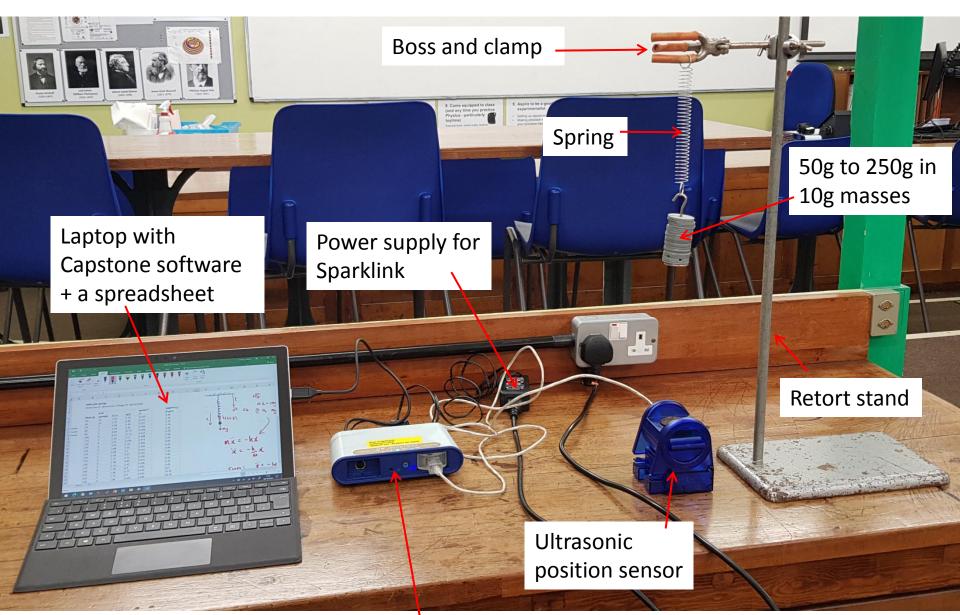
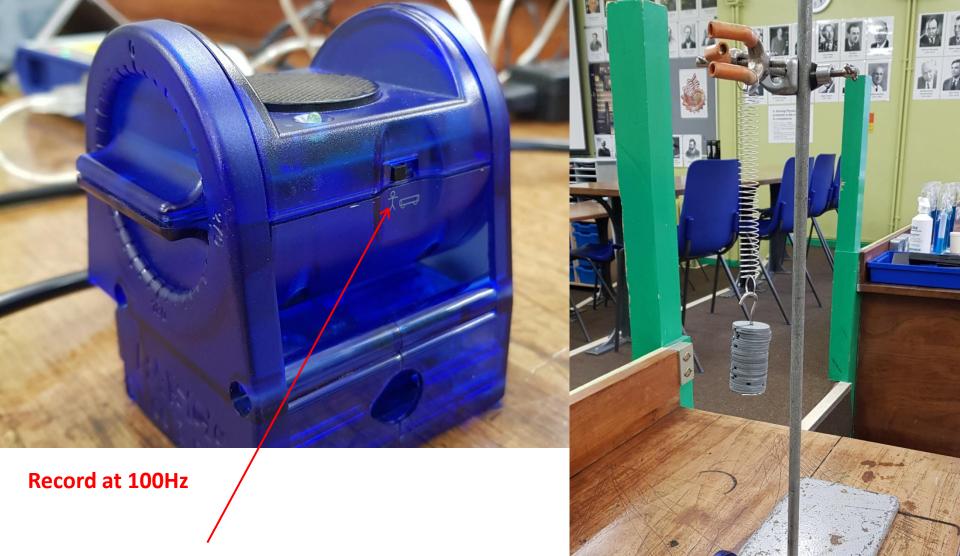


Equipment setup



PASCO Sparklink USB hub (this plugs into the USB port of the laptop)



Set ultrasonic position sensor in 'person' mode. The beam is slightly wider, and will mean smooth sinuoidal measurements will be obtained even if the mass jerks around sideways a little.



