h}(1 - \cos\theta)\right)^{\frac{1}{2}}$

$\frac{h}{r} = \frac{7}{4}$ So $\dot{\theta} = \sqrt{\frac{2g}{r}} \frac{7}{4} \left(1 - \frac{4}{7}(1 - \cos\theta)\right)^{\frac{1}{2}}$

$$\therefore \int_0^{\frac{\pi}{2} + \frac{\pi}{6}} \frac{d\theta}{1 - \frac{4}{7} + \frac{4}{7}\cos\theta} = \int_0^t dt \times \sqrt{\frac{g}{r}} \sqrt{\frac{7}{2}}$$

$$\int_0^{\frac{2\pi}{3}} \frac{7d\theta}{3 + 4\cos\theta} = t \sqrt{\frac{g}{r}} \sqrt{\frac{7}{2}}$$

Now $\int \frac{7d\theta}{3 + 4\cos\theta} = 2\sqrt{7} \operatorname{tanh}^{-1}\left(\frac{1}{\sqrt{7}} \tan\left(\frac{\theta}{2}\right)\right)$ (Wolfram Alpha!)

$$\tan\left(\frac{2\pi}{3} \cdot \frac{1}{2}\right) = \tan \frac{\pi}{3} = \sqrt{3}$$

So $\int_0^{\frac{2\pi}{3}} \frac{7d\theta}{3 + 4\cos\theta} = 2\sqrt{7} \operatorname{tanh}^{-1}\left(\frac{\sqrt{3}}{\sqrt{7}}\right)$

Now $\operatorname{tanh}^{-1} x = \frac{1}{2} \ln\left(\frac{1+x}{1-x}\right)$ so $\operatorname{tanh}^{-1}\left(\frac{\sqrt{3}}{\sqrt{7}}\right)$

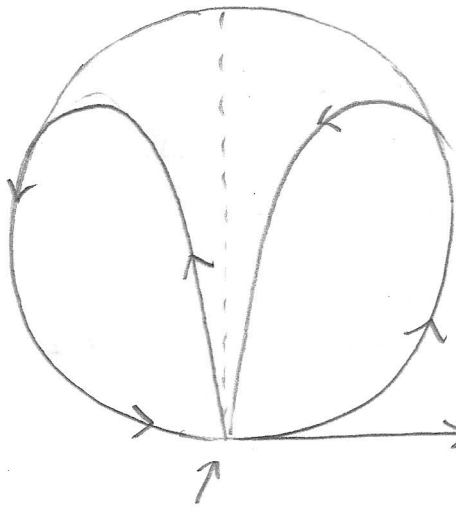
$$= \frac{1}{2} \ln\left(\frac{1 + \frac{\sqrt{3}}{\sqrt{7}}}{1 - \frac{\sqrt{3}}{\sqrt{7}}}\right) = \frac{1}{2} \ln\left(\frac{\sqrt{7} + \sqrt{3}}{\sqrt{7} - \sqrt{3}}\right)$$

$$\therefore t \sqrt{\frac{g}{r}} \frac{\sqrt{7}}{\sqrt{2}} = \sqrt{7} \ln\left(\frac{\sqrt{7} + \sqrt{3}}{\sqrt{7} - \sqrt{3}}\right)$$

$$\therefore t = \sqrt{\frac{r}{g}} \sqrt{2} \ln\left(\frac{\sqrt{7} + \sqrt{3}}{\sqrt{7} - \sqrt{3}}\right)$$

$$t \approx \sqrt{\frac{r}{g}} \times 2.216$$

Now by symmetry, if bounce (elastic) occurs at (op)



Assume special hoppers / shuttles in track here to allow entry, exit and elastic bounce!

It should take a further

$$\sqrt{\frac{r}{g}} \left(\sqrt{6} + \sqrt{2} \ln \left(\frac{\sqrt{7} + \sqrt{3}}{\sqrt{7} - \sqrt{3}} \right) \right)$$

seconds before exiting the loop the loop at speed

$$u = \sqrt{2gh}$$

(ie the speed it entered)

