PHYSICS USEFUL DATA AND FORMULAE

JP MP VBk version

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The Cosmos is all that is or ever was or ever will be.

In the last few millennia we have made the most astonishing and unexpected discoveries about the Cosmos and our place within it, explorations that are exhilarating to consider. They remind us that humans have evolved to wonder, that understanding is a joy, that knowledge is prerequisite to survival.

I believe our future depends on how well we know this Cosmos in which we float like a mote of dust in the morning sky.



Carl Sagan (1934-1996) *Cosmos* pp20

| 20,000 BC | 5,0 | 000 BC | 3000 B | C 200 | 00 BC | 3000 - 300 BC |
|-----------------------|-------------------------|------------------------|-------------------|----------|---------|---------------|
| Ishango Bor Africa | ne Mega | lithic structur | res Babylon | ian Hind | veda | Ancient Egypt |
| 520BC | 500BC | | 384-322BC | 2 | 200AD | 1564-1642 |
| Jainism | P A Old Testament | armenides naxagoras | Aris Aristotle | starchus | Ptolemy | Galileo |
| 500AD | 1473-1543 | 1571-1630 | 1642-1727 | 1879-195 | 5 1894- | -1966 |
| Aryabhata | Copernicus | Kepler | Newton | Einstein | Lema | itre |

A human history of cosmology

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Physical quantities and units 1.

 $\pi \approx 3.142$ $e \approx 2.718$ $\sqrt{2} \approx 1.414$ **SI** means 'Système International d'Unités' (International System of Units)

| Quantity | Symbol | Vector | Unit | Unit | Notes |
|----------|--------------------------------------|---------------|-----------------|-------------------------------|--|
| | | or scalar? | | abbreviation | |
| Mole | n | scalar | mole | mol | Mol is a base SI unit |
| SI | | | | | Avogadro's constant |
| | | | | | $N_A = 6.022 \times 10^{23}$ molecules per mole |
| Mass | m, M | scalar | kilogram | kg | kg is a base SI unit |
| SI | | | tonne gram | 10° Kg 10 ⁻³ kg | Electron mass $m_e = 9.109 \times 10^{-31}$ kg |
| | | | atomic mass | io ng | Proton mass $m_p = 1.673 \times 10^{-27} \text{ kg}$ |
| | | | unit | u | Neutron mass $m_n = 1.675 \times 10^{-27} \text{kg}$ |
| | | | | | $u = 1.660 \times 10^{-27} \mathrm{kg}$ |
| | | | | | Earth mass M_\oplus = 5.974×10 ²⁴ kg |
| | | | | | Solar mass $M_{\odot}{=}1.989{\times}10^{30}{ m kg}$ |
| Longth | | scalar | angstrom | $Å - 10^{-10}$ m | m is a base SI unit |
| CI | <i>l</i> , <i>L</i> , | Scalai | nanometre | $nm = 10^{-9}m$ | |
| 51 | <i>a</i> , <i>b</i> , <i>c</i> , | | micron | μm = 10 ⁻⁶ m | |
| | <i>x</i> , <i>y</i> , <i>z</i> | | millimetre | $mm = 10^{-3}m$ | |
| | | | metre | cm = 10 m | |
| | | | kilometre | $km = 10^{3}m$ | |
| | | | mile | mile | mile = 1,609m |
| | | | Astronomical | A11 | $A = 1.406 \times 10^{11} m$ |
| | | | parsec | AU parsec | $AO = 1.490 \times 10^{-110}$ parsec = 3.086 x10 ⁻¹⁶ m |
| | | | light-year | lyr | $lyr = 9.461 \times 10^{15} m$ |
| Angle | θ, ϕ | scalar | degrees | °, deg | π radians = 180° |
| 0 | a.b.ca. B | | radians | rad | |
| | ,.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, | | arc-minute | arcmin = | |
| | | | arc-second | (1/60) deg | |
| | | | | (1/3600) deg | |
| Area | A | scalar | square mm | mm ² | $mm^2 = 10^{-6} m^2$ |
| | | | centimetres | cm ² | $cm^2 = 10^{-4} m^2$ |
| | | | square metres | m ² | |
| | | | square | km ² | 10^{6} m^{2} |
| | | | hectares | ha | $ha = 10^4 m^2$ |
| | | | acre | acre | acre = $4.047 \times 10^3 \text{ m}^2$ |
| Volume | V | scalar | cubic | 3 | 40 ⁻⁶ 3 |
| | | | centimetre | cm [°] | cm [°] = 10 [°] m [°] |
| | | | cubic kilometre | km ³ | $km^3 = 10^9 m^3$ |
| | | | millilitre | ml | ml = 1 cm ³ (pure water at STP) |
| | | | litre | 1 | $I = 10^{3} \text{ cm}^{3} = 10^{-3} \text{ m}^{3}$ |
| | | | gallon | gal | gal = 4.546 x10 ັ mັ |

| Quantity | Symbol | Vector | Unit | Unit | Notes |
|--------------|------------|---------|-----------------------|------------------------------------|---|
| | | or | | abbreviation | |
| Time | <i>t τ</i> | scalar? | nicosecond | DC . | s is a base SI unit |
| CI | ι, ι | Scalai | nanosecond | ns | s is a base of unit |
| 31 | | | microsecond | μS | min = 60s, hr = 60min = 3600s, |
| | | | millisecond | ms | $yr \approx 365 \times 24 \times 3600s$ |
| | | | second | S | $v_{\rm r} \sim 3.154 \times 10^7 {\rm s}$ |
| | | | minute | min | $y_1 \approx 3.134 \times 10^{\circ}$ |
| | | | hour | hr d Othr | $yr \approx \pi \times 10' s$ |
| | | | vear | d = 24nr | Age of the Earth = 4.5×10^9 yr |
| Cread | c. | | | уг | Age of the Universe = 13.8 x 10° yr |
| Speed | 5 | Scalar | second | ms ⁻¹ | $c = 2.998 \times 10^8 \text{ ms}^{-1}$ |
| | u, v | | 3000110 | ino | Speed of sound in air $(20^{\circ}C)$: 344 ms ⁻¹ |
| | | | kilometre per hour | kmh ⁻¹ | Speed of sound in water: 1482 ms ⁻¹ |
| | | | mile per hour | mph | $1 \text{ms}^{-1} = 3.6 \text{kmh}^{-1}$ |
| | | | | | $1 \text{ms}^{-1} = 2.24 \text{ mph}$ |
| | | | | | 1 min per mile at 60mph |
| | | | | | 3 mins per mile at 20mph |
| Frequency | £ | scalar | Hortz | $H_7 = e^{-1}$ | 6 mins per mile at 10mpn |
| Frequency | J | Scalai | Kilohertz | HZ = 5 kHz = 10 ³ Hz | Radio waves 3kHz - 300MHz |
| | | | Megahertz | $MHz = 10^{6} Hz$ | Microwaves 3MHz - 100GHz |
| | | | Gigahertz | $GHz = 10^9 Hz$ | Infrared 100GHz - 300THz |
| | | | Terahertz | $THz = 10^{12} Hz$ | Visible light $10^{14} - 10^{15}$ Hz |
| | | | | | Ultraviolet 10^{19} Hz - 10^{19} Hz |
| | | | | | X-rays 10^{10} Hz - 10^{20} Hz |
| Period | | scalar | Same as time | Same as time | Time to complete a single oscillation |
| 1 chica | 1 | 500101 | | | |
| | | | | | $T = \frac{1}{f}$ e.g. period of Earth's rotation is |
| | | | | | 24 hours, period of Earth's orbit about the sun is 1 year. |
| Displacement | X | vector | Same as | Same as | Magnitude as well as direction. Often |
| | x, y, z | | length | length | we describe \mathbf{x} in terms of a <i>coordinate</i> |
| | | | | | system e.g. x,y,z Cartesians. In this |
| | | | | | backwards' |
| | | | | | In one direction, displacement is the |
| | | | | | area under a (time,velocity) graph, |
| | | | | | where area below the time axis is |
| | | | | | negative. |
| Velocity | V | vector | Same as | Same as | Magnitude as well as direction. Often |
| | и, v | | speed | speed | systeme a x y z Cartesians In this |
| | | | | | case a negative value of v means 'going |
| | | | | | backwards'. |
| | | | | | In one direction, velocity is the gradient |
| | | | | | of a (time,displacement) graph. |
| | | | | | It is also the <i>area</i> under a (time, |
| | | | | | the time axis is pegative |
| | | | | | u is typically a symbol for initial velocity |
| | | | | | v for final or 'current' velocity |
| Acceleration | a | vector | metre per | ms ⁻² | Magnitude as well as direction. Often |
| | a | | second | | we describe in terms of a coordinate |
| | | | squared | | system e.g. x,y,z Cartesians. |
| | | | | | In one direction, acceleration is the |
| | | | | | Free-fall' acceleration under gravity |
| | | | | | $\sigma = 9.81 \text{ ms}^{-2}$ |
| | | | | | $\mathcal{S}_{earth} = \mathcal{I}_{o} \mathcal{I}_{o} \mathcal{I}_{o}$ |
| | | | | | $g_{moon} = 1.63 \text{ms}^{-2}$ |