MT:

M = my-k(x+2)

@ es my= k2

Simple Harmonic Motion (SHM)

$$x = A\cos\left(\frac{2\pi t}{T}\right)$$

$$\dot{x} = -A \frac{2\pi}{T} \sin\left(\frac{2\pi t}{T}\right)$$

$$\ddot{x} = -A \frac{4\pi^2}{T^2} \cos\left(\frac{2\pi t}{T}\right)$$

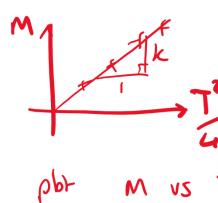
$$\ddot{x} = -\frac{4\pi^2}{T^2}x$$

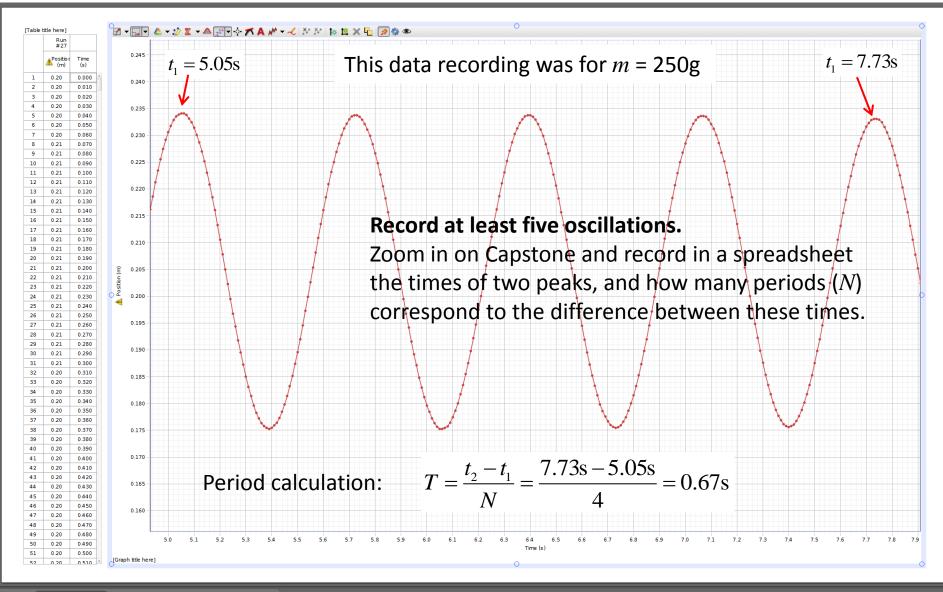
$$x = A\cos\left(\frac{2\pi t}{T}\right)$$

$$\frac{dr}{T^2} = \frac{R}{m}$$

$$\frac{dr}{dr} = \frac{R}{m}$$

$$\frac{dr}{dr} = \frac{R}{m}$$







Set recording rate at 100Hz

Capstone screenshot

SHM with springs

Andy French. Winchester College P5. 28/10/2020.

beats beats beats

	# of			period T
Mass /g	periods	t1 /s	t2/2	/s
50	12	2.63	6.29	0.305
60	14	2.22	6.86	0.331
70	7	2.94	5.44	0.357
80	5	3.44	5.36	0.384
90	5	8.69	10.73	0.408
100	6	8.52	11.12	0.433
110	5	1.93	4.17	0.448
120	4	2.31	4.205	0.474
130	6	2.65	5.59	0.490
140	5	2.88	5.41	0.506
150	5	2.48	5.1	0.524
160	5	2.36	5.07	0.542
170	5	1.72	4.51	0.558
180	5	1.98	4.85	0.574
190	5	2.53	5.47	0.588
200	4	1.99	4.4	0.603
210	5	1.68	4.77	0.618
220	5	1.75	4.9	0.630
230	4	1.86	4.445	0.646
240	4	2.27	4.91	0.660
250	5	2.17	5.52	0.670

1000*T^2 /
4*pi^2
2.36
2.78
3.23
3.74
4.22
4.76
5.08
5.69
6.08
6.49
6.96
7.44
7.89
8.35
8.76
9.20
9.67
10.05
10.58
11.03
11.37

$$m = k \frac{T^2}{4\pi^2}$$