$$h = \frac{7}{4}r \quad \text{so} \quad u = \sqrt{2g \frac{7}{4}r}$$

$$u = \sqrt{\frac{7}{2}gr}$$

So total time inside circular track is

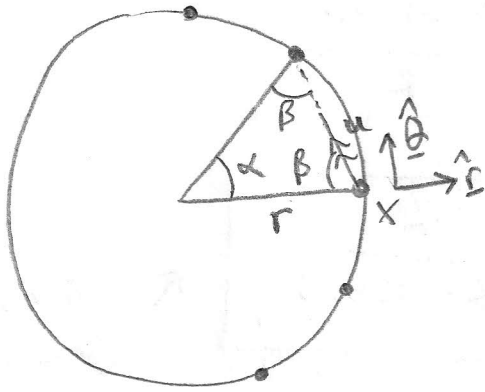
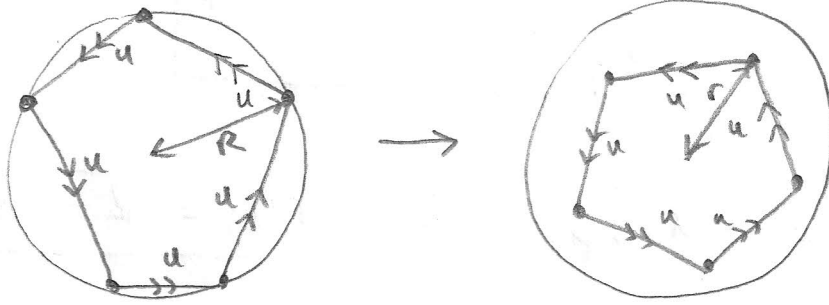
$$t = \sqrt{\frac{r}{g}} \left(2\sqrt{6} + 2\sqrt{2} \ln \left(\frac{\sqrt{7} + \sqrt{3}}{\sqrt{7} - \sqrt{3}} \right) \right)$$

$$\approx 9.331 \sqrt{\frac{r}{g}}$$

6/

The snails will preserve the N-gon shape, but the N-gon will rotate and shrink over time.

eg



$$\alpha = \frac{2\pi}{N} \quad \beta = \frac{\pi - \alpha}{2} \Rightarrow \boxed{\beta = \frac{\pi}{2} - \frac{\alpha}{2}}$$

Consider a polar coordinate system for snail X. ($t=0, \theta=0, r=R$).

$$\text{velocity } \underline{v} = \dot{r} \underline{\hat{r}} + r \dot{\theta} \underline{\hat{\theta}}$$

$$\text{Now } \boxed{\dot{r} = -u \cos \beta} \quad \text{and} \quad \boxed{r \dot{\theta} = u \sin \beta}$$

$$\text{Now } \frac{\dot{r}}{\dot{\theta}} = \frac{dr/dt}{d\theta/dt} = \frac{dr}{d\theta}$$

$$\frac{\dot{r}}{\dot{\theta}} = \frac{-u \cos \beta}{u \sin \beta / r} = -r \cot \beta$$

$$\therefore \frac{dr}{d\theta} = -r \cot \beta \Rightarrow \int_{R}^r \frac{1}{r} dr = -\cot \beta \int_0^{\theta} d\theta$$

$$\Rightarrow \left[\ln r \right]_R^r = -\cot \beta \theta$$

$$\Rightarrow \ln\left(\frac{r}{R}\right) = -\theta \cot \beta$$

$$\Rightarrow \boxed{r = R e^{-\theta \cot \beta}}$$

For other snails, starting at $\theta_n = (n-1) \times \frac{2\pi}{N}$

$$r_n(\theta) = R e^{-(\theta - \theta_n) \cot \beta}$$

Now $\dot{r} = -u \cos \beta \quad \therefore \quad \boxed{r(t) = R - ut \cos \beta}$

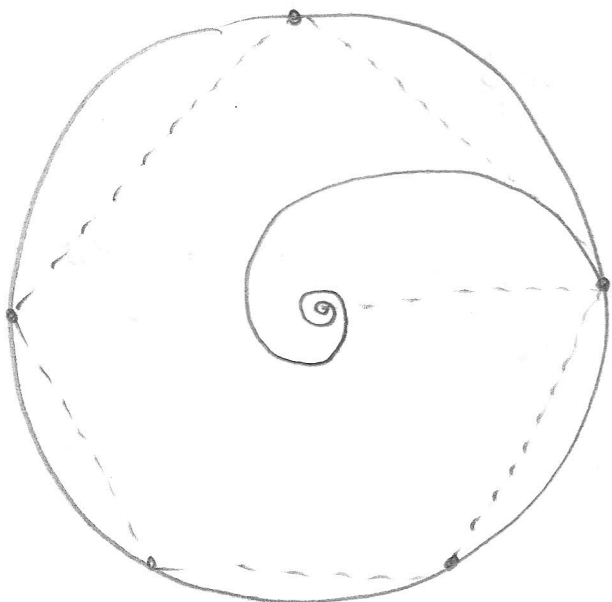
So snail $\ln\left(\frac{r}{R}\right) = -\theta \cot \beta$