| Quantity | Symbol | Vector | Unit | Unit | Notes |
|------------|-------------------------------------|---------------|--|---|---|
| | | or scalar? | | appreviation | |
| Energy | E | scalar | Joules kilojoules megajoules calories kilo-calories kilowatt- hour | J kJ = 10^{3} J MJ = 10^{6} J cal = 4.184J kcal = 10^{3} cal kWh | Energy is <i>conserved,</i> i.e. in a closed system has the <i>same numerical value</i> . It can be converted into different forms e.g. <i>kinetic</i> and <i>potential</i> energy. Calories measure energy in food 1kWh is a standard measure of domestic electricity consumption. <i>Total</i> UK energy consumption is about 125 kWh per person |
| | | | electron- volts | eV keV = $10^3 eV$ MeV = $10^6 eV$ | per day. eV = kinetic energy of an electron accelerated by a voltage V $eV = 1.602 \times 10^{-19} J$ |
| Power | P | scalar | Watts kilowatts megawatts gigawatts terawatts horsepower | $W = Js^{-1}$ $kW = 10^{3} W$ $MW = 10^{6} W$ $GW = 10^{9} W$ $TW = 10^{12} W$ hp = 746W | Power is the rate of energy changed from one form into another A light bulb uses about 20W Dr French's computers use about 250W A kettle uses about 2kW A Tour-de-France cyclist expends 250- 500W A wind turbine generates 1-10MW A power station generates up to 5GW About 1.36 kWm ² of solar radiation shine on the Earth. |
| Force | f <i>f</i> , <i>F</i> | vector | Newtons kilonewtons | N kN | Newton's Second Law: mass x acceleration = vector sum of forces |
| Weight | W | vector | Newtons kilonewtons | N kN | The gravitational force F acting upon a mass m is $F = mg$. |
| Tension | Т | vector | Newtons kilonewtons | N kN | Force applied by a taught cable or string. Often these are modelled as <i>light</i> and <i>inextensible</i> . i.e. ignore the effect of their mass and assume they don't stretch. |
| Momentum | $\mathbf{p} = m\mathbf{v}$ $p = mv$ | vector | kilogram- metres per second | kgms⁻¹ | Note <i>impulse</i> is a change in momentum, e.g. due to a collision or from the action of some external force over a period of time. |
| Moment | m = Fd | scalar | Newton- metre | Nm | Force x <i>perpendicular</i> distance from a pivot |
| Elasticity | $k = \frac{\lambda}{l}$ | scalar | Newtons per metre | Nm ⁻¹ | If an elastic body (such as spring or rubber band) is <i>Hookean</i> , the restoring force following extension by <i>x</i> is $F = \frac{\lambda}{l} x$ where <i>l</i> is the natural length and λ is the elastic modulus. |

| Quantity | Symbol | Vector | Unit | Unit abbreviation | Notes |
|--|----------------------------------|---------|--|---|---|
| | | scalar? | | abbrothation | |
| Density | ρ | scalar | mass per unit volume | kgm ⁻³ gcm ⁻³ | Air is about 1.2 kgm ⁻³ Wood is about 0.5 gcm ⁻³ Water is about 1 gcm ⁻³ Aluminium is 2.7 gcm ⁻³ Iron is 7.8 gcm ⁻³ Copper is 8.9 gcm ⁻³ Mercury is 13.5 gcm ⁻³ Gold is 19.3 gcm ⁻³ Uranium is 19.1 gcm ⁻³ |
| Pressure | p | scalar | Pascal kilopascal megapascal millibar Atmosphere | Pa kPa = 10 ³ Pa MPa = 10 ⁶ Pa mbar = 100Pa atm | Force per unit area Pa = 1Nm ⁻² atm = 101,325 Pa is essentially a 'reference' atmospheric pressure at sea level. atm = 1013.25 mbar. Millibars are used to measure air pressure in <i>meteorology</i> , i.e. climate science and weather forecasting. |
| Temperature SI | Т | scalar | degrees celcius degrees fahrenheit degrees kelvin | °C °F K | K is a base SI unit $T_{K} = T_{C} + 273.15$ $T_{F} = \frac{9}{5}T_{C} + 32$ Temperature in K is proportional to the mean kinetic energy of molecules. Hence nothing can be colder than 0K "absolute zero" |
| Solid or liquid specific heat capacity | с | scalar | joules per kilogram per Kelvin | Jkg ⁻¹ K ⁻¹ | water 4200 Jkg ⁻¹ K ⁻¹ alcohol 2500 Jkg ⁻¹ K ⁻¹ ice 2100 Jkg ⁻¹ K ⁻¹ aluminium 900 Jkg ⁻¹ K ⁻¹ concrete 800 Jkg ⁻¹ K ⁻¹ glass 700 Jkg ⁻¹ K ⁻¹ steel 500 Jkg ⁻¹ K ⁻¹ copper 400 Jkg ⁻¹ K ⁻¹ |
| Gas specific heat capacity | С _р С _v | scalar | joules per kilogram per Kelvin | Jkg ⁻¹ K ⁻¹ | c_p is at constant pressure, c_V at constant volume. c_p for dry air is about 1000Jkg ⁻¹ K ⁻¹ |
| Specific latent heat of fusion | L ΔH | scalar | joules per kilogram | Jkg ⁻¹ | water 336,000 Jkg ⁻¹ alcohol 108,000 Jkg ⁻¹ |
| Specific latent heat of vaporisation | L ΔH | scalar | joules per kilogram | Jkg ⁻¹ | water 2,260,000 Jkg ⁻¹ alcohol 855,000 Jkg ⁻¹ |

| Quantity | Symbol | Vector or scalar? | Unit | Unit abbreviation | Notes |
|----------------------------|--------|-------------------------|---|---|---|
| Charge | q,Q | scalar | Coulombs | С | charge on the electron |
| | e | | | | $e = 1.602 \times 10^{-19} \text{ C}$ |
| Voltage | V | scalar | Volts millivolts kilovolts Megavolts | V mV = 10^{-3} V kV = 10^{3} V MV = 10^{6} V | Potential energy per coulomb of charge Energy change per coulomb of charge <i>across</i> a resistor. 'Electromotive force' (EMF). |
| Current SI | Ι | scalar | Amps milliamps | A mA | A is a base SI unit Rate of charge flowing in an electrical circuit (coulombs per second). |
| Resistance | R | scalar | Ohms kilo-ohms mega-ohms | Ω | Ohm's Law: $V = IR$ Voltage drop across a resistor is proportional to resistance, and current flowing through it. |
| Resistivity | ρ | scalar | ohm-metre | Ωm | Resistance of a cylindrical wire of length l and cross sectional area A is $R = \rho \frac{l}{A}$ Copper $\rho = 1.68 \times 10^{-8} \Omega m$ Aluminium $\rho = 2.82 \times 10^{-8} \Omega m$ Gold $\rho = 2.44 \times 10^{-8} \Omega m$ Iron $\rho = 1.00 \times 10^{-7} \Omega m$ Sea water $\rho = 2.00 \times 10^{-7} \Omega m$ Glass $\rho = 10^{11} - 10^{15} \Omega m$ Hard rubber $\rho = 10^{13} \Omega m$ Dry wood $\rho = 10^{14} - 10^{16} \Omega m$ Air $\rho = 1.3 - 3.3 \times 10^{16} \Omega m$ |
| Electric field strength | E | vector | Volts per metre | Vm ⁻¹ | Force on a charge q coulombs in a electric field of strength E is F = qE A dielectric will conduct electricity ('breakdown') when E exceeds a critical value. Note: $1MVm^{-1} = 10^{6}Vm^{-1}$ Air $E > 3MVm^{-1}$ Glass $E > 10MVm^{-1}$ Oil $E > 10MVm^{-1}$ Rubber $E > 15MVm^{-1}$ pure water $E > 65MVm^{-1}$ Mica $E > 118MVm^{-1}$ Diamond $E > 2,000 \times 10^{6}Vm^{-1}$ |

| Quantity | Symbol | Vector | Unit | Unit abbreviation | Notes |
|-------------------------|-------------------|---------|---------------------|----------------------|---|
| | | scalar? | | abbreviation | |
| Magnetic field | В | vector | Tesla | т | Force on a wire of length l carrying current |
| strength | В | | | | I in magnetic field B is $F = BIl$ |
| | | | | | Note force, current and field are <i>mutually</i> |
| | | | | | perpendicular. Magnetic field inside a solenoid (a coil of |
| | | | | | wire carrying current I of n turns per unit |
| | | | | | length) is $B = \mu_0 nI$ |
| | | | | | 'Permeability of free space' |
| | | | | | $\mu_0 = 4\pi \times 10^{-7} \mathrm{Hm}^{-1}$ |
| | | | | | Earth's magnetic field $\approx 25\mu T - 65\mu T$ |
| | | | | | $(\mu T = 10^{-6}T)$ |
| | | | | | 5 X 10 1 strength of tridge magnet |
| | | | | | Resonance Imaging (MRI) system |
| | | | | | 10 ⁶ T-10 ⁸ T field strength of a <i>neutron star</i> |
| Crovitational | σ | vector | matrag | | 10°T-10''T field strength of a <i>magnetar</i> |
| field strength | 5 0 | vector | second | ms | $g_{earth} = 9.81 \text{ms}^{-2}$ |
| | 8 | | squared | _ | $g_{moon} = 1.63 \text{ms}^{-2}$ |
| Radioactive activity | A | scalar | Becquerel Curies | Bq | Bq = radioactive decays per second |
| | | | | Ci | Ci = 3.7 10 ¹⁰ Bq |
| | | | | | (activity of one gram of $\frac{^{226}}{^{88}}Ra$) |
| Half life | $T_{\frac{1}{2}}$ | scalar | Seconds, | s, d, yr | Time for half of a sample of radioactive |
| | ~ | | days, years | | Isotopes to have decayed |
| | | | | | $\frac{1}{92}$ U 7 x 10° yr |
| | | | | | ¹⁴ ₁₂ C 5,730 yr |
| | | | | | $^{123}_{53}$ I 13 hrs |
| Refractive | n | scalar | just a | - | $n = \frac{C_{\text{vacuum}}}{1}$ i.e. ratio of speed of light in a |
| muex | | | number | | C _{material} |
| | | | | | vacuum (2.998 x 10 ⁸ ms ⁻¹) to speed of light in |
| | | | | | a material. |
| | | | | | air 1 00 |
| | | | | | ice 1.31 |
| | | | | | water 1.33 |
| | | | | | human cornea 1.37-1.40 human lens 1.39-1.41 |
| | | | | | plexiglas 1.49 |
| | | | | | crown glass 1.52 |
| | | | | | sapphire 1.76-1.78 |
| | | | | | diamond 2.42 |

2. Mechanics

| Name | Equation | Description of variables | Notes / diagram |
|------------------------------------|--|--|---|
| Kinematics | $v = \frac{dx}{dt} x = \int v dt$ $a = \frac{dv}{dt} v = \int a dt$ | x displacement v velocity a acceleration t time | Velocity is the gradient of a (time,displacement) graph. Displacement is the area under a (time, velocity). graph. Note areas below the time axis are negative. Acceleration is the gradient of a (time,velocity) graph velocity is the area under a (time, velocity). graph. Note areas below the time axis are negative. |
| Constant acceleration motion | $v = u + at$ $x = x_0 + \frac{1}{2}(u + v)t$ $x = x_0 + ut + \frac{1}{2}at^2$ $v^2 = u^2 + 2ax$ | <i>u</i> initial velocity /ms ⁻¹ <i>a</i> acceleration /ms ⁻² <i>t</i> time /s <i>v</i> final velocity /ms ⁻¹ <i>x</i> displacement /m x_0 initial displacement /m | Only valid for motion when acceleration <i>a</i> is <i>constant</i> . Easily derived from linear velocity, time graph. <i>a</i> is the <i>gradient</i> $a = \frac{v-u}{t}$ and $x - x_0$ is the <i>area</i> <i>under the graph</i> , which is a <i>trapezium</i> hence $x - x_0 = \frac{1}{2}(u + v)t$ |
| Newton's First Law | $\mathbf{a} = 0$ $\Rightarrow \mathbf{v} = \text{ constant}$ | a acceleration v velocity | A object will move at constant velocity if it is not accelerating, and therefore the vector sum of forces is zero. It is in equilibrium. |
| Newton's Second Law | $m\mathbf{a} = \sum_{i} \mathbf{f}_{i}$ | mass x acceleration = vector sum of forces | Most mechanics problems are often solved by firstly writing down Newton II for each direction of a coordinate system (typically Cartesian x, y) appropriate for the problem. |
| Newton's Third Law | "For every action there is an equal and opposite reaction" | | If body A imposes a contact force \mathbf{F} upon body B, body B will in turn impose a contact force $-\mathbf{F}$ upon body A. |
| Conservation of momentum | $\underbrace{m_1 \mathbf{u}_1 + m_2 \mathbf{u}_2 + \dots}_{\text{BEFORE COLLISION}} = \underbrace{m_1 \mathbf{v}_1 + m_2 \mathbf{v}_2 + \dots}_{\text{AFTER COLLISION}}$ | momentum = mass x velocity | The vector sum of momenta is the same before and after a collision |
| Impulse | "Force x time = change in momentum" $\int_0^t \mathbf{f}(t) dt = m\mathbf{v} - m\mathbf{u}$ | f(t) force (as a function of time t), m mass v final velocity u initial velocity 'impulse' means momentum change | In each direction of a coordinate system, the area under the (time,force) graph is the <i>change in momentum</i> . If force is a constant force x time = change in momentum |