$$\Rightarrow \theta(t) = -\frac{1}{\cot \beta} \ln\left(\frac{R - ut \cos \beta}{R}\right)$$

$$\Rightarrow \boxed{\theta(t) = \tan \beta \ln\left(\frac{R}{R - ut \cos \beta}\right)} \quad \leftarrow \text{add } \theta_n \text{ for snail } n.$$

It takes the snail T seconds to reach (0,0)

where $0 = R - uT \cos \beta \quad \Rightarrow \quad \boxed{T = \frac{R}{u \cos \beta}}$



Extra: what is the acceleration of the snail?

$$\underline{a} = (\ddot{r} - r\dot{\theta}^2) \hat{r} + (r\ddot{\theta} + 2\dot{r}\dot{\theta}) \hat{\theta}$$

$$\dot{r} = -u \cos \beta, \quad r\dot{\theta} = u \sin \beta$$

$$\text{so } \ddot{r} = 0 \quad \Rightarrow \quad \dot{\theta}^2 = \frac{u^2 \sin^2 \beta}{r^2}$$

$$\dot{\theta} = -\tan \beta \frac{R}{R - ut \cos \beta} \quad (-u \cos \beta) / R$$

$$\Rightarrow \boxed{\dot{\theta} = \frac{u \sin \beta}{R - ut \cos \beta}}$$

$$i. \quad \underline{a} = - \frac{ru^2 \sin^2 \beta \hat{r}}{r^2} + \left(r\ddot{\theta} - 2u \cos \beta \frac{u \sin \beta}{R - ut \cos \beta} \right) \hat{\theta}$$

$$\dot{\theta} = \frac{-Ru \sin \beta}{(R - ut \cos \beta)^2} (-u \cos \beta)$$

$$\ddot{\theta} = \frac{Ru^2 \sin \beta \cos \beta}{(R - ut \cos \beta)^2} = \frac{u^2 \sin \beta \cos \beta}{r^2}$$

$$So \quad \underline{a} = - \frac{u^2 \sin^2 \beta \hat{r}}{r} + \left(\frac{u^2 \sin \beta \cos \beta}{r} - \frac{2u^2 \times \cos \beta \sin \beta}{r} \right) \hat{\theta}$$

$$\underline{a} = - \frac{u^2 \sin^2 \beta \hat{r}}{r} - \frac{u^2}{r} \sin \beta \cos \beta \hat{\theta}$$

where $r = R - ut \cos \beta$.

$$So \quad \underline{a} = - \frac{u^2}{r} \sin \beta \left(\sin \beta \hat{r} + \cos \beta \hat{\theta} \right)$$

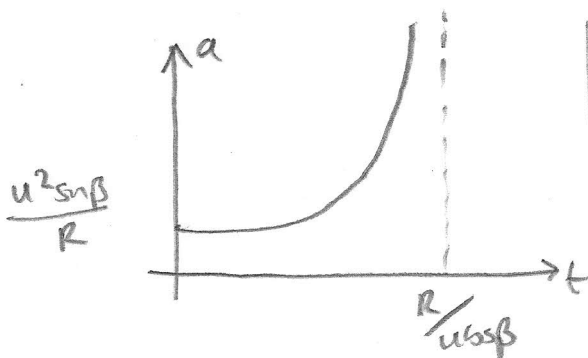
So the magnitude of acceleration $a = |\underline{a}|$

$$is: \quad a = \frac{u^2}{r} \sin \beta$$

($\sin \beta$ will be the)

$$Since \quad \left| \sin \beta \hat{r} + \cos \beta \hat{\theta} \right|$$

$$= \sqrt{\sin^2 \beta + \cos^2 \beta} = 1.$$



$$a(t) = \frac{u^2 \sin \beta}{R - ut \cos \beta}$$

$$\beta = \frac{\pi}{2} - \frac{\pi}{N}$$