| Conservation | $\frac{1}{2}mu^2 + GPE_0 + EPE_0 + = \frac{1}{2}mv^2 + GPE_1 + EPE_1 +$ | u, v initial and | $g_{\rm max} = 9.81 {\rm ms}^{-2}$ |
|---------------------------------|--|---|--|
| of energy | CDE - mah | final speeds. | $\frac{1}{62}$ $\frac{1}{2}$ |
| | OFE = mgn | h change in | $g_{moon} = 1.03IIIS$ |
| | $GPE = -\frac{GMm}{M}$ | vertical height. | $G = 6.67 \times 10^{-11} \mathrm{Nm^2 kg^{-2}}$ |
| | r | g gravitational | |
| | $\mathbf{E}\mathbf{P}\mathbf{E} = (L_{1}^{2} + \lambda_{1}^{2})$ | field strength. | |
| | $EPE = \frac{1}{2}Kx = \frac{1}{2}\frac{1}{l}x$ | M,m masses. | |
| | U U | r distance | |
| | | between | |
| | | G gravitational | |
| | | force constant | |
| | | x spring | |
| | | extension. | |
| | | k spring | |
| | | constant. | |
| | | λ modulus of | |
| | | elasticity. | |
| | | <i>l</i> original length | |
| | | of spring. | |
| Coefficient of | $C = \frac{\text{speed of separation}}{1}$ | C = 1 elastic coll | ision (kinetic energy |
| restitution | speed of approach | C = 0 inclustic of | allicion (objects romain |
| | | C = 0 inelastic contraction to determine the some kinetic some kine | instin (objects remain |
| Work done | 'WORK DONE = FORCE x DISTANCE' | f force | Work done is "the area |
| | $W = \int \mathbf{f} d\mathbf{r} = 1 m r^2 - 1 m r^2$ | r | under a (displacement, |
| | $W = \int \mathbf{I} \cdot d\mathbf{I} = \frac{1}{2}mV = \frac{1}{2}mu$ | displacement. | force) graph", noting |
| | | m mass. | that areas below the x |
| | | u, v initial and | axis are <i>negative</i> . |
| | | final speeds. | |
| | | | |
| | | | |
| Moments | 'MOMENT = FORCE x PERPENDICULAR DISTANCE | F force | In equilibrium , the sum |
| Moments | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M - Ed | <i>F</i> force <i>d</i> distance | In equilibrium , the sum of moments (clockwise |
| Moments | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd | F force d distance from axis of | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the |
| Moments | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd | <i>F</i> force <i>d</i> distance from axis of rotation | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! |
| Moments Projectile | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos \theta$ $v_y = u \sin \theta - gt$ | F force d distance from axis of rotation v_x horizontal | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos \theta$ $v_y = u \sin \theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ | F force d distancefrom axis ofrotation v_x horizontalvelocity v_x vertical | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> acceleration motion in |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> acceleration motion in both x and y directions, if air resistance is |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos \theta$ $v_y = u \sin \theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos \theta$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v_y speed | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially constant acceleration motion in both x and y directions, if air resistance is ignored |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos \theta$ $v_y = u \sin \theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos \theta$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed u launch speed | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2}(1 + \tan^2\theta)x^2$ | Fforceddistancefrom axis ofrotation v_x horizontalvelocity v_y verticalvelocityv speedulaunch speedθlaunch | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially constant acceleration motion in both x and y directions, if air resistance is ignored. In the x direction acceleration is zero, |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos \theta$ $v_y = u \sin \theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos \theta$ $y = y_0 + x \tan \theta - \frac{g}{2u^2}(1 + \tan^2 \theta)x^2$ $t = \frac{u \sin \theta}{2u^2}$ | Fforceddistancefrom axis ofrotation v_x horizontalvelocity v_y verticalvelocityv speedulaunch speed θ launchelevationgggggggratio | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> |
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| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos \theta$ $v_y = u \sin \theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos \theta$ $y = y_0 + x \tan \theta - \frac{g}{2u^2} (1 + \tan^2 \theta) x^2$ $t_a = \frac{u \sin \theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2 \theta}{2a}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ $x = \frac{u^2 \sin\theta \cos\theta}{2g}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal displacement | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ $x_a = \frac{u^2 \sin\theta \cos\theta}{g}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal displacement <i>y</i> vertical | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially constant acceleration motion in both x and y directions, if air resistance is ignored. In the x direction acceleration is zero, hence a constant velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ $x_a = \frac{u^2 \sin\theta \cos\theta}{g}$ $u^2 \sin 2\theta$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal displacement <i>y</i> vertical | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories for a given launch |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ $x_a = \frac{u^2 \sin\theta \cos\theta}{g}$ $R = \frac{u^2 \sin 2\theta}{g}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal displacement <i>y</i> vertical displacement y_0 initial | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories for a given launch velocity <i>u</i> |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ $x_a = \frac{u^2 \sin\theta \cos\theta}{g}$ $R = \frac{u^2 \sin 2\theta}{g}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal displacement <i>y</i> vertical displacement y_0 initial vertical | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories for a given launch velocity <i>u</i> corresponding to 'steep' |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ $x_a = \frac{u^2 \sin\theta \cos\theta}{g}$ $R = \frac{u^2 \sin 2\theta}{g}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal displacement y vertical displacement y_0 initial vertical displacement | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories for a given launch velocity <i>u</i> corresponding to 'steep' and 'shallow' solutions |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u\cos\theta$ $v_y = u\sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut\cos\theta$ $y = y_0 + x\tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u\sin\theta}{g}$ $y_a = y_0 + \frac{u^2\sin^2\theta}{2g}$ $x_a = \frac{u^2\sin\theta\cos\theta}{g}$ $R = \frac{u^2\sin2\theta}{g}$ | Fforceddistancefrom axis ofrotation v_x horizontalvelocity v_y verticalvelocityv speedulaunch speed θ launchelevationggravitationalaccelerationttime sincelaunchxhorizontaldisplacementyverticaldisplacement y_0 initialverticaldisplacement t_a apogee time | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories for a given launch velocity <i>u</i> corresponding to 'steep' and 'shallow' solutions for elevation θ . |
| Moments Projectile motion | $\begin{array}{l} \text{'MOMENT} = \text{FORCE x PERPENDICULAR DISTANCE} \\ \text{FROM ROTATION AXIS'} \\ M = Fd \end{array}$ $\begin{array}{l} v_x = u\cos\theta v_y = u\sin\theta - gt \\ v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)} \\ x = ut\cos\theta \\ y = y_0 + x\tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2 \\ t_a = \frac{u\sin\theta}{g} \\ y_a = y_0 + \frac{u^2\sin^2\theta}{2g} \\ x_a = \frac{u^2\sin\theta\cos\theta}{g} \\ R = \frac{u^2\sin2\theta}{g} \end{array}$ | Fforceddistancefrom axis ofrotation v_x horizontalvelocity v_y verticalvelocityv speedulaunch speed θ launchelevationggravitationalaccelerationttime sincelaunchkhorizontaldisplacementyverticaldisplacement y_0 initialverticaldisplacement t_a apogee time x_a, y_a apogee | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories for a given launch velocity <i>u</i> corresponding to 'steep' and 'shallow' solutions for elevation θ . |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ $x_a = \frac{u^2 \sin\theta \cos\theta}{g}$ $R = \frac{u^2 \sin 2\theta}{g}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal displacement <i>y</i> vertical displacement y_0 initial vertical displacement t_a apogee time x_a, y_a apogee coordinates | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially <i>constant</i> <i>acceleration motion in</i> <i>both x and y directions</i> , if air resistance is ignored. In the x direction acceleration is zero, hence a <i>constant</i> velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories for a given launch velocity <i>u</i> corresponding to 'steep' and 'shallow' solutions for elevation θ . |
| Moments Projectile motion | 'MOMENT = FORCE x PERPENDICULAR DISTANCE FROM ROTATION AXIS' M = Fd $v_x = u \cos\theta$ $v_y = u \sin\theta - gt$ $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2g(y - y_0)}$ $x = ut \cos\theta$ $y = y_0 + x \tan\theta - \frac{g}{2u^2}(1 + \tan^2\theta)x^2$ $t_a = \frac{u \sin\theta}{g}$ $y_a = y_0 + \frac{u^2 \sin^2\theta}{2g}$ $x_a = \frac{u^2 \sin\theta \cos\theta}{g}$ $R = \frac{u^2 \sin 2\theta}{g}$ | <i>F</i> force <i>d</i> distance from axis of rotation v_x horizontal velocity v_y vertical velocity v speed <i>u</i> launch speed θ launch elevation <i>g</i> gravitational acceleration <i>t</i> time since launch <i>x</i> horizontal displacement <i>y</i> vertical displacement y_0 initial vertical displacement t_a apogee time x_a, y_a apogee coordinates <i>R</i> horizontal | In equilibrium , the sum of moments (clockwise or anticlockwise) is zero , regardless of the axis position chosen! Projectile motion is essentially constant acceleration motion in both x and y directions, if air resistance is ignored. In the x direction acceleration is zero, hence a constant velocity $v_x = u \cos \theta$. The x,y curve traced out by particle is an <i>inverted</i> <i>parabola</i> . Typically for a given range there are two possible trajectories for a given launch velocity <i>u</i> corresponding to 'steep' and 'shallow' solutions for elevation θ . |

| Lift and drag | $F_{L} = \frac{1}{2}c_{L}\rho Av^{2}$ $F_{D} = \frac{1}{2}c_{D}\rho Av^{2}$ $F = 6\pi a\eta v$ | c_L lift coefficient. c_D drag coefficient. ρ density of air/fluid. A area of object in fluid stream. v speed. a radius of sphere. η viscosity | The linear Stokes drag equation $F = 6\pi a\eta v$ is typically applicable in <i>low Reynolds number</i> scenarios when <i>viscous</i> <i>forces dominate</i> . Air resistance models for bikes, cars, planes, skydivers are typically better served by the v^2 models. |
|--|---|--|--|
| Force of gravity & Kepler's Laws of orbital motion | $\mathbf{W} = m\mathbf{g}$ $\mathbf{F} = -\frac{GMm}{r^2} \hat{\mathbf{r}}$ $r = \frac{a(1-\varepsilon^2)}{1+\varepsilon\cos\theta}$ $\varepsilon = \sqrt{1-\frac{b^2}{a^2}}$ $P^2 = \frac{4\pi^2}{G(M+M_{\odot})}a^3$ $\frac{dA}{dt} = \frac{1}{2}\sqrt{G(M+M_{\odot})(1-\varepsilon^2)a}$ | W weight g gravitational field strength. M,m masses. r distance between masses. G gravitational force constant. ε eccentricity of elliptical orbit. a semi-major axis of the ellipse. b semi-minor axis of the ellipse. M_{\odot} stellar mass. θ polar angle (anticlockwise from semi- major axis). P orbital | $g_{earth} = 9.81 \text{ms}^{-2}$ $g_{moon} = 1.63 \text{ms}^{-2}$ $G = 6.67 \times 10^{-11} \text{Nm}^2 \text{kg}^{-2}$ Kepler's First Law: Bound gravitational orbits of two masses are ellipses, with foci about the common centre of mass. Kepler's Second Law: The rate of ellipse area swept out (radially from the focus of the ellipse) is a constant Kepler's Third Law: The square of orbital period is proportional to the cube of the ellipse semi-major axis |
| Elasticity (or elastic strings) | $F = kx = \frac{\lambda}{l}x$ $E = \frac{1}{2}kx^{2}$ | F force.kelasticconstant. λ elasticmodulus.loriginal lengthof elastic string.xextension.Eelasticpotential energy | Most elasticity models are <i>Hookean</i> and assume a constant modulus of elasticity. In reality for large extensions there will be plastic deformation and ultimately breakage. |
| Friction | $F \le \mu R$ $F = \mu R$ | F frictional force. μ coefficient of friction. R normal contact force | A system is said to be in 'limiting' equilibrium' if $F = \mu R$, i.e. 'on the point of sliding'. Once an object is sliding along a surface, the friction force 'maxes out' out $F = \mu R$. Note μ may change in this dynamic case. $F \le \mu R$ can be used to determine conditions (e.g. tilt angle of a slope) for sliding to occur. |

| Power & driving force | $P = Fv$ $P = \mathbf{F} \cdot \mathbf{v}$ $D = \frac{P}{v}$ | F , F force P power v , v velocity D driving force | One <i>Horsepower</i> (hp) = 746W. This equation is useful in relating energy conversion rates in engines to resulting motion. |
|--------------------------|--|---|---|
| | | | |

| Name | Equation | Description of variables | Notes / diagram |
|--------------------------|--|---|---|
| Charge on a capacitor | Q = CV | Q charge /coulombs | Voltage across two |
| | | C capacitance /Farads | capacitor plates |
| | | V voltage /volts | separated by an |
| | | / | insulating <i>dielectric</i> |
| Ohm's law | V = IR | V voltage /volts | Voltage or potential |
| | | I current /amps | difference' across a |
| | | R resistance /ohms | resistive element |
| Electrical power | P = VI | P power /watts | |
| | | V voltage /volts | |
| | | I current /amps | |
| Resistive power loss | $P = I^2 R$ | P power /watts | |
| | | I current /amps | |
| | | R resistance /ohms | |
| Resistance of a wire | $P = \rho l$ | R resistance | Assume uniform |
| | $R = \frac{A}{A}$ | <i>l</i> length | resistivity and cross |
| | | A cross sectional area | sectional area. |
| | | ho resistivity | |
| | | | $\rho = 1.68 \times 10^{\circ} \Omega m$ |
| | | | |
| | | | $\rho = 2.82 \times 10^{-1} \Omega m$ |
| | | | All $1.2 - 2.2 \times 10^{16} \text{Om}$ |
| Addition of parion | | <i>B</i> registeres | $\rho = 1.3 - 3.3 \times 10^{\circ} \Omega$ |
| resistors | $R = R_1 + R_2 + \dots$ | <i>R</i> resistance | |
| Addition of parallel | 1 1 1 | R resistance | |
| resistors | $\frac{1}{p} = \frac{1}{p} + \frac{1}{p} + \dots$ | | |
| | $\mathbf{K} \mathbf{K}_1 \mathbf{K}_2$ | | |
| Magnetic field inside an | $B = III \frac{NI}{N}$ | <i>B</i> magnetic field strength | A soft magnetic material |
| infinite solenoid | $B = \mu \mu_0 \frac{l}{l}$ | μ relative permeability | inside the coil will |
| | | μ_0 permeability of free | field For ferrite $\mu > 640$ |
| | | space = $4\pi \times 10^{-7} \text{Hm}^{-1}$ | field. For remite $\mu > 0+0$ |
| | | N turns in length l | |
| | | <i>I</i> current | |
| Transformers | $V_2 = N_2$ | V_1, I_1 Voltage, current in | This assumes no power |
| | $\frac{1}{V} = \frac{1}{N}$ | primary coil | is lost i.e. |
| | | V_2 , I_2 voltage. current in | $V_1 I_1 = V_2 I_2$ |
| | $\left \frac{I_2}{I} = \frac{I_{N_1}}{N} \right $ | secondary coil N N | |
| | $I_1 I_2$ | number of turns in primary | |
| | | secondary coils | |

| Name | Equation | Description of variables | Notes / diagram |
|---------------------------|---|--|---|
| Wave speed equation | $c = f \lambda$ | c wave speed | Speed of light in a |
| | - J | f frequency | vacuum |
| | | | $c = 2.998 \text{ x} 10^8 \text{ ms}^{-1}$ |
| | | x wavelength | Speed of sound in air |
| | | | (20°C): 344 ms ⁻¹ |
| | | | Speed of sound in |
| | | | water: 1482 ms ⁻¹ |
| | | | |
| Wavenumber | $k = \frac{2\pi}{2\pi}$ | λ wavelength | Phase of a wave is |
| | $\lambda = \lambda$ | | $\phi = kx - \omega t$ |
| Frequency and period | . 1 | f frequency | |
| | $f = \frac{1}{T}$ | T period | |
| Speed of waves in | | c wave speed | e a guitar string low F |
| elastic media | $c = \int \frac{I}{c}$ string under tension | T string tension | $\mu = 0.0059 \text{ kgm}^{-1}$ |
| | $\mathbb{N}\mu$ | μ mass per unit length | f = 82.41 Hz |
| | \overline{E} | E Elastic modulus | $\int -02.41112$ |
| | $c = \sqrt{\frac{2}{c}}$ elastic solid | ρ Density | (lundamental mode, |
| | VΡ | p Donoky | so string length = $\frac{1}{2}\lambda$) |
| | | | T = 67.8N |
| | | | $\lambda = 1.30 \text{ m}$ |
| Law of reflection | $\theta_i = \theta_r$ | θ_i angle of incidence | Angles measured |
| | | θ_r angle of reflection | reflecting surface |
| Snell's law of refraction | $n \sin \theta - n \sin \theta$ | n refractive index of | Angles measured |
| | $n_1 \sin o_1 - n_2 \sin o_2$ | | from normal to the |
| | $n = \frac{\text{speed of light in vaccum}}{1 + 1 + 1 + 1 + 1}$ | nequum i | reflecting surface |
| | speed of light in medium | θ_1 angle of incidence to | |
| | $n_1 \sin \theta_1$ | boundary of medium 1 to 2 | Total internal |
| | $\sin\theta_2 = \frac{1}{n}$ | n_2 refractive index of | reflection at glass : air |
| | | medium 2 | interface i.e. no |
| | $0 \le \theta \le \frac{1}{2}\pi$ | θ_2 angle of refraction in | retraction if |
| | $\therefore 0 \le \sin \theta_2 \le 1$ | medium 2 | $\theta_{i} > \sin^{-1} \left(\frac{n_{air}}{n_{air}} \right)$ |
| | $\therefore 0 \le \frac{n_1 \sin \theta_1}{1} \le 1$ | | (n_{glass}) |
| | $n_2 \leq \frac{n_2}{n_2}$ | | $(1)^{-1}$ |
| | | | $\theta_i > \sin^{-1}\left(\frac{1}{1.52}\right)$ |
| | $\theta_1 \leq \sin^{-1} \left(\frac{n_2}{2} \right)$ | | (1.52) |
| | (n_1) | | $\theta_i > 41.1^\circ$ |
| | | | critical angle |
| Gauss' Lens Formula | $\frac{1}{-+-} \frac{1}{-+-} \frac{1}{}$ | <i>u</i> object distance | 1/f = Dioptre |
| | u v f | v image distance | number. |
| | | J tocal length of a lens | fnumberio |
| | | | |
| | | | aperture diameter |
| | | | An f-number of 2 |
| | | | would conventionally |
| | | | be written as f/2 , |
| | | | which gives the |
| | | | aperture diameter |
| | | | given the lens focal |
| Lensmakers' formula | 1 (1 1) | f focal length of a lens | |
| | $\left \frac{1}{n} = (n-1) \left \frac{1}{n} - \frac{1}{n} \right $ | n refractive index of lens | |
| | $f \land (R_1 \ R_2)$ | <i>P P</i> rodii of our others of | |
| | | $\mathbf{A}_1, \mathbf{A}_2$ radii of curvature of | |
| | | lens surface | |

| Doppler effect | $\Delta f = \frac{v}{f} f$ | v velocity towards observer |
|----------------|----------------------------|--------------------------------|
| | С | c wave speed |
| | | f emitted wave |
| | | frequency |
| | | Δf frequency shift |
| | | (from f) of waves |
| | | arriving at observer. |

THE ELECTROMAGNETIC SPECTRUM



5. Thermal physics

| Name | Equation | Description of variables | Notes / diagram |
|---|---|--|--|
| Ideal gas laws | pV = nRT $V \propto T$ Charles' Law $p \propto \frac{1}{V}$ Boyle's Law | <i>p</i> pressure <i>V</i> volume <i>n</i> number of moles of gas <i>R</i> molar gas constant <i>T</i> absolute temperature (in kelvin) | $R = 8.314 \text{ Jmol}^{-1}\text{K}^{-1}$ |
| Heat capacity and energy change | $\Delta E = mc\Delta T$ | ΔE energy required to raise the temperature of a mass <i>m</i> by ΔT <i>c</i> is the specific heat capacity | |
| Kelvin, Celcius and Fahrenheit temperature scales | $T_{K} = T_{C} + 273.15$ $T_{F} = \frac{9}{5}T_{C} + 32$ | | |
| Fluid pressure | $p = \rho g h$ | p pressure ρ fluid density g gravitational field strength h height of fluid column | |

| Name | Equation | Description of variables | Notes / diagram |
|--|--|--|--|
| Photon energy | E = hf | <i>h</i> Planck's constant = $6.63 \times 10^{-34} \text{ m}^2 \text{kgs}^{-1}$ <i>f</i> frequency | |
| Mass-energy relation | $\Delta E = \Delta m c^2$ | ΔE energy change Δm mass change c speed of light | Mass change in a nuclear reaction equates to an energy change, essentially due to the changes in nucleon binding energies. $c = 2.998 \times 10^8 \mathrm{ms}^{-1}$ |
| Radioactive decay | $\frac{dN}{dt} = -\lambda N$ $\lambda = \frac{\ln 2}{T_{\frac{1}{2}}}$ $N = N_0 \exp\left(-\frac{t}{T_{\frac{1}{2}}} \ln 2\right)$ | N Number of radioact that have not yet deca N_0 Number of radioac λ decay constant $T_{\frac{1}{2}}$ half life. The time ta t time | tive atoms at time t yed tive atoms at $t = 0$ aken for $N = \frac{1}{2}N_0$ |
| Geiger-Nuttall rule | $\log \lambda = A + B \log x$ $I = I_0 e^{-\mu x} \text{gamma rays}$ $I = \frac{dN}{dt} \text{'activity'}$ | λ decay constant μ absorption coefficient (Gamma rays) A, B empirical parameters or radioactive sample, and medium in which they are decaying into (e.g. air, paper, metal, lead x distance from source | |
| Alpha decay (alpha particles are Helium nuclei) | $ {}^{Z+N}_{Z} X \rightarrow {}^{Z+N-4}_{Z-2} Y + \alpha $ $ {}^{229}_{90} Th \rightarrow {}^{225}_{88} Ra + \alpha $ | Alpha decay. Atomic number (Z) <i>reduces</i> by 2. Mass number <i>reduces</i> by 4 Kinetic energy of alpha particle approximately 5MeV. (100,000 x ionization energy for an air molecule) | |
| Beta decay (beta particles are high energy electrons) | ${}^{Z+N}_{Z}X \rightarrow {}^{Z+N}_{Z+1}Y + \beta$ ${}^{14}_{6}C \rightarrow {}^{14}_{7}N + \beta$ | Beta decay. Atomic number (Z) increases by 1 Mass number stays the same Kinetic energy of beta particles 0.01 to 10MeV i.e. a spectrum of energies $[1MeV = 1.60 \times 10^{-13} J]$ | |
| Nuclear fission | ${}^{235}_{92}\text{U} + {}^{1}_{0}\text{n} \rightarrow {}^{141}_{56}\text{Ba} + {}^{92}_{36}\text{Kr} + 3{}^{1}_{0}\text{n}$ | 174 MeV per reaction 71.5 million MJ /kg of f coal 24 MJ per kg gas 46 MJ per kg sandwich 10 MJ per kg 1MeV = 1.60 x 10 ⁻¹³ J | j |
| Nuclear fusion | $^{2}_{1}D + ^{3}_{0}T \rightarrow ^{4}_{2}\text{He} + ^{1}_{0}n$ | 17.6 MeV per reaction 338 million MJ /kg of fu $[1MeV = 1.60 \times 10^{-13} J]$ | uel] |

| | | 87 Fr Francium | 55 CS Cesium 132.90545198(6) | 37 Rb Rubidium 85.4678(3) | 19 K Potassium 39.0983(1) | Na Sodium 22.98976928(2) | 3 Lithium | 1 1 Hydrogen Hydrogen |
|--|---|-----------------------------|--|---|---|--------------------------------|--|-------------------------------------|
| Actini Serie | Lantha Seri | 88 Ra Radium | 56 Ba Barium | 38 Sr Strontium 87.62(1) | 20 Ca calcium 40.078(4) | Magnesium [24.304,24.307 | 4 Beg Beryllium 3.0121831(5) | 2 11A 2A |
| es 89 | nide 57 es Lanth | 89-103 | 57-71 | 39 Y Yttrium 88.90584(2) | 21 Sc Scandium 44.955908(5) | 3B 🖩 🏻 | Atomic massv Masæs expres Masæs expres of the longest | |
| | anum Ce | 104 Rf Rutherfordiun | 72 Hf Hafnium ^{178.49(2)} | 40 Zr Zirconium ^{ST.224(2)} | 22 Ti Titanium ^{47.867(1)} | 48 48 | ralues reflect the IUPAC seed in [a;b] format sho the physical and chem seed in < > format are th | |
| The grade protection of the second se | 59 Film 116(1) | 105 Dubnium | 73 Ta Tantalum 180.94788(2) | 41 Niobium 92.90637(2) | 23 Vanadium | 5B 음 5 | accepted values as of 0 v the lower and upper I kal history of the eleme re mass numbers ern math no stable nucl | |
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| - | | noctium | A n tadon | Ke ienon | Nypton 1.798(2) | Ar Vrgon 3.948(1) | Neon 1797(6) | 18 /IIIA 8A elium elium |

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7. Cosmology

| Name | Equation | Description of variables | Notes / diagram |
|---|--|--|---|
| Bode's law for the solar system | $D_{AU} = \frac{4 + 3 \times 2^n}{10}$ | $\begin{array}{l} D_{AU} \ \text{planetary orbital} \\ \text{radius /AU} \\ n=0 \ \text{Venus} \\ n=1 \ \text{Earth} \\ n=2 \ \text{Mars} \\ n=3 \ \text{Ceres} \\ n=4 \ \text{Jupiter} \\ n=5 \ \text{Saturn} \\ n=6 \ \text{Uranus} \\ n=7 \ \text{Neptune} \end{array}$ | 1AU (Astronomical unit) = mean Earth-Sun separation = 1.496 x10 ¹¹ m |
| Hubble's law | $v = H_0 d$ | v cosmological recession velocity H_0 Hubble constant = 67.8 kms ⁻¹ /Mpc d distance of galaxy | The entire universe is expanding, so d can be measured from <i>any</i> observation point. 1Mpc = 3.09 x 10 ²² m |
| Schwarzschild radius of a Black Hole | $R_{s} = \frac{2GM}{c^{2}} \approx 3\frac{M}{M_{\odot}} \mathrm{km}$ | $G = 6.67 \times 10^{-11} \text{ Nm}^2 \text{kg}^{-2}$ <i>M</i> black hole mass <i>c</i> speed of light 2.998 x 10^8ms^{-1} | M_{\odot} solar mass =1.99 x 10 ³⁰ kg The Schwarzschild radius is the radius of a spherical mass whose <i>gravitational escape velocity</i> equals the speed of light. |
| Escape velocity | $E = \frac{1}{2}mu^{2} - \frac{GMm}{r}$ $E_{R} = \frac{1}{2}mu^{2} - \frac{GMm}{R}$ $E_{\infty} = \frac{1}{2}mv^{2}$ $v > 0 \Longrightarrow E_{R} > 0$ $\therefore u > \sqrt{\frac{2GM}{R}}$ | $G = 6.67 \times 10^{-11} \text{ Nm}^2 \text{kg}^{-2}$ M mass of (spherical) object R radius of object u launch velocity r radius from object centre m mass of object escaping E total energy of escaping object | For Earth, the escape velocity is $u > \sqrt{\frac{2 \times 6.67 \times 10^{-11} \times 5.97 \times 10^{24}}{6.38 \times 10^{6}}}$ $u > 11.2 \mathrm{kms^{-1}}$ |
| Redshift | $z = \frac{\lambda - \lambda_0}{\lambda_0}$ | λ observed wavelength λ_0 emitted wavelength | |

The Solar System has the following parameters. (Woan, 2000 pp176). All orbits are assumed to be elliptical about the sun. Note

and

In SI units:

 $\frac{M_{\odot}}{M_{\oplus}} \approx 332,948$ $R_{\oplus} \approx \frac{\mathrm{AU}}{23,455}$

| M_{\odot} | = | $1.9891 \times 10^{30} \text{ kg}$ |
|-------------|---|-------------------------------------|
| R_{\odot} | = | $6.960 \times 10^8 \mathrm{m}$ |
| M_\oplus | = | $5.9742 \times 10^{24} \text{ kg}$ |
| R_\oplus | = | $6.37814\times10^6~{\rm m}$ |
| 1AU | = | $1.495979 \times 10^{11} \ {\rm m}$ |

| Object | M/M_{\oplus} | a /AU | ε^4 | θ_0 | β | α | R/R_{\oplus} | T_{rot} / days | P/Yr |
|--------------------|----------------|--------|-----------------|------------|---------|----------|----------------|------------------|-----------------|
| Sun | $332,\!837$ | - | - | - | - | - | 109.123 | | - |
| Mercury | 0.055 | 0.387 | 0.21 | * | 7.00 | 0 | 0.383 | 58.646 | 0.241 |
| Venus [†] | 0.815 | 0.723 | 0.01 | * | 3.39 | 0 | 0.949 | 243.018 | 0.615 |
| Earth | 1.000 | 1.000 | 0.02 | * | 0.00 | 0 | 1.000 | 0.997 | 1.000 |
| Mars | 0.107 | 1.523 | 0.09 | * | 1.85 | 0 | 0.533 | 1.026 | 1.881 |
| Jupiter | 317.85 | 5.202 | 0.05 | * | 1.31 | 0 | 11.209 | 0.413 | 11.861 |
| Saturn | 95.159 | 9.576 | 0.06 | * | 2.49 | 0 | 9.449 | 0.444 | 29.628 |
| $Uranus^{\dagger}$ | 14.500 | 19.293 | 0.05 | * | 0.77 | 0 | 4.007 | 0.718 | 84.747 |
| Neptune | 17.204 | 30.246 | 0.01 | * | 1.77 | 0 | 3.883 | 0.671 | 166.344 |
| Pluto [†] | 0.003 | 39.509 | 0.25 | * | 17.5 | 0 | 0.187 | 6.387 | 248.348 |

where β is the orbital inclination /degrees. In all cases the semi-major axis pointing direction is

$$\mathbf{d} = d_x \hat{\mathbf{x}} + d_y \hat{\mathbf{y}} + d_y \hat{\mathbf{z}} = \cos \beta \hat{\mathbf{x}} + \sin \beta \hat{\mathbf{z}}$$

* For the current orbital polar angle θ_0 (and indeed more accurate values for solar system parameters) see the website of the Jet Propulsion Laboratory (JPL) http://ssd.jpl.nasa.gov/

[†]These planets rotate clockwise about their own internal polar axis. ("Retrograde"). All the other planets rotate anti-clockwise about their own internal axis. All the planets orbit the sun in an anticlockwise direction.

⁴http://nineplanets.org/data.html

8. Mathematics

| Name | Equation | Notes / diagram |
|-----------------------|---|---|
| Trigonometry & | $x = r \cos \theta$ | $\cos\theta$ is the x coordinate of the |
| Pythagoras' | $y = r \sin \theta$ | unit circle |
| theorem | $r = \sqrt{r^2 + v^2}$ | $\sin \theta$ is the <i>y</i> coordinate |
| | $\int -\sqrt{x} + y$ $\sin^2 \theta + \sin^2 \theta = 1$ | sint is the y coordinate. |
| | $\sin \theta + \cos \theta = 1$ | heta is measured anticlockwise from |
| | $\tan \theta = \frac{\sin \theta}{\cos \theta}$ | the <i>x</i> axis. |
| Special triangles | $\sin 30^\circ = \pm \sin 60^\circ = \frac{\sqrt{3}}{2}$ | |
| | $\sin 30^{\circ} = \frac{1}{2} - \sin 30^{\circ} = \frac{\sqrt{3}}{2}$ | |
| | $\cos 00^{\circ} = \frac{1}{2} \cos 0^{\circ} = \frac{1}{2}$ | |
| | $\sin 45^\circ = \frac{1}{\sqrt{5}} \cos 45^\circ = \frac{1}{\sqrt{5}} \tan 45^\circ = 1$ | |
| Laws of indices | $\sin 45 - \frac{1}{\sqrt{2}} \cos 45 - \frac{1}{\sqrt{2}} \tan 45 - 1$ | |
| | $\begin{array}{c} x \ x = x \\ (a)^{b} ab \end{array}$ | |
| | $(x^{\alpha}) = x^{\alpha \beta}$ | |
| | $x^{-a} = \frac{1}{x^a}$ | |
| | $\sqrt[n]{x} = x^{\frac{1}{n}}$ | |
| Laws of | $y = \log_{b} x \Longrightarrow x = b^{y}$ | Base b>0 |
| logarithms | $\log_{h} x + \log_{h} y = \log_{h} xy$ | |
| | $\log_b x - \log_b y = \log_b \frac{x}{y}$ | |
| | $\log_b x^n = n \log_b x$ | |
| | $x = b^{\log_b x}$ | |
| | $\log_{10} x = \log_{10} x = \log_{c} x$ | |
| | $\log_b x - \frac{1}{\log_{10} b} - \frac{1}{\log_c b}$ | |
| Binomial expansion | $ (a+b)^{n} = {\binom{n}{0}} a^{0} b^{n} + {\binom{n}{1}} a^{1} b^{n-1} + {\binom{n}{2}} a^{2} b^{n-2} + \dots + {\binom{n}{n}} a^{n} b^{0} $ | Binomial expansion <i>n</i> integer, >0 |
| | $\binom{n}{n} = \frac{n!}{n!}$ | |
| | (r) $(n-r)!r!$ | Generalized binomial expansion |
| | $(1+x)^n = 1 + nx + n(n-1)x + n(n-1)(n-2)\frac{x^2}{2!} + \dots$ | x < 1 |
| | $+n(n-1)(n-2)(n-3)\frac{x^3}{3!}+$ | |
| Arithmetic | $u_n = a + (n-1)d$ | |
| progression | $u_1 = a$ | |
| | $u_{n+1} - u_n = d$ | |
| | $S_{n} = \sum_{i=1}^{n} u_{i} = \frac{1}{2}n(u_{1} + u_{n})$ | |
| Geometric | $u_n = ar^{n-1}$ | If $ r < 1$ |
| progression | $u_1 = a$ | $s \rightarrow \frac{a}{a}$ |
| | $\frac{u_{n+1}}{r} = r$ | $S_{\infty} \xrightarrow{-7} \frac{1-r}{1-r}$ |
| | | |
| | $\int_{S} -a + ar + ar^{2} + ar^{n-1} - a(1 - r^{n})$ | |
| | $S_n = a + ar + ar + + ar = \frac{1}{1 - r}$ | |

| Summation formulae | $\sum_{n=1}^{N} n = \frac{1}{2}n(n+1)$ | |
|--------------------|--|--|
| | $\sum_{n=1}^{N} n^2 = \frac{1}{6} n(n+1)(2n+1)$ | |
| | $\sum_{n=1}^{N} n^{3} = \frac{1}{4} n^{2} (n+1)^{2}$ | |
| Triangle | $A = \frac{1}{2}bh = \frac{1}{2}ab\sin C$ Area of a triangle $\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$ Sine and Cosine rules | b is base of triangle h perpendicular height a,b,c sides of triangle A = C expensive englage to sides |
| Circlo | $a^2 = b^2 + c^2 - 2bc\cos A$ | A, B, C opposite angles to sides |
| Circle | $(x-a)^{2} + (x-b)^{2} = r^{2}$ | Circumference C and area A |
| | $C = 2\pi r$ | Arc angle (radians) θ and area <i>a</i> |
| | $A = \pi r^2$ | |
| | $s = r\theta$ | |
| | $a = \frac{1}{2}r^2\theta$ | |
| Ellipse | $\frac{(x-x_0)^2}{a^2} + \frac{(y-y_0)^2}{b^2} = 1$ | Geometric centre (x_0, y_0) semi-major axis <i>a</i> and semi-minor |
| | $A = \pi a b$ | Area A |
| Cylinder | $A = 2\pi r h + 2\pi r^2$ | Area A and volume V |
| | $V = \pi r^2 h$ | h height or length of cylinder |
| Cone | $A = \pi r l$ | <i>l</i> slant height |
| | $V = \frac{1}{3}\pi r^2 h$ | r radius of base |
| Frustum | $V = \frac{1}{2} \left(A + \sqrt{A} + \frac{1}{2} \right)$ | Top and base areas a A |
| | $V = \frac{1}{3}n(A + \sqrt{aA} + a)$ | Perpendicular height h |
| Combinatorics | n! | <i>n</i> objects, <i>p</i> repeats of type A, q |
| | $P = \frac{1}{p!q!r!\dots}$ | repeats of type B etc. |
| | $n_{C} = n!$ | ${}^{n}C$ is upper of combinations of r |
| | $C_r = \frac{1}{(n-r)!r!}$ | C_r is under or combinations of r |
| | ${}^{n}P_{r} = \frac{n!}{(n-r)!}$ | of n distinct objects i.e. order of subset doesn't matter. |
| | | ^{<i>n</i>} P_r is umber of <i>permutations</i> of <i>r</i> |
| | | distinct objects from a population of n distinct objects i.e. order of subset does matter |
| Quadratic | $y = ax^2 + bx + c$ | Quadratic formula |
| equations | $y = 0 \Rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$ | Discriminant $\Delta = b^2 - 4ac$ |
| Matrices | $ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} e & f \\ g & h \end{pmatrix} = \begin{pmatrix} ae + bg & af + bh \\ ce + dg & cf + dh \end{pmatrix} $ | |
| | $(-1)^{-1}$ | |
| | $ \begin{pmatrix} a & b \\ c & d \end{pmatrix}^{T} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} $ | Inverse matrix |
| | $ \begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} $ | Identity matrix |

| Basic | $f'(x) = \frac{d}{dx} f(x)$ | $\frac{dy}{dy}$ is the <i>gradient</i> at point (x, y) |
|-------------------|--|---|
| uncrentiation | dx dx | dx |
| | $\frac{d}{dx}x^n = nx^{n-1}$ | Stationary point (x, y) when |
| | d a a | dv |
| | $\frac{d}{dx}e^{ax} = ae^{ax}$ | $\frac{dy}{dx} = 0$ |
| | | maxima if $\left. \frac{d^2 y}{dx^2} \right _{x=x_s} < 0$ |
| | | minima if $\left. \frac{d^2 y}{dx^2} \right _{x=x_s} > 0$ |
| Basic integration | $\int f'(x)dx = f(x) + c$ | $\int g(x)dx$ is the area between the |
| | $\int_{a}^{b} f'(x) dx = [f(x)]^{b} = (f(b)) - (f(a))$ | curve $g(x)$ and the x axis, with |
| | $\int_{a}^{b} x^{n} dx = \frac{1}{n+1} x^{n+1} + c$ | the caveat that area beneath the axis counts as negative. |
| | $\int e^{ax} dx = \frac{1}{2} e^{ax} + c$ | $\int g(x) dx$ is also the <i>inverse</i> of |
| | J a | differentiating $y = g(x)$ |
| | | i.e. $\int \frac{dy}{dx} dx = y + c$ |
| | | (which is true up to a <i>constant of integration</i> , which must be specified). |
| | | |
| | | |
| | | |
| | | |

| Linear regression | $\overline{x} = \frac{1}{N} \sum_{n=1}^{N} x_n \qquad \overline{y} = \frac{1}{N} \sum_{n=1}^{N} y_n$ | Formulae for calculating the line of best fit to a set of data |
|----------------------|--|--|
| | $\overline{x^2} = \frac{1}{N} \sum_{n=1}^{N} x^2$ $\overline{y^2} = \frac{1}{N} \sum_{n=1}^{N} y^2$ | $\{x_n, y_n\}$ |
| | $N \sum_{n=1}^{N} \sum_{n=1}^{N} N \sum_{n=1}^{N} $ | cov[x, y] is the covariance |
| | $\overline{xy} = \frac{1}{N} \sum_{n=1}^{N} x_n y_n$ | cov[x, y] |
| | $\operatorname{cov}[x, y] = \overline{xy} - \overline{x} \times \overline{y}$ | $p = \frac{1}{\sqrt{V[x]V[y]}}$ is the |
| | $V[x] = \overline{x^2} - \overline{x}^2 V[y] = \overline{y^2} - \overline{y}^2$ | product moment correlation coefficient. |
| | $p = \frac{\text{cov}[x, y]}{5}$ | ······································ |
| | $\sqrt{V[x]V[y]}$ | p = -1 perfect negative correlation between x and y |
| | y = mx + c | p = +1 perfect positive |
| | $m = \frac{\operatorname{cov}[x, y]}{V[x]} c = \overline{y} - m\overline{x} \text{vertical fit}$ | correlation between x and y $p = 0$ no correlation |
| | $m = \frac{V[y]}{\operatorname{cov}[x, y]}$ $c = \overline{y} - m\overline{x}$ horizontal fit | between x and y |
| Statistical analysis | $\overline{\mathbf{r}} = F[\mathbf{r}] = \frac{1}{N} \sum_{n=1}^{N} \mathbf{r}$ | \overline{x} mean, or expectation |
| | $X = D[X] = N \sum_{n=1}^{\infty} X_n$ | σ^2 variance |
| | $\sigma^{2} = V[x] = \frac{1}{N-1} \sum_{n=1}^{N} (x_{n} - \overline{x})^{2}$ | |
| Bayes' Theorem & | P(H T)P(T) = P(T H)P(H) | <i>H</i> hypothesis true |
| inference | $P(H \mid T) = \frac{P(T \mid H)P(H)}{P(T \mid T) + P(T \mid T)}$ | <i>T</i> test for hypothesis pass |
| | $P(T \mid H)P(H) + P(T \mid H')P(H')$ | T' test for hypothesis fail |
| | $P(H T') = \frac{P(T' H)P(H)}{P(T' H)P(H) + P(T' H')P(H')}$ | P(H T) is probability of |
| | I(I II)I(II) + I(I II)I(II) | hypothesis being true given |
| | | a test has been passed. This is often what a patient |
| | | wants to know following a |
| | | medical applications a |
| | | pharmaceutical company |
| | | P(T H) e.g. probability |
| | | that a test passes given a |
| | | sample has the disease. If a disease is rare, |
| | | $P(H) \ll 1$ which may mean |
| | | P(H T) is low even if |
| | | $P(T \mid H)$ is close to 100%. |
| | | P(H T') is called a false |
| - | | DOSILIVE. |

